

Post-processing pipeline

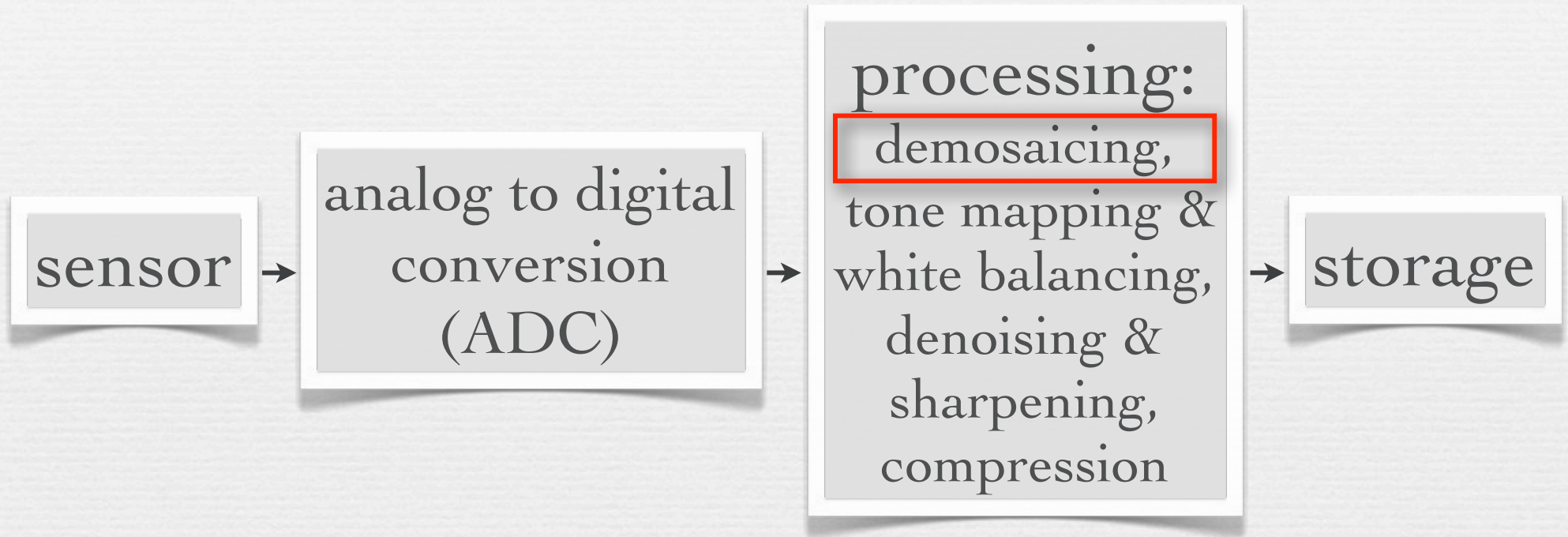
CS 178, Spring 2012

Begun 5/31/12, finished 6/5.



Marc Levoy
Computer Science Department
Stanford University

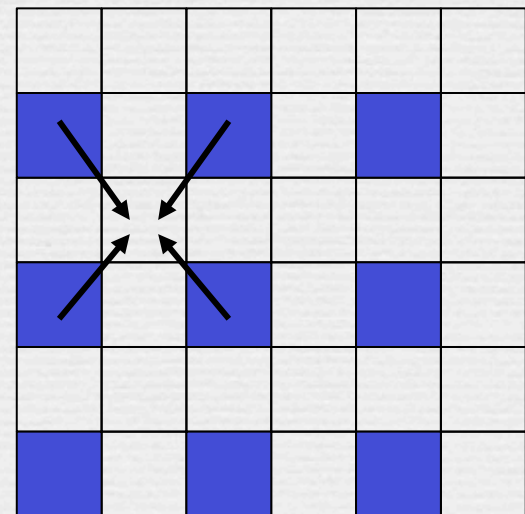
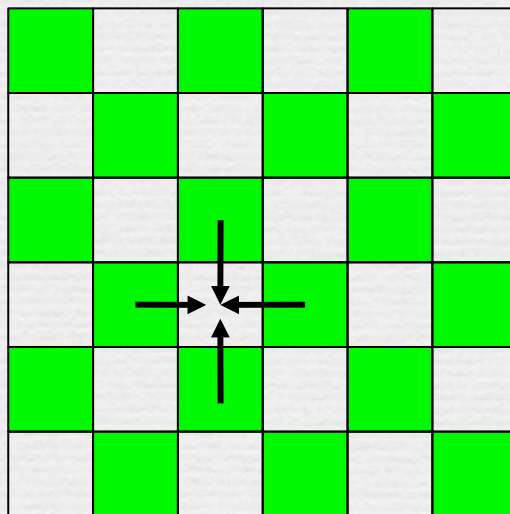
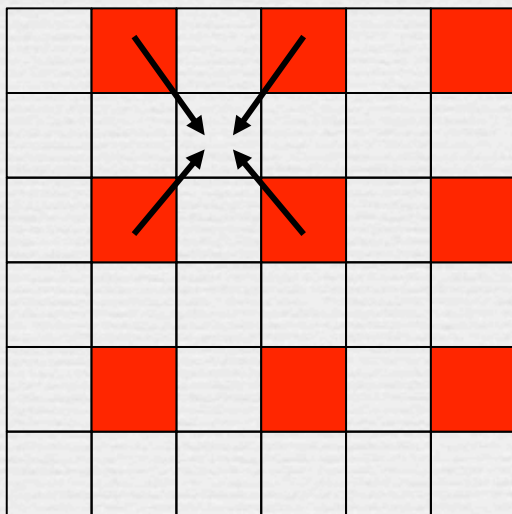
Camera pixel pipeline



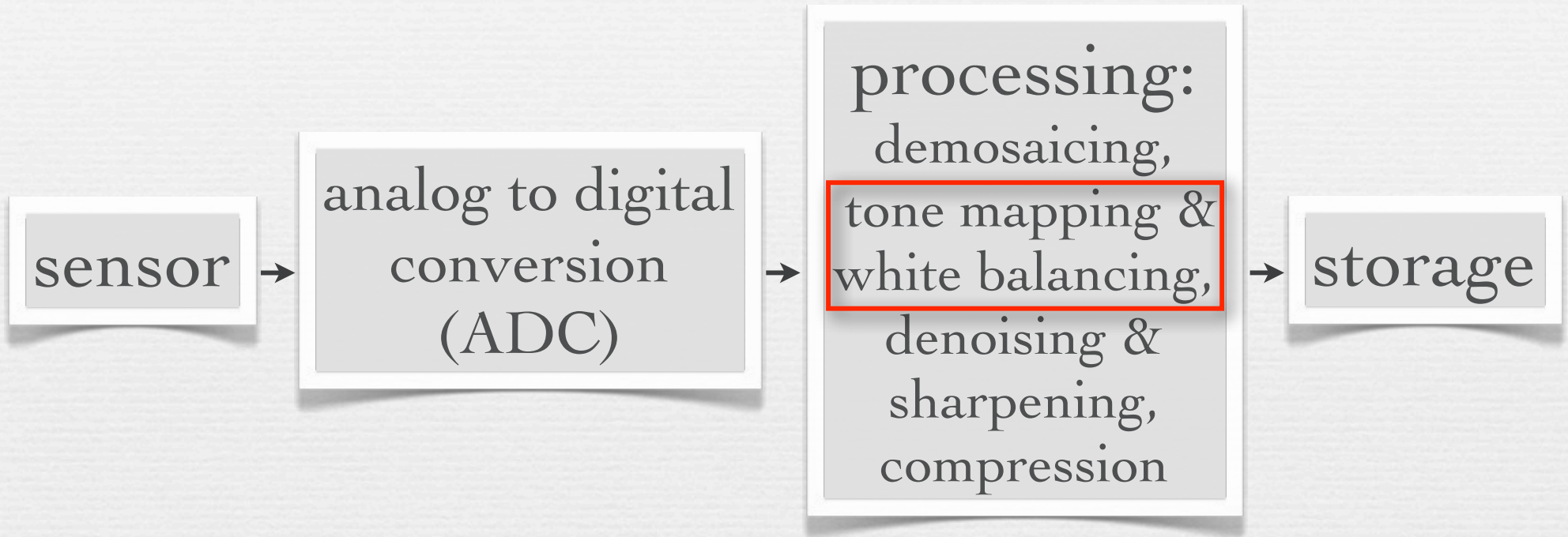
- ◆ every camera uses different algorithms
- ◆ the processing order may vary
- ◆ most of it is proprietary

Demosaicing (review)

- ◆ linear interpolation
 - average of the 4 nearest neighbors of the same color
- ◆ cameras typically use more complicated scheme
 - try to avoid interpolating across feature boundaries
 - demosaicing is often combined with denoising, sharpening...



Camera pixel pipeline



Gamma and gamma correction

- ◆ the goal of digital imaging is to accurately reproduce relative scene luminances on a display screen
 - absolute luminance is impossible to reproduce
 - humans are sensitive to relative luminance anyway
- ◆ in some workflows, pixel value is made proportional to scene luminance, in other systems to perceived brightness
 - in CRTs luminance was proportional to voltage $^\gamma$ with $\gamma \approx 2.5$, so TV cameras had to be designed to output scene luminance $^{1/\gamma}$
 - pixel value \propto luminance $^{1/2.5}$ is roughly perceptually uniform, so in CG and digital photography it's a good space for quantization, JPEG, etc.



(FLASH DEMO)

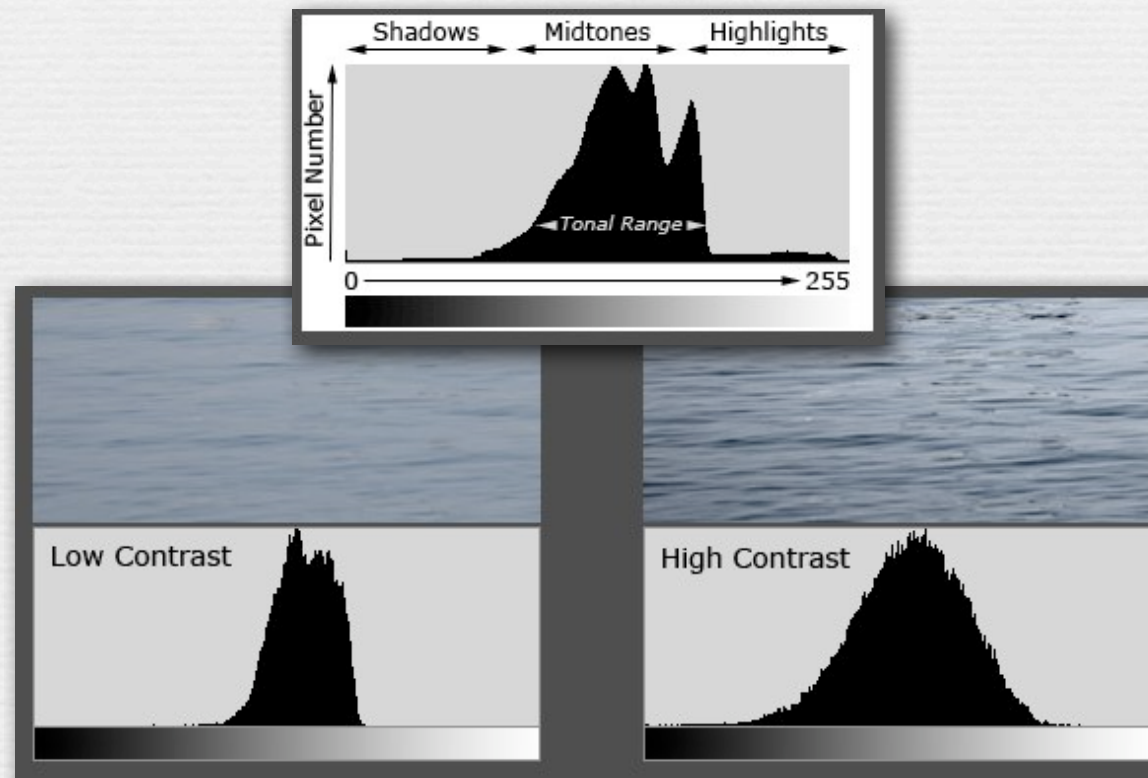
<http://graphics.stanford.edu/courses/cs178/applets/gamma.html>



Contrast correction (a.k.a. tone mapping)

- ◆ manual editing

- capture image in RAW mode, then fiddle with histogram in Photoshop, dcraw, Canon Digital Photo Professional, etc.



Contrast correction (a.k.a. tone mapping)

- ◆ manual editing
 - capture image in RAW mode, then fiddle with histogram in Photoshop, dcraw, Canon Digital Photo Professional, etc.
- ◆ gamma transform (in addition to RAW→JPEG gamma)
 - output = input $^\gamma$ (for $0 \leq I_i \leq 1$)
 - simple but crude



original



$\gamma = 0.5$



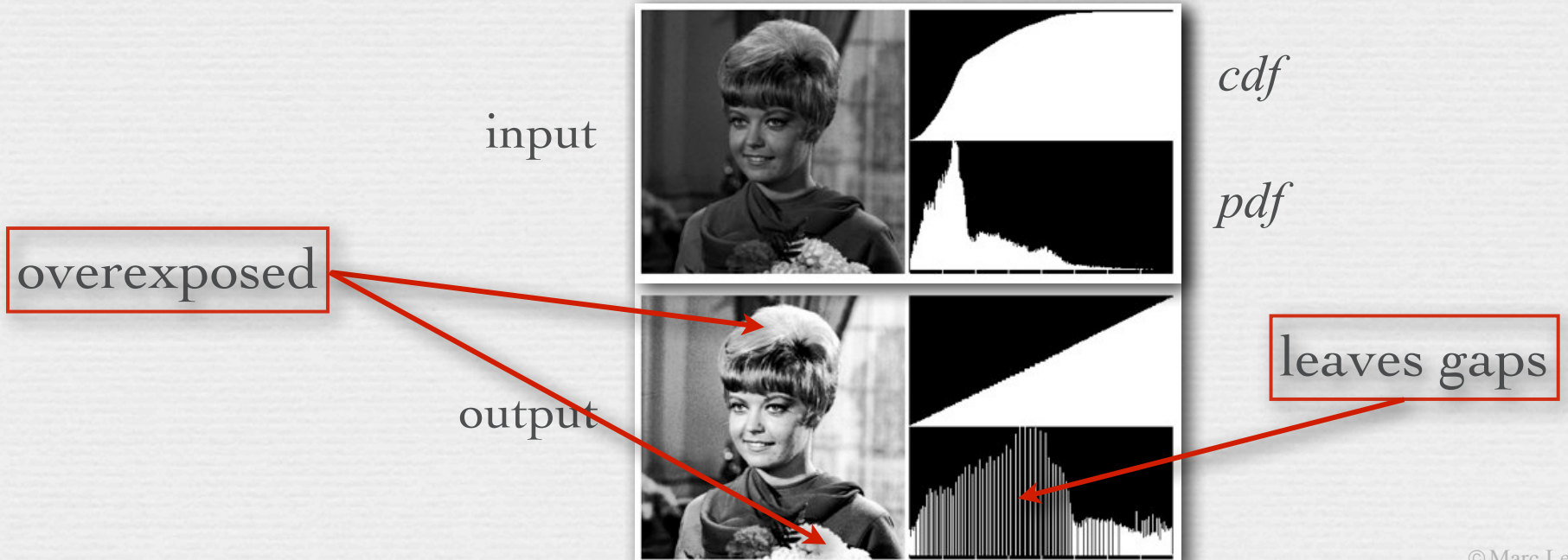
$\gamma = 2.0$

Contrast correction (a.k.a. tone mapping)

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 - capture image in RAW mode, then fiddle with histogram in Photoshop, dcrw, Canon Digital Photo Professional, etc.
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 - simple but crude
- ◆ histogram equalization

Histogram equalization

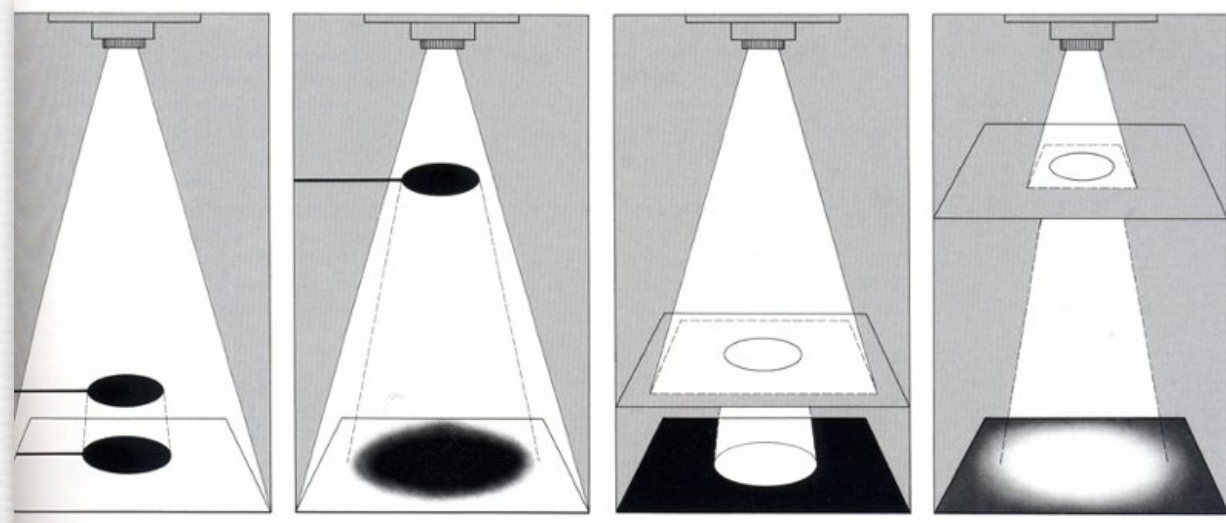
1. convert image to range $[0,1]$
2. calculate histogram of intensity, i.e. $pdf(i) = \frac{N_i}{N}$
where N_i is the number of pixels of intensity i ,
and N is the total number of pixels
3. calculate cumulative density function $cdf(i) = \sum_{j=0}^i pdf(j)$
4. re-map each pixel using $I_{out} = cdf(I_{in}) \times 255 / N$ (for 8-bit pixels)



Contrast correction (a.k.a. tone mapping)

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 - capture image in RAW mode, then fiddle with histogram in Photoshop, dcrw, Canon Digital Photo Professional, etc.
- ◆ gamma transform (in addition to RAW→JPEG gamma)
 - output = input $^\gamma$ (for $0 \leq I_i \leq 1$)
 - simple but crude
- ◆ histogram equalization
- ◆ global versus local transformations

Traditional dodging and burning

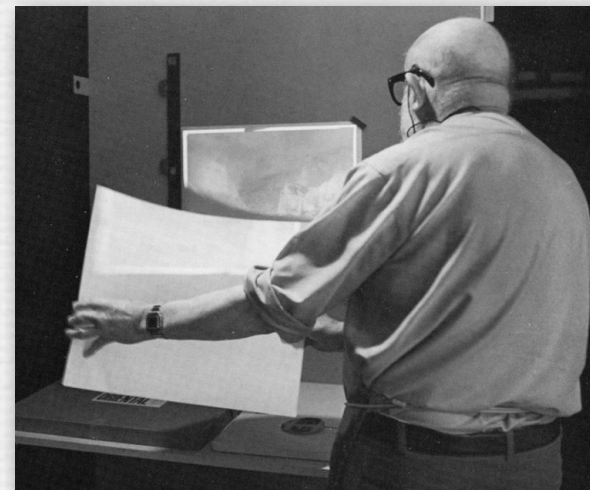
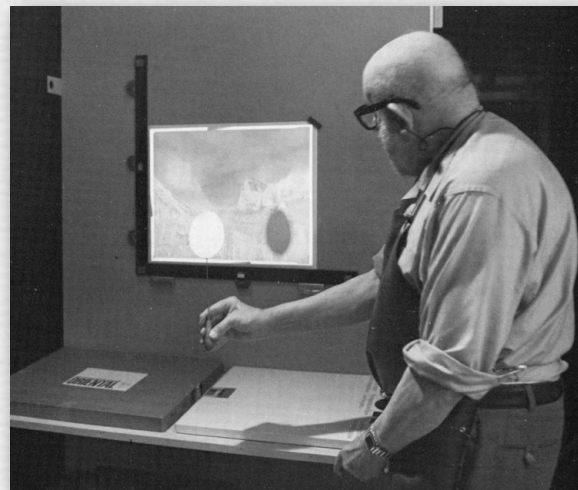


(Rudman)

dodging
(leaves print lighter)

burning
(makes print darker)

Ansel Adams in
his darkroom



(Adams)



straight
print

Ansel Adams, Clearing Winter Storm, 1942



toned
print

Ansel Adams, Clearing Winter Storm, 1942

Recap

- ◆ in CRTs luminance = voltage $^\gamma$ where $\gamma \approx 2.5$, so television cameras output luminance $^{1/\gamma}$ to compensate
 - NTSC cameras use luminance $^{0.5}$, yielding a *system gamma*, to compensate for human *dark adaptation* during viewing
- ◆ digital cameras also gamma transform sensed pixels before storing them in JPEG files
 - while this matches television cameras, another good reason is perceptual uniformity, thereby reducing quantization artifacts
 - for sRGB cameras, $\gamma = 1/2.2$
- ◆ *tone mapping* methods may include
 - contrast expansion
 - additional gamma mapping
 - histogram equalization
 - local methods, like dodging & burning

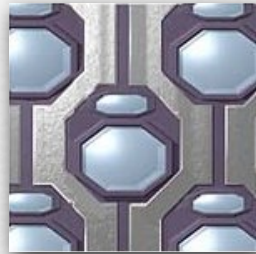
Questions?

High dynamic range (HDR) imaging

- ◆ step 1: capturing HDR images
- ◆ step 2a: direct display of HDR images, or
- ◆ step 2b: tone mapping to create an LDR image for display

Capturing HDR images

- ◆ assorted pixels



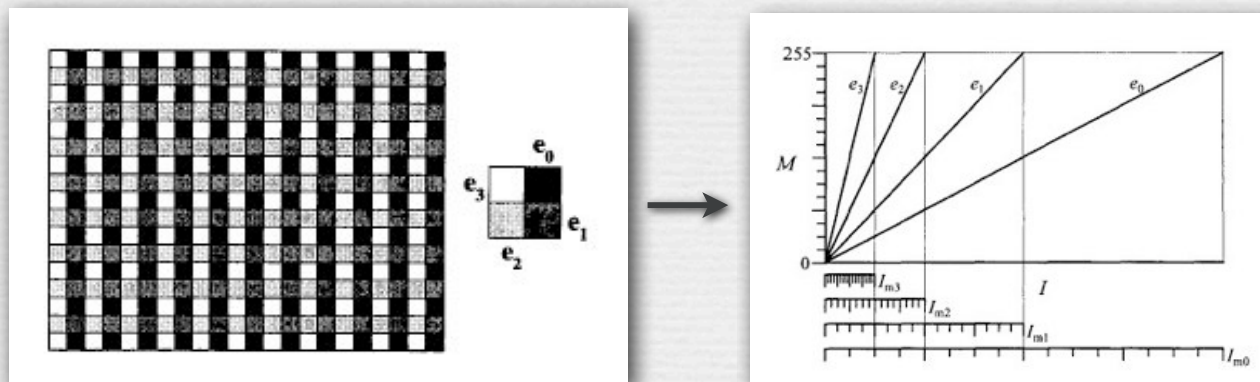
Fuji SuperCCD

- ◆ per-pixel neutral density filters
[Nayar CPVR 2000]

- throws away photons
- trades spatial resolution for dynamic range



Sony



Games with ND filters



1/500s, f/5.6, ISO 800

Games with ND filters



1/125s

Games with ND filters



1/30s

Games with ND filters



1/8s

Games with ND filters



1/2s

Games with ND filters

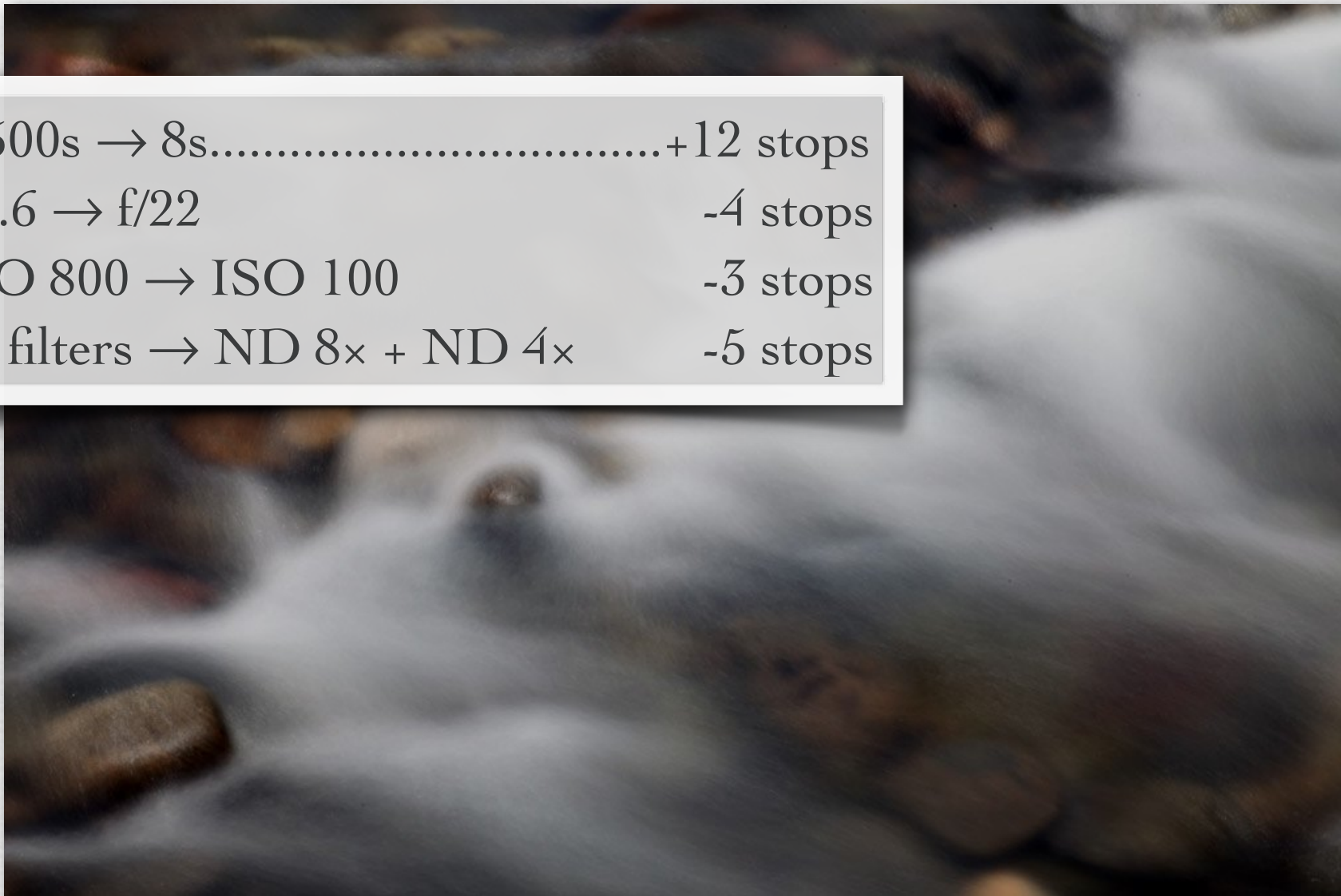


Games with ND filters



Games with ND filters

1/500s → 8s.....	+12 stops
f/5.6 → f/22	-4 stops
ISO 800 → ISO 100	-3 stops
no filters → ND 8× + ND 4×	-5 stops



8s



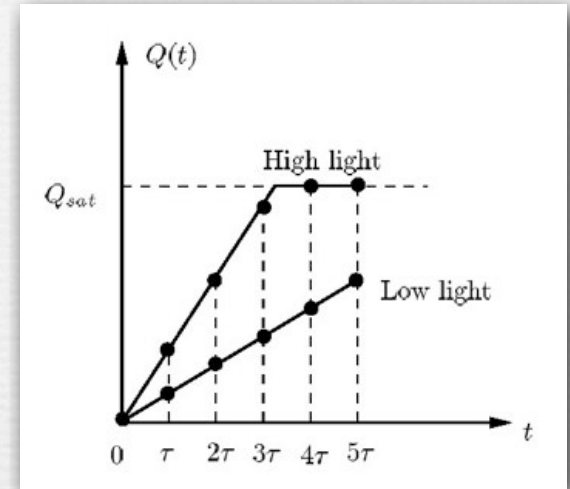


Capturing HDR images

◆ non-destructive readout of pixels

[Gamal 1999]

- measures light by counting time to saturation
- improves dynamic range, but SNR at low brightness levels is no better than an ordinary camera



To expand on this last point, remember that SNR is a metric that is different for every scene brightness. As we learned in the noise lecture, if the scene is dim, then the number of photons is low, in which case the photon shot noise is high relative to the number of photons, and SNR is poor. Reading out pixel values more frequently lets us reliably measure intensity in bright pixels (because we read them before they saturate), but it doesn't provide any improvement in our measurement in dim pixels. Only a larger pixel or a longer exposure would do this.



normal

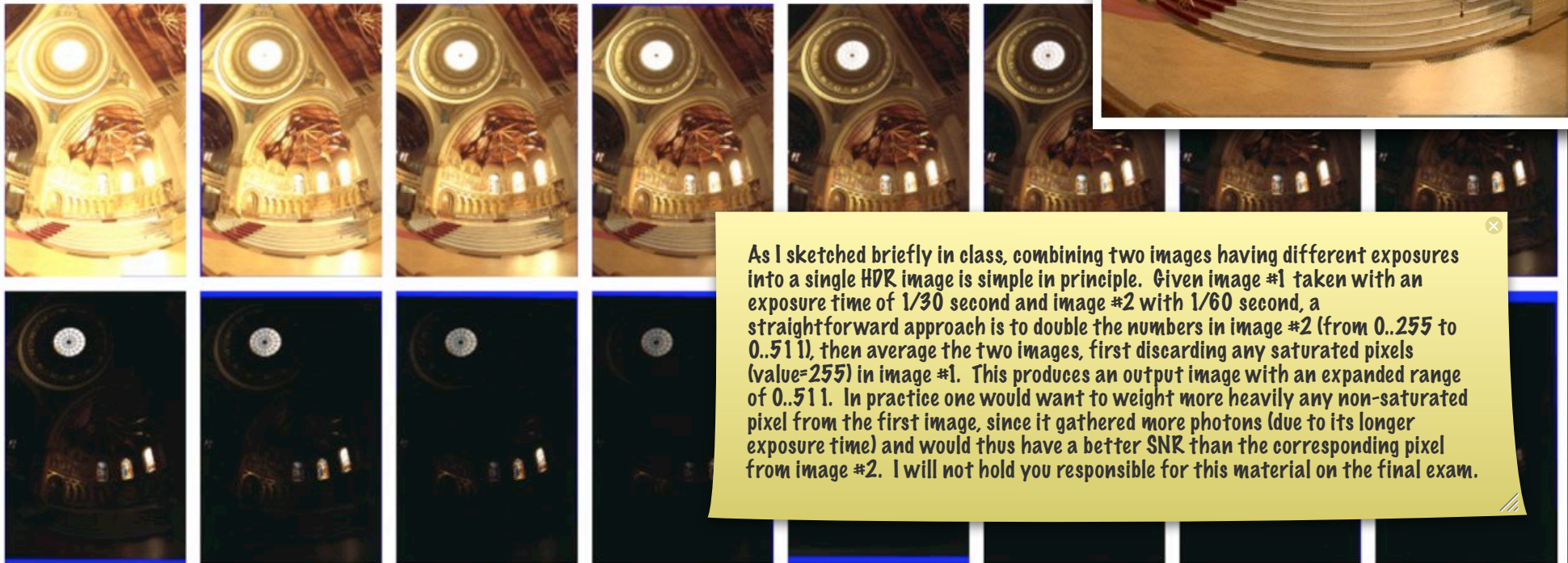
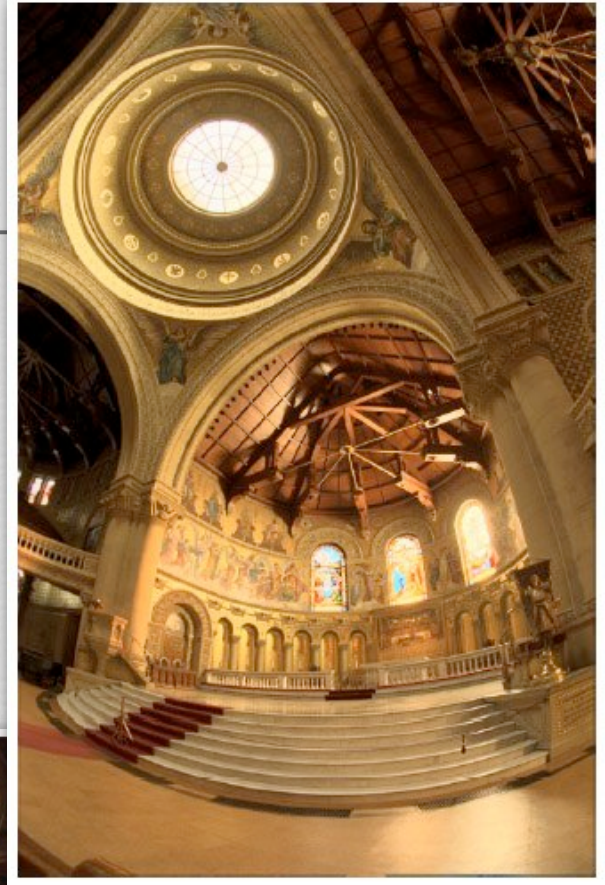


Pixim

Capturing HDR images

- ◆ multiple bracketed exposures
[Debevec SIGGRAPH 1997]
- ◆ changing the exposure time is usually better than changing the aperture

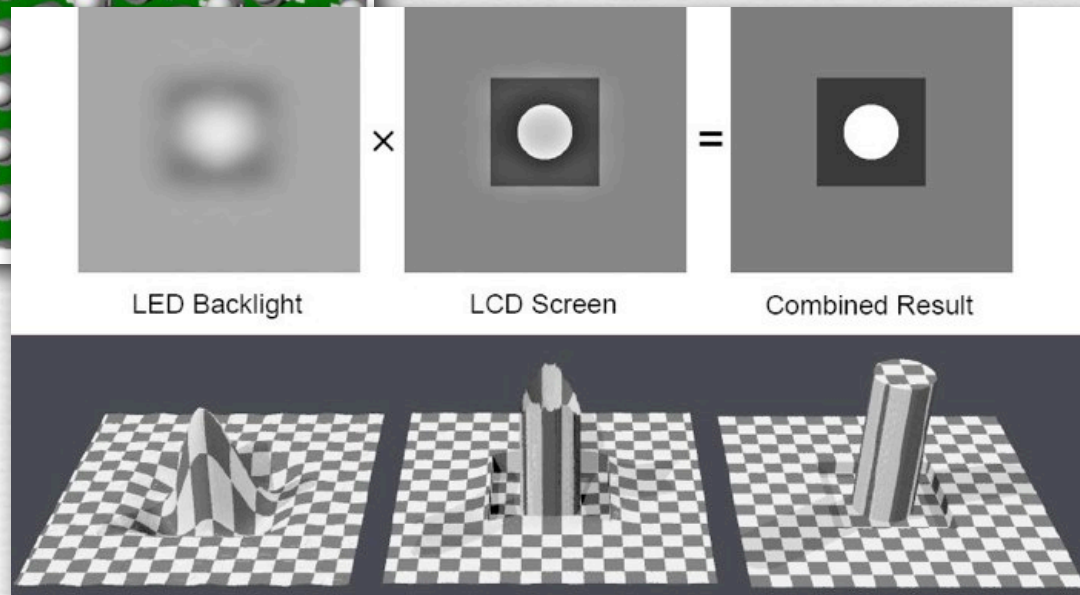
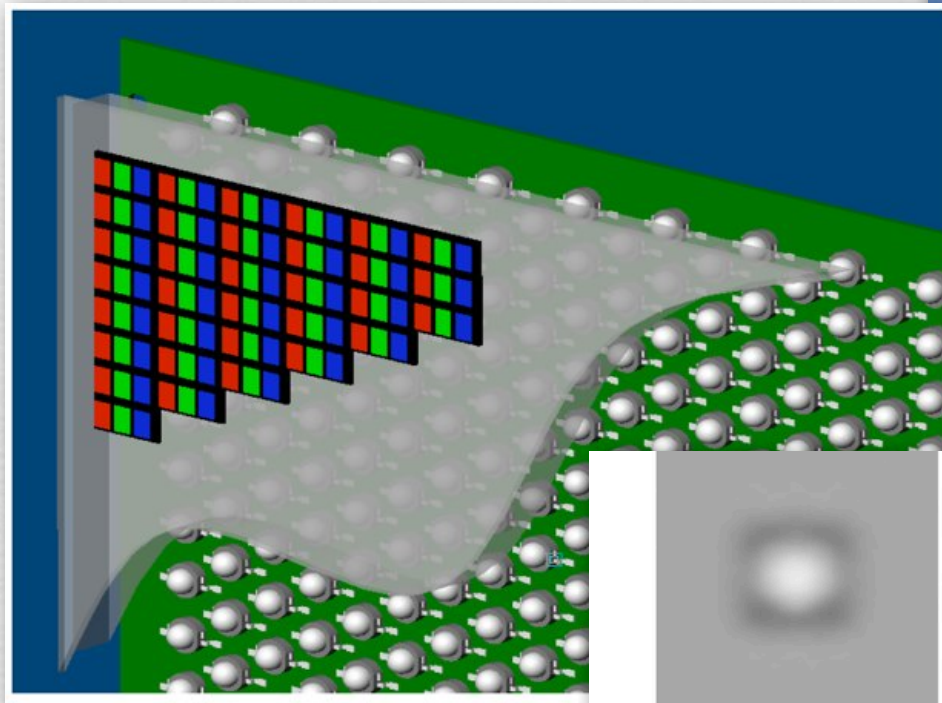
Q. How about changing the ISO?



As I sketched briefly in class, combining two images having different exposures into a single HDR image is simple in principle. Given image #1 taken with an exposure time of $1/30$ second and image #2 with $1/60$ second, a straightforward approach is to double the numbers in image #2 (from 0..255 to 0..511), then average the two images, first discarding any saturated pixels (value=255) in image #1. This produces an output image with an expanded range of 0..511. In practice one would want to weight more heavily any non-saturated pixel from the first image, since it gathered more photons (due to its longer exposure time) and would thus have a better SNR than the corresponding pixel from image #2. I will not hold you responsible for this material on the final exam.

Direct display of HDR images

◆ Sunnybrook HDR display





Brightside HDR display

High dynamic range imaging (review)

- ◆ step 1: capturing HDR images
- ◆ step 2a: direct display of HDR images, or
- ◆ step 2b: tone mapping to create an LDR image for display

you're not responsible for
HDR tone mapping on your final

- ◆ goals of HDR → LDR tone mapping
 - squeeze >12 bits of HDR image into 8 bits for JPEG
 - apply mapping for human adaption if scene was very dark
 - or bright...



(Marc Levoy)



(Marc Levoy)



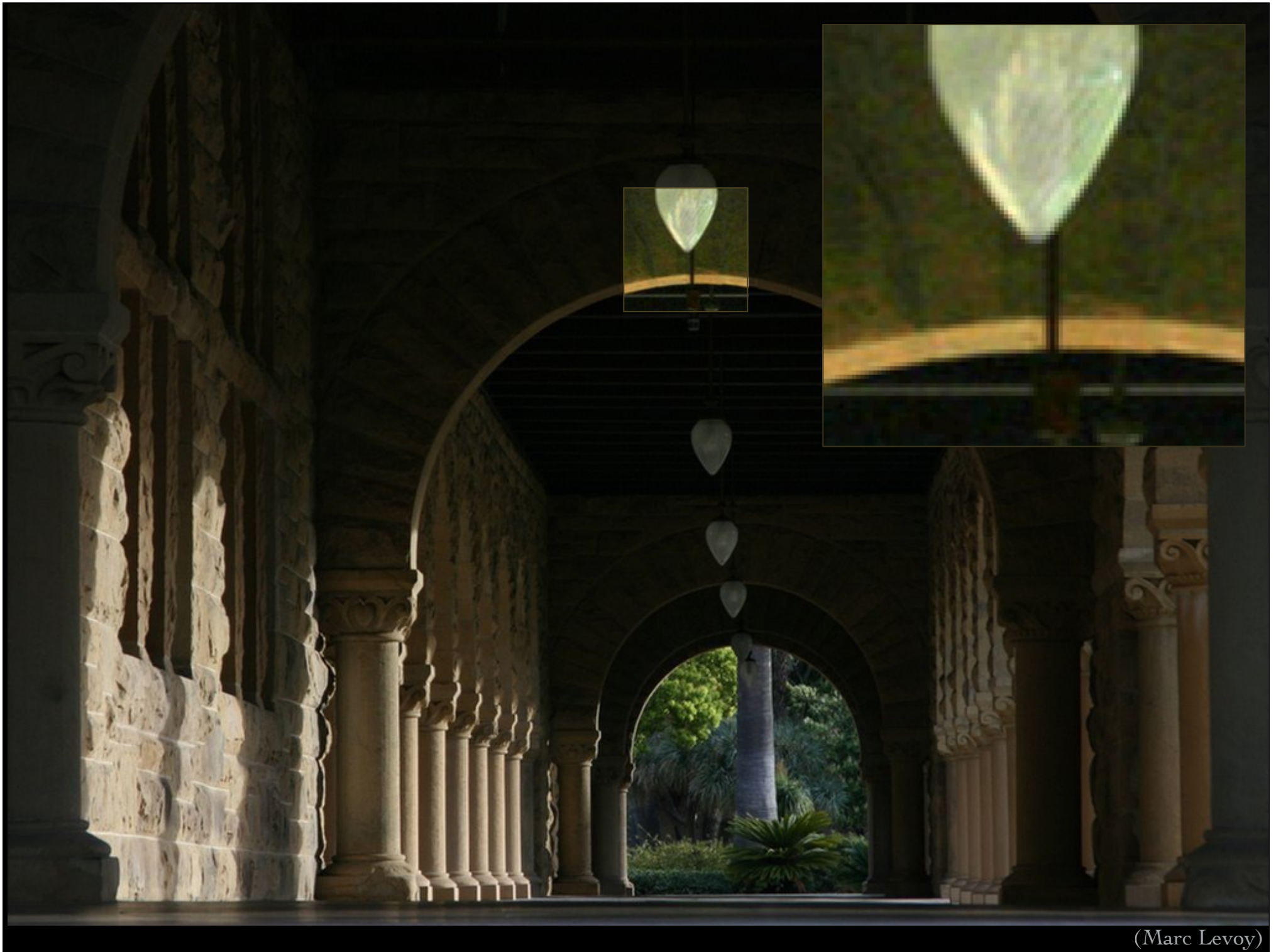
(Marc Levoy)



(Marc Levoy)



(Marc Levoy)



(Marc Levoy)



(Marc Levoy)



Cathedral,
Valencia

(Marc Levoy)



Cathedral,
Valencia

(Marc Levoy)



Cathedral,
Valencia

(Marc Levoy)

tone mapping in
Photoshop CS4
by exposure and
gamma



Cathedral,
Valencia

(Marc Levoy)

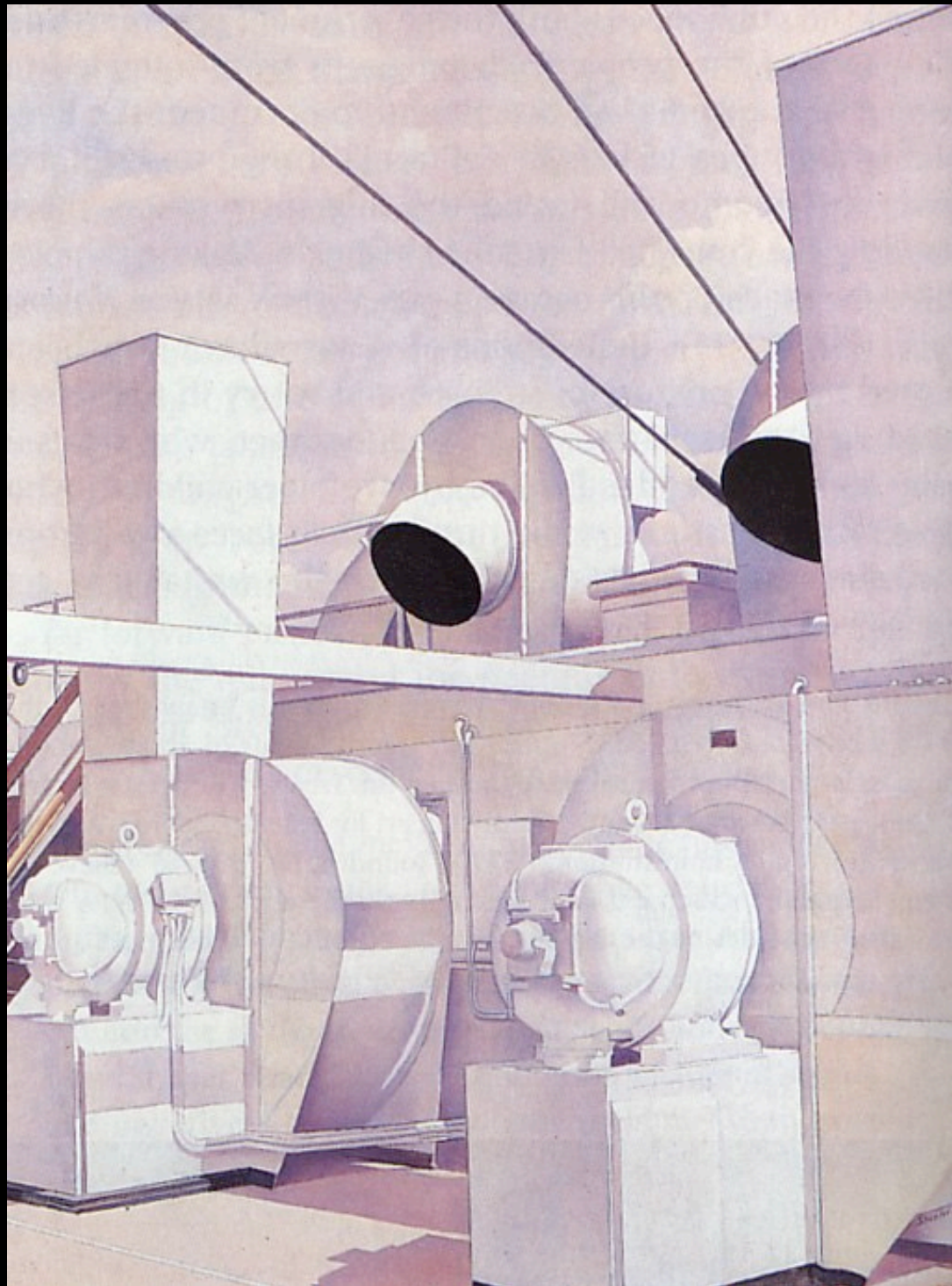
tone mapping in
Photoshop CS4
by histogram
equalization



Cathedral,
Valencia

(Marc Levoy)

How do artists solve the tone mapping problem?



Charles Sheeler,
The Upper Deck
(1929)



Joseph Wright, *The Orrery* (1765)

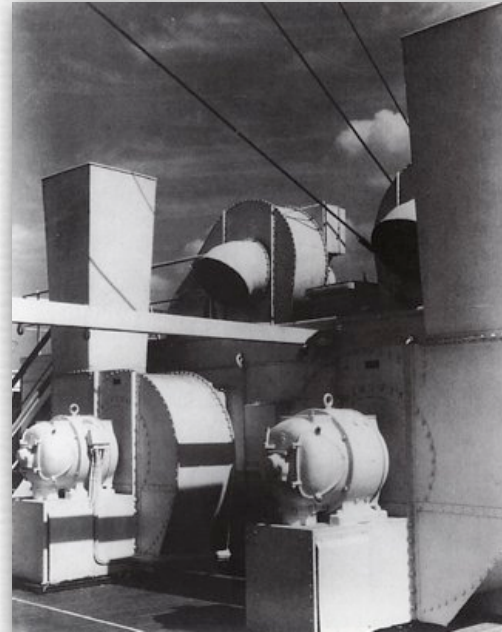
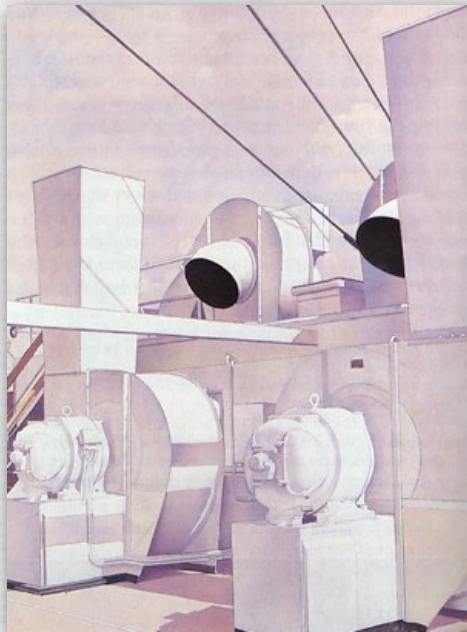
How do artists solve the tone mapping problem?



Hermann von Helmholtz
(1821-1894)

“The relation of optics to painting”

- ◆ for bright scenes
 - human vision is dazzled, compressing brightnesses
- ◆ for dark scenes
 - shadows are below threshold, so completely black

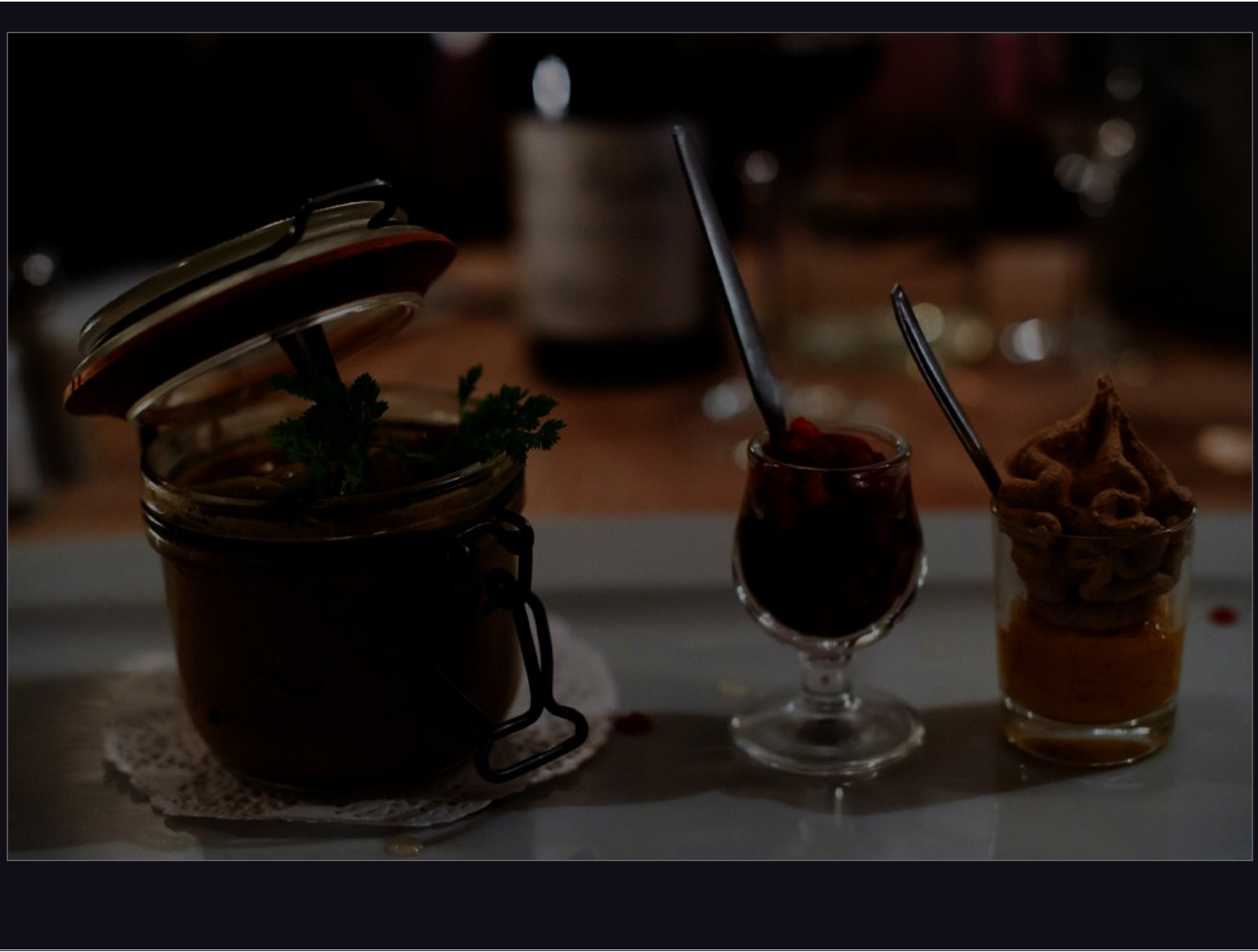


(Gardner)



(borrowed from lecture on noise)





Tone mapping techniques

(slides from Fredo Durand)

- ◆ image has 10,000:1 dynamic range, projector has 1000:1
- ◆ how can we compress the image's dynamic range?



Global tone mapping operators

- ◆ gamma compression, applied independently on R,G,B

$$\text{output} = \text{input}^\gamma \quad (\gamma = 0.5 \text{ here})$$

- ◆ colors become washed out

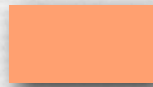
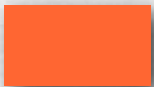
i.e. depend on gamma transform during RAW
→ JPEG conversion

input



output

$$(1.0, 0.4, 0.2)^{0.5} = (1.0, 0.63, 0.44)$$



(try it yourself in Photoshop)



Global tone mapping operators

- ◆ gamma compression on intensity only
- ◆ saturated but light colors become garish

luminance



(e.g. $0.3R+0.7G+0.01B$)

chrominance



(e.g. $R/lum, G/lum, B/lum$)



(from our convolution applet)

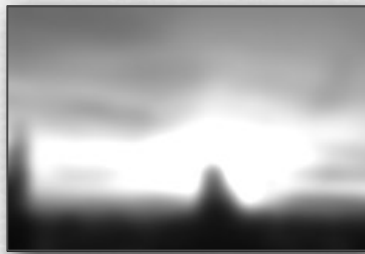
0.00	-2.00	0.00
-2.00	9.00	-2.00
0.00	-2.00	0.00

Local tone mapping operators



- ◆ reduce contrast of low frequencies, while preserving high frequencies [Oppenheim 1968, Chiu et al. 1993]
- ◆ produces halos!

low
frequency



(e.g. Gaussian blur)

high
frequency



(e.g. original - Gaussian)

chrominance



Local tone mapping operators

- ◆ bilateral filtering to compute large scale image without blurring across edges, remainder is detail image (no halos!); reduce contrast of large scale, while preserving details [Durand and Dorsey SIGGRAPH 2002]

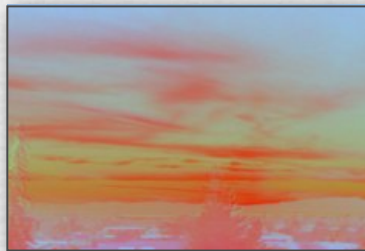
large
scale



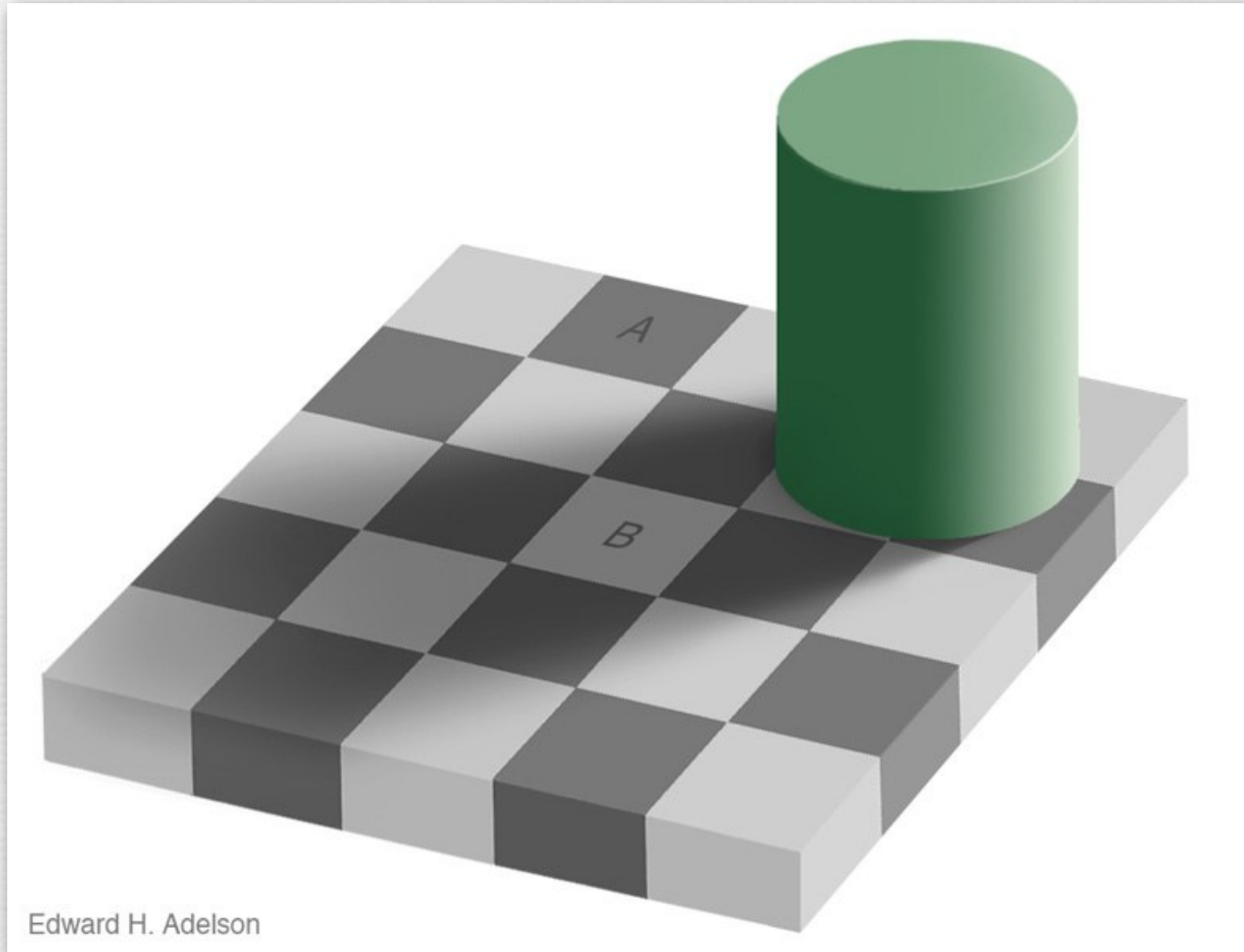
detail



chrominance

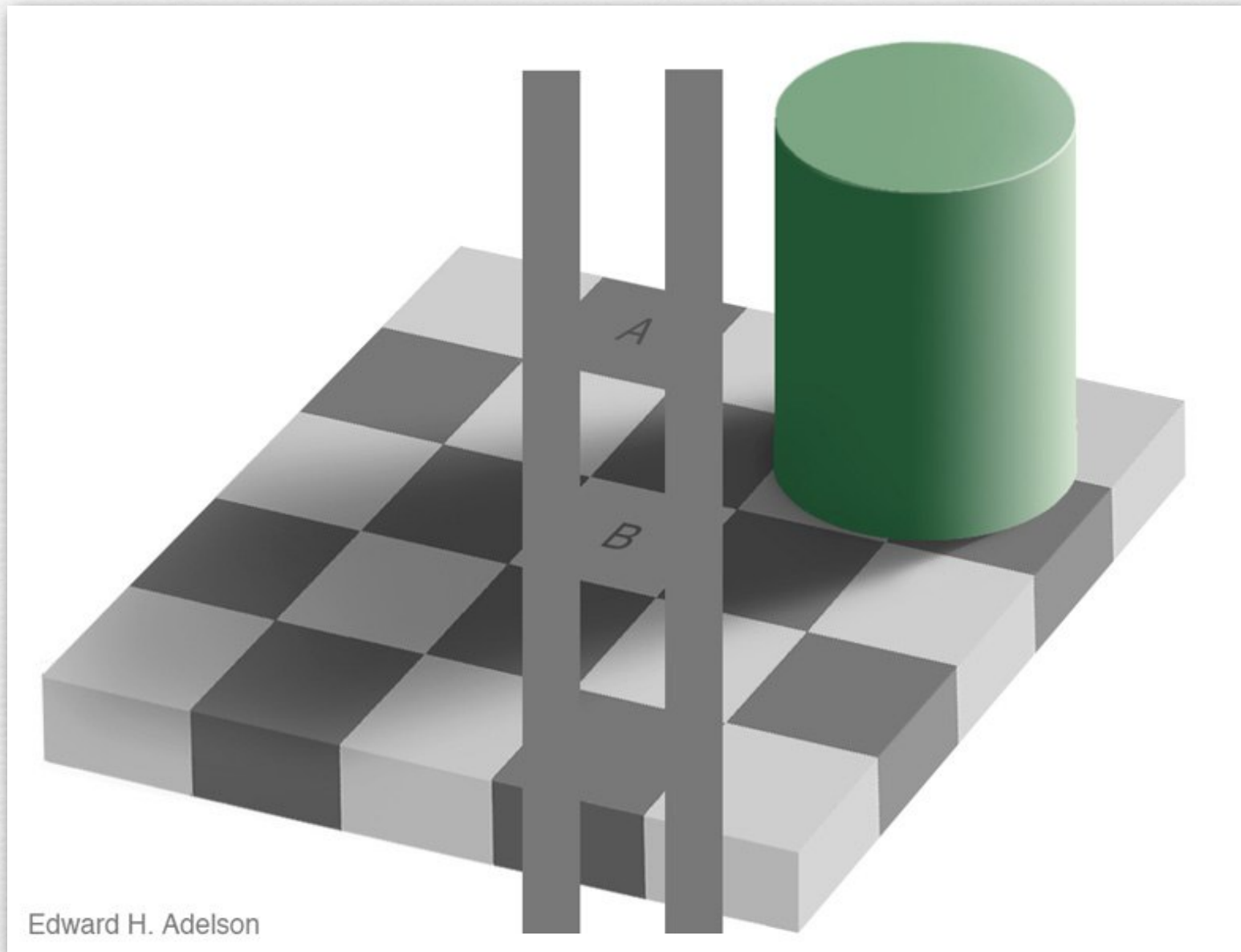


The importance of local contrast



Edward H. Adelson

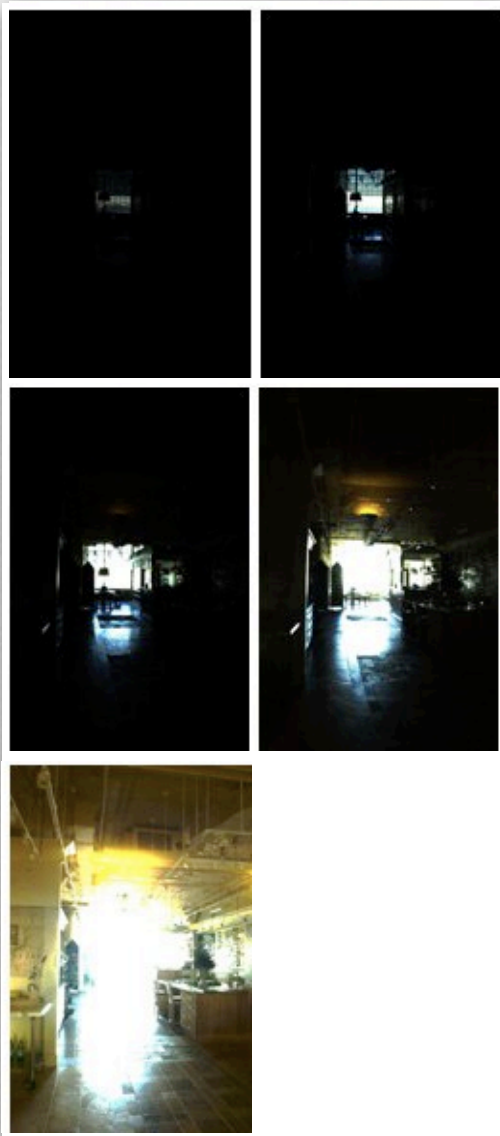
The importance of local contrast



Edward H. Adelson

Tone mapping using bilateral filters

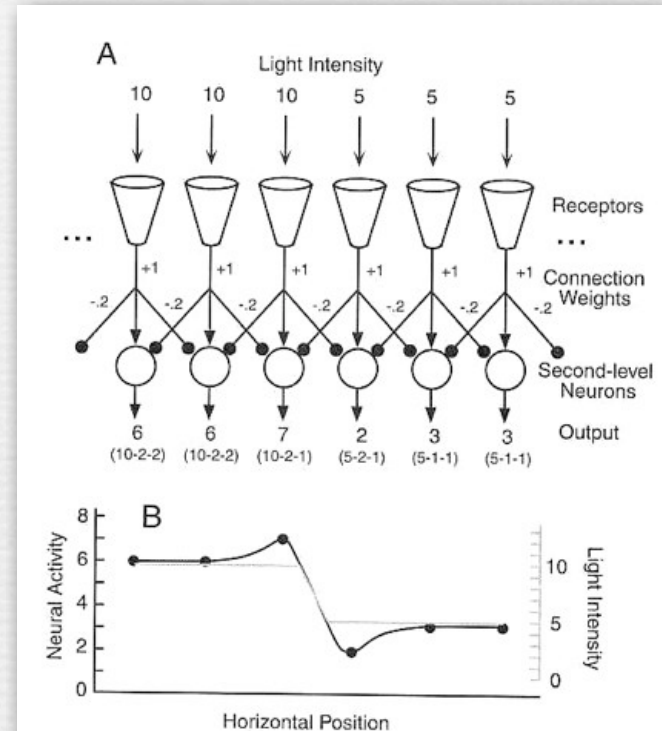
[Durand and Dorsey SIGGRAPH 2002]



Mach bands and lateral inhibition



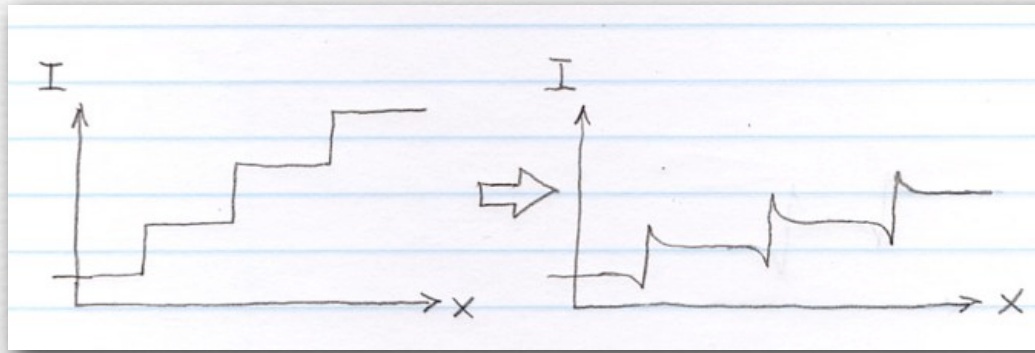
the Mach band illusion: each wedge should appear brighter on its right side



(Goldstein or Wolfe)

- ◆ lateral inhibition among receptive fields in the retina is equivalent to image convolution with a sharpening kernel

Why might tone mapping look cartoony? (contents of whiteboard)



- ◆ a step wedge (at left) is converted by a tone mapping operator that enhances local contrast to the plot at right
 - the human eye does this internally due to lateral inhibition, but that doesn't necessarily mean we want to present an image like this to the human eye!



La Grande Jatte, Georges Seurat, 1884

(Marc Levoy)

Commissary,
Fort Ross, CA,
2010

(Panasonic ZS3,
1/30s, ISO 125)



(Marc Levoy)

Commissary,
Fort Ross, CA,
2010

(Panasonic ZS3,
1/30s, ISO 250)



(Marc Levoy)

Commissary,
Fort Ross, CA,
2010

(Panasonic ZS3,
1/25s, ISO 400)



(Marc Levoy)

Commissary,
Fort Ross, CA,
2010

(Panasonic ZS3,
1/13s, ISO 400)



(Marc Levoy)

Commissary,
Fort Ross, CA,
2010

(Panasonic ZS3,
1/8s, ISO 400)



(Marc Levoy)

Commissary,
Fort Ross, CA,
2010

(tone mapped HDR using Photomatix
v3.3.2's "detail enhancer" algorithm)



(Marc Levoy)

Commissary,
Fort Ross, CA,
2010

(tone mapped HDR using Photomatix
v3.3.2's "tone compressor" algorithm)



(Marc Levoy)

based on [Mertens 2007]

- directly blends original images, without first computing an HDR image
- downweights noisy and saturated pixels
- multi-band blending to avoid seams
- not physically based, but simple and fast

Commissary,
Fort Ross, CA,
2010

(tone mapped HDR using Photomatix
v3.3.2's "exposure fusion" algorithm)



(Marc Levoy)



Stanford Arcade, 2009 (1/160s, f/6.3, ISO 100)

(Marc Levoy)



Stanford Arcade, 2009 (1/125s, f/5.6, ISO 100)

(Marc Levoy)




Stanford Arcade, 2009 (1/100s, f/5.4, ISO 100)

(Marc Levoy)



Stanford Arcade, 2009 (Photomatix 3.3.2, “tone compressor” algorithm)

(Marc Levoy)



so was HDR imaging
necessary in this
case?

Stanford Arcade, 2009 (1/125s, f/5.6, ISO 100)

(Marc Levoy)



Stanford Arcade, 2009 (Photomatix 3.3.2, “tone compressor” algorithm)

(Marc Levoy)

The HDR “look”



The HDR “look”



The HDR “look”

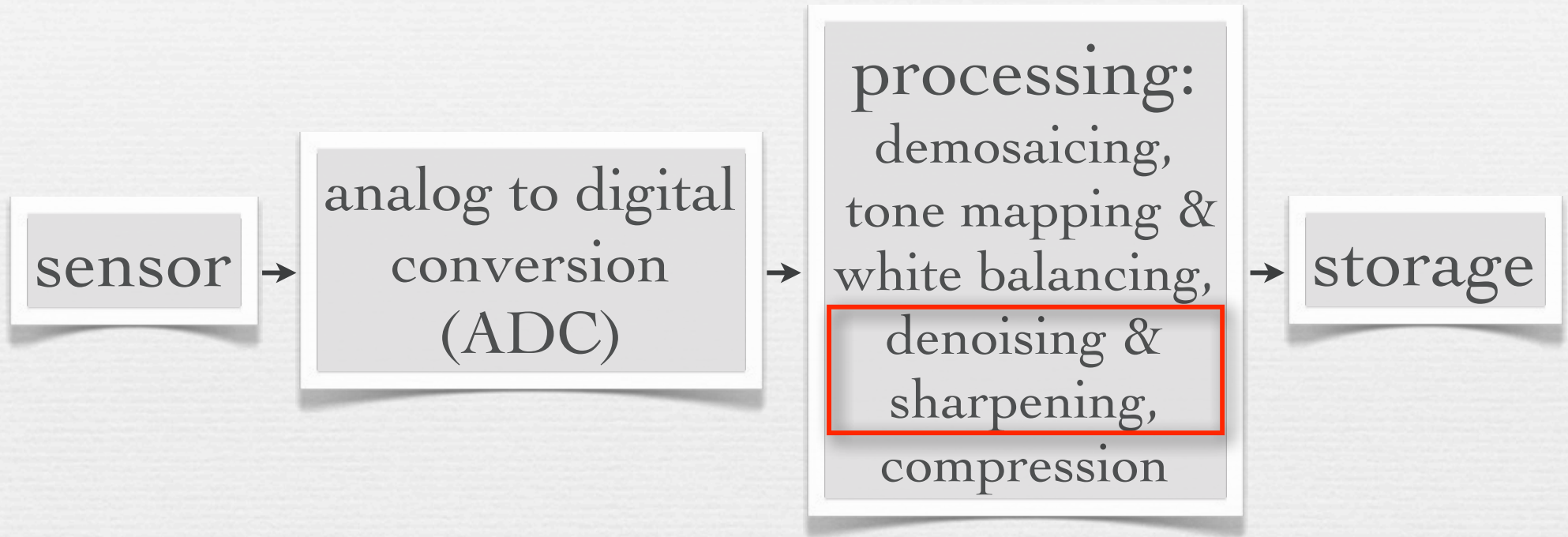


Recap

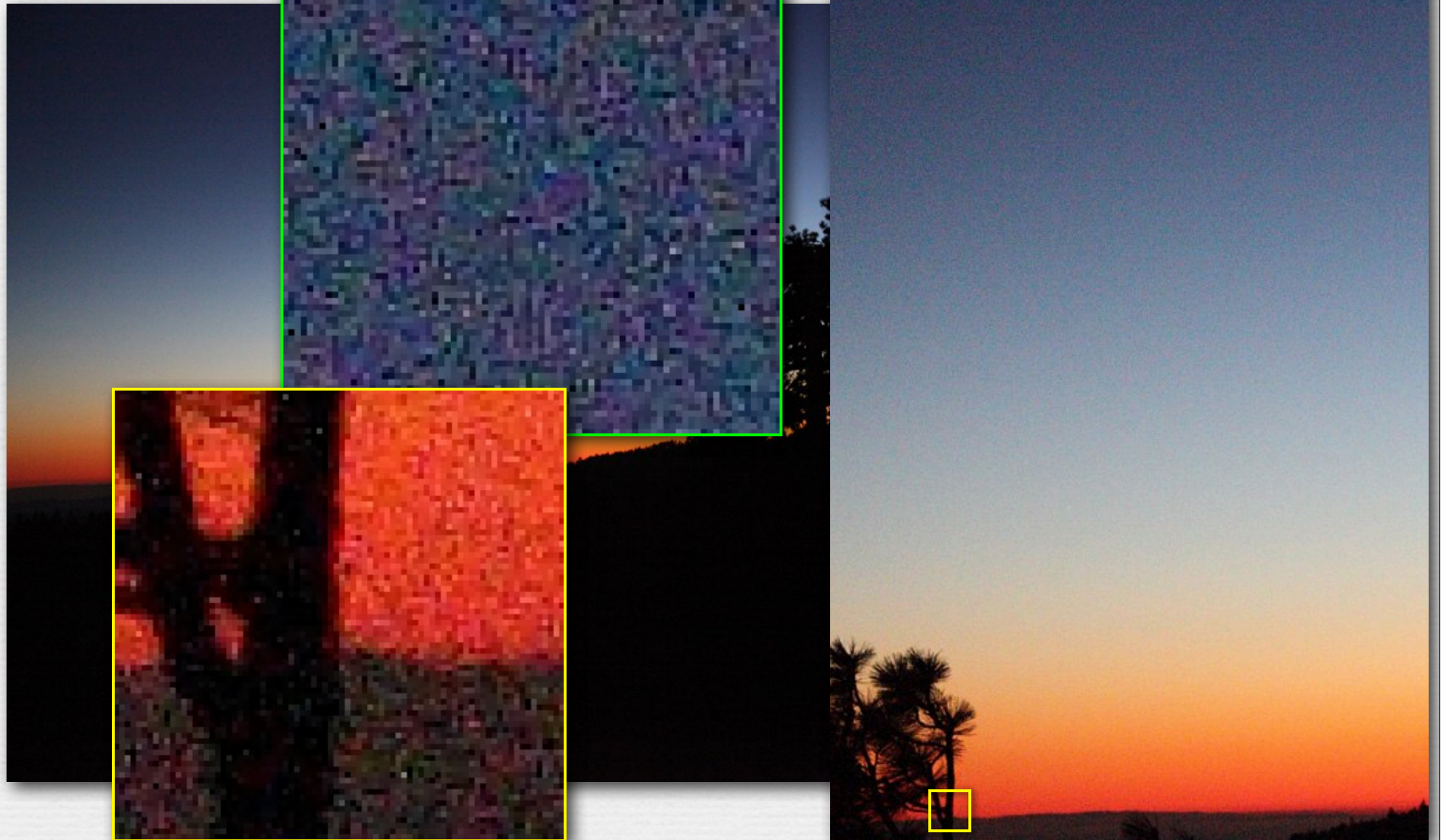
- ◆ high dynamic range (HDR) imaging is useful, and a new aesthetic, but is not necessary in most photographic situations
 - SLRs have more useful dynamic range (~12 bits) than point-and-shoot cameras or cell phones, i.e. w/o shadows being noisy
- ◆ low dynamic range (LDR) tone mapping methods apply to HDR, but reducing 12 bits to 8 bits using only global methods is hard
 - the reduction is needed for JPEG, display, and printing
- ◆ successful methods reduce large-scale luminance changes (across the image) while preserving *local contrast* (across edges)
 - use bilateral filtering to isolate large-scale luminance changes
- ◆ these methods mimic *lateral inhibition* in the human visual system
 - but this may not justify applying them to an image before sensing

Questions?

Camera pixel pipeline



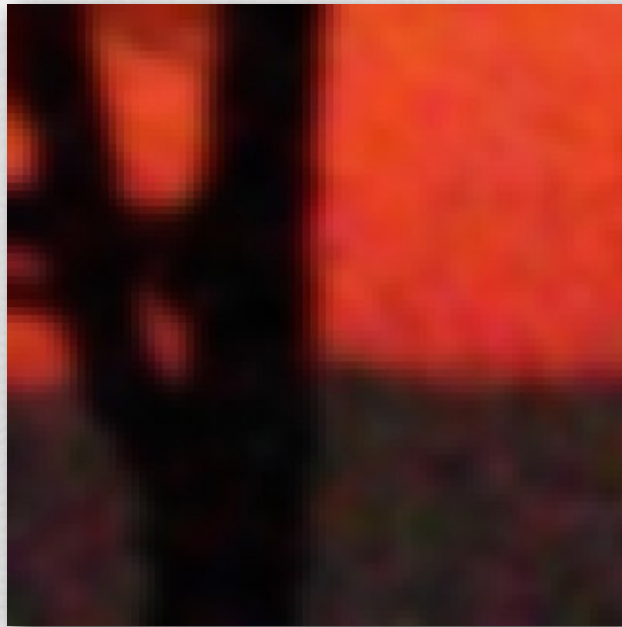
Canon 5D II at dusk



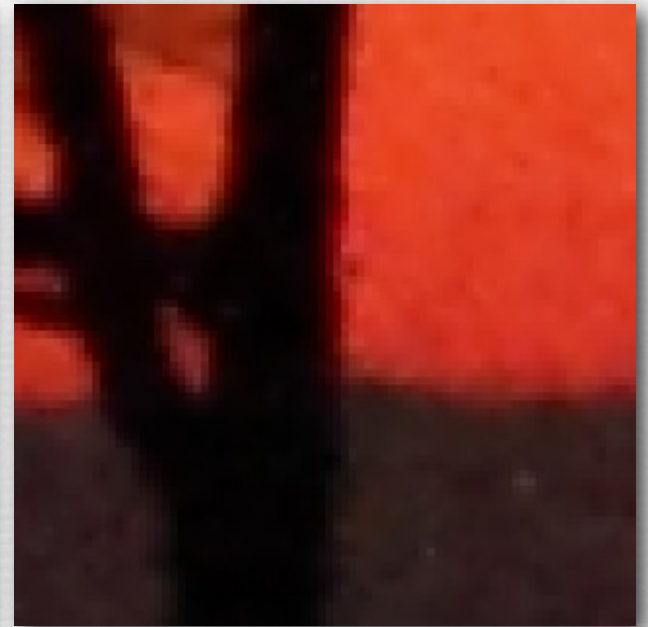
Denoising



RAW (ISO 6400)



Gaussian blur, radius = 1.3

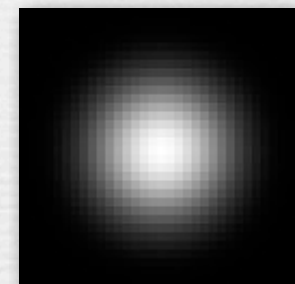
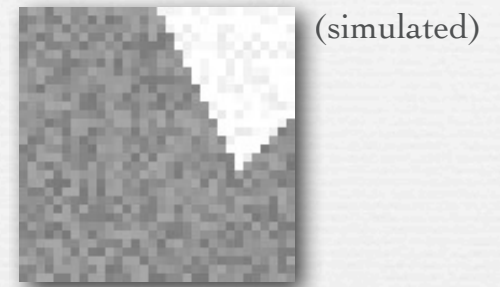


Canon denoising

- ◆ goal is to remove sensor noise
 - blurring works, but also destroys edges
 - I don't know what Canon does, but here's something that works...

Bilateral filtering [Tomasi ICCV 1998]

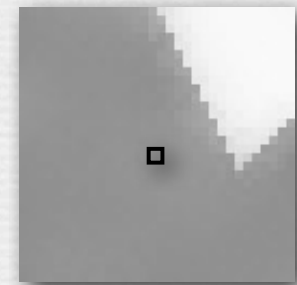
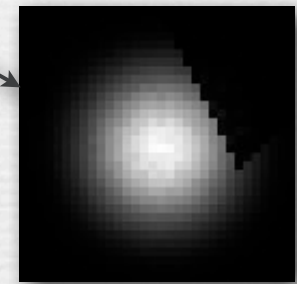
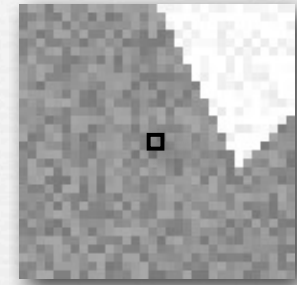
- ◆ images are often piecewise constant with noise added
 - in this case, nearby pixels are often a different noisy measurement of the same data
- ◆ simple blurring doesn't work
 - because it also blurs the edges
- ◆ we should blur only within each constant-colored scene region
 - not across edges between regions



Bilateral filtering

- ◆ if the pixels are similar in intensity, they are probably from the same region of the scene
- ◆ so perform a convolution where the weight applied to nearby pixels in the summation falls off
 - with increasing (x,y) distance from the pixel being blurred
 - with increasing intensity difference from the pixel being blurred
- ◆ i.e. blur in *domain* and *range* dimensions!

effective filter weights are thus different for each pixel of input



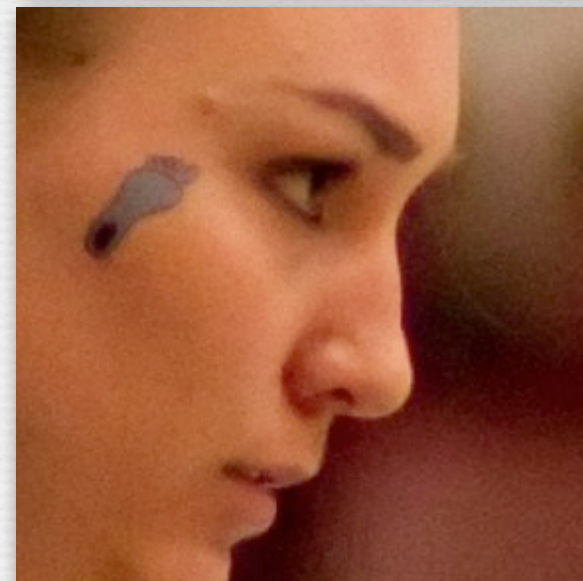
Example of bilateral filtering

Women's
gymnastics

(Canon 7D,
1/1000 sec,
ISO 3200,
f/1.8, 85mm)



original



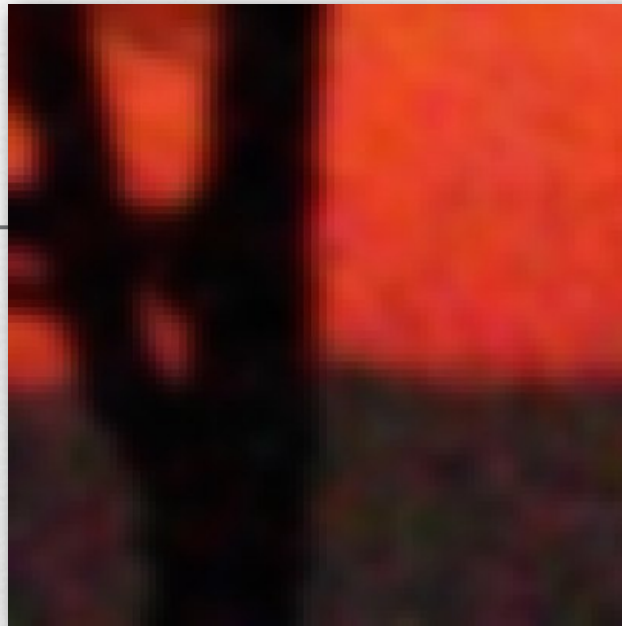
denoised in
Noise Ninja

Denoising

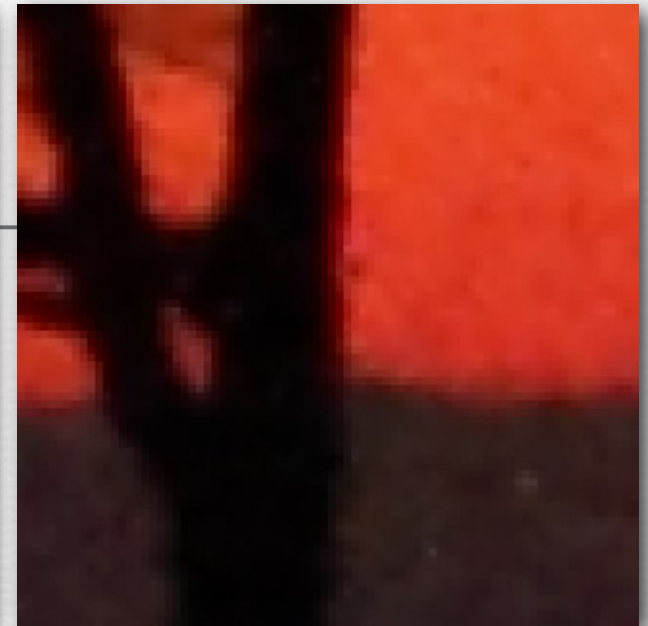


RAW (ISO 6400)

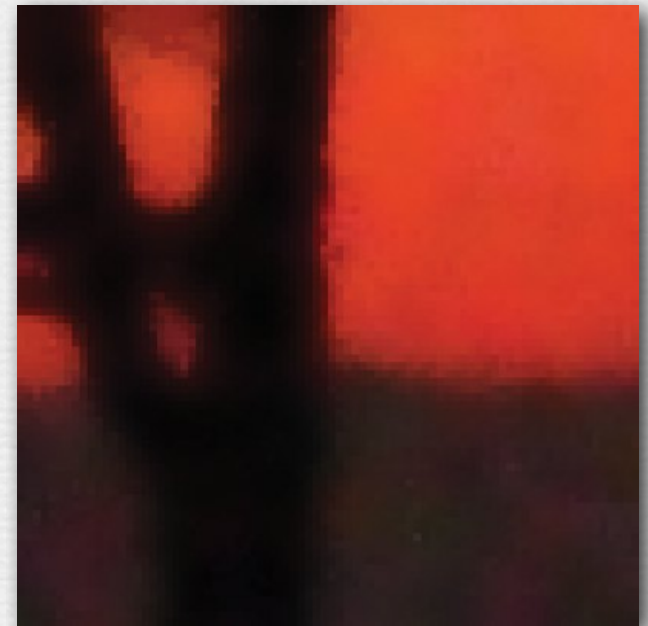
- ◆ bilateral filtering removes sensor noise without blurring edges
- ◆ can easily be extended to RGB



Gaussian blur, radius = 1.3



Canon denoising



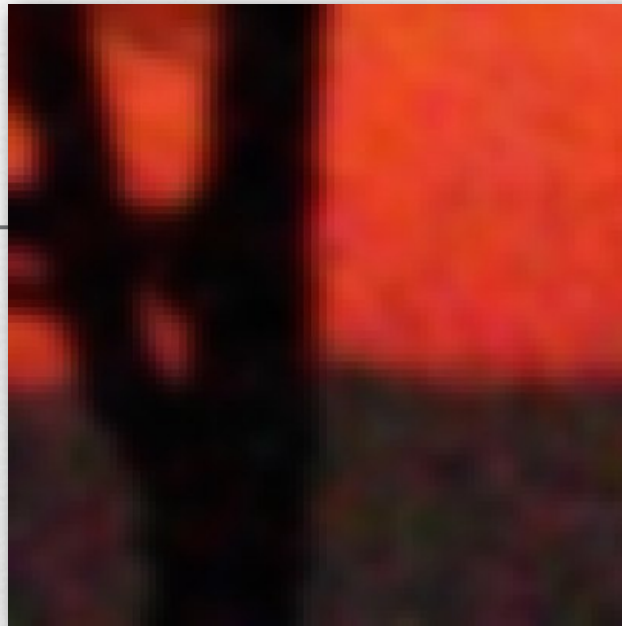
bilateral filtering

Denoising

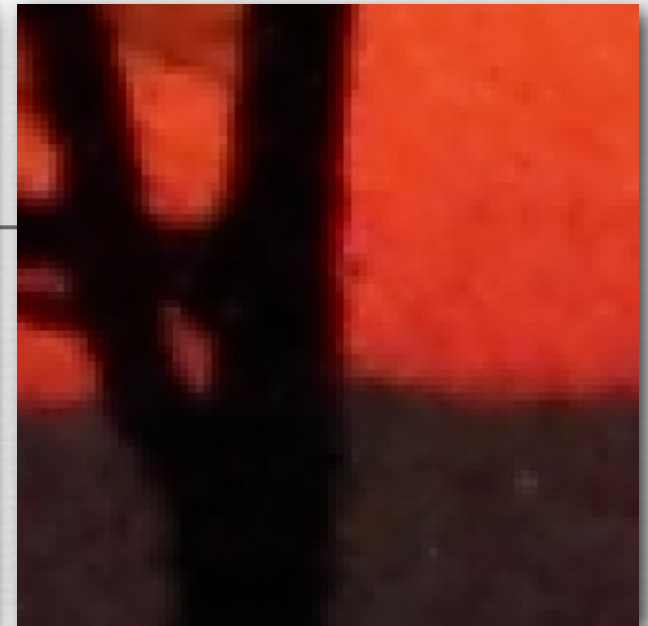


RAW (ISO 6400)

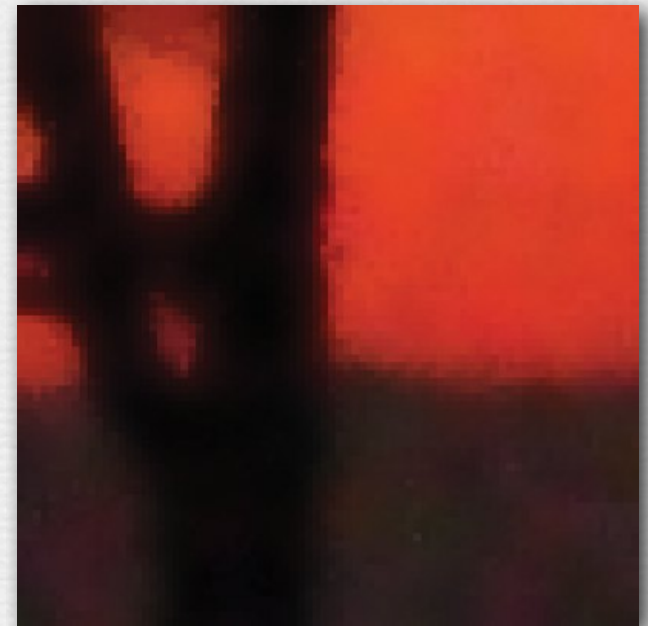
- ◆ can be applied more (or less) strongly to chrominance than luminance
- ◆ can be combined with demosaicing
- ◆ active area of research...



Gaussian blur, radius = 1.3



Canon denoising



bilateral filtering

Sharpening

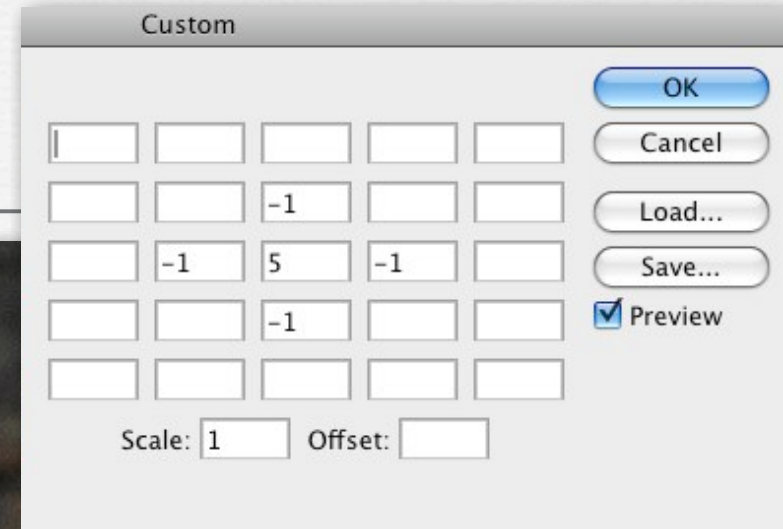


original

(Marc Levoy)

© Marc Levoy

Sharpening



Filter/Other/Custom
in Photoshop CS4

Sharpening



Custom

<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>
<input type="text"/>	<input type="text"/>	-2	<input type="text"/>	<input type="text"/>
<input type="text"/>	-2	9	-2	<input type="text"/>
<input type="text"/>	<input type="text"/>	-2	<input type="text"/>	<input type="text"/>
<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>

Scale: Offset:

Preview

Filter/Other/Custom
in Photoshop CS4

Sharpening

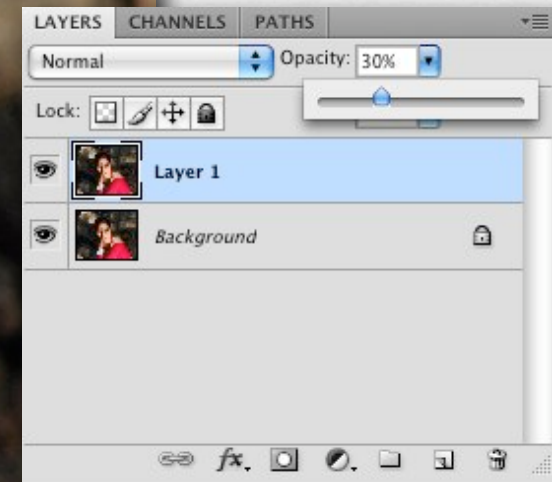
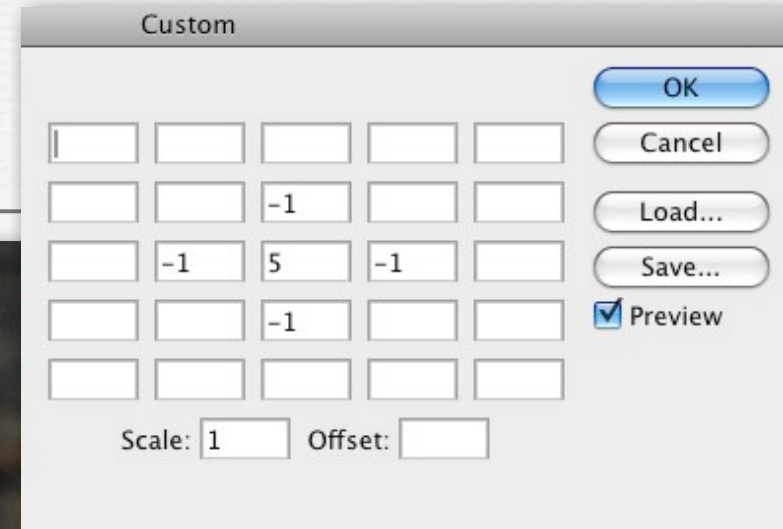


original

(Marc Levoy)

© Marc Levoy

Sharpening

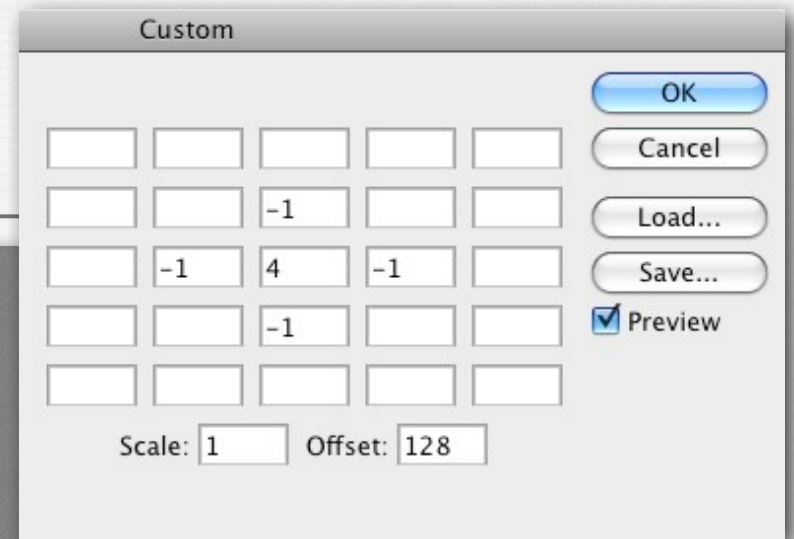
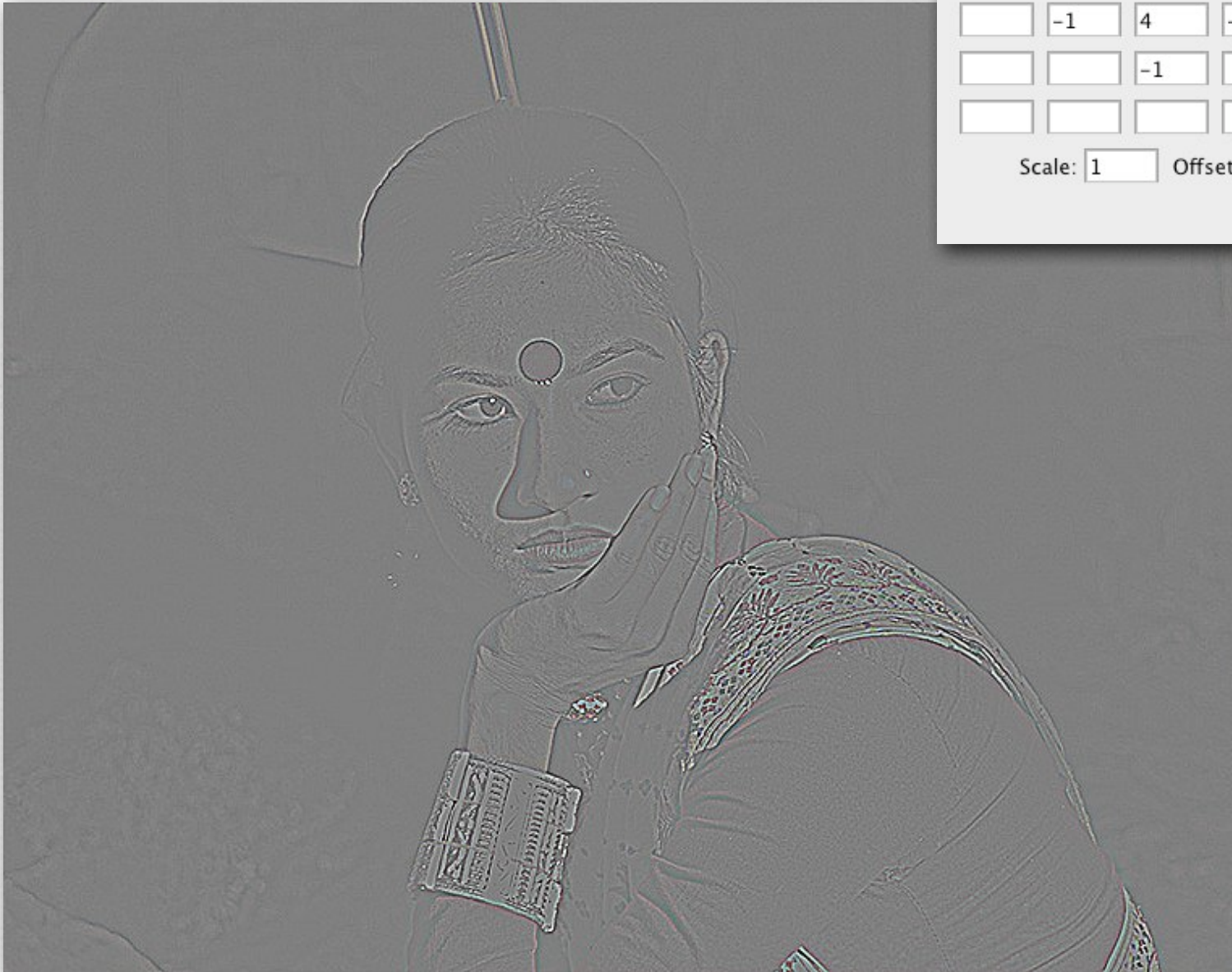


1st layer is original,
2nd layer is sharpened,
blend w. 30% opacity

(Marc Levoy)

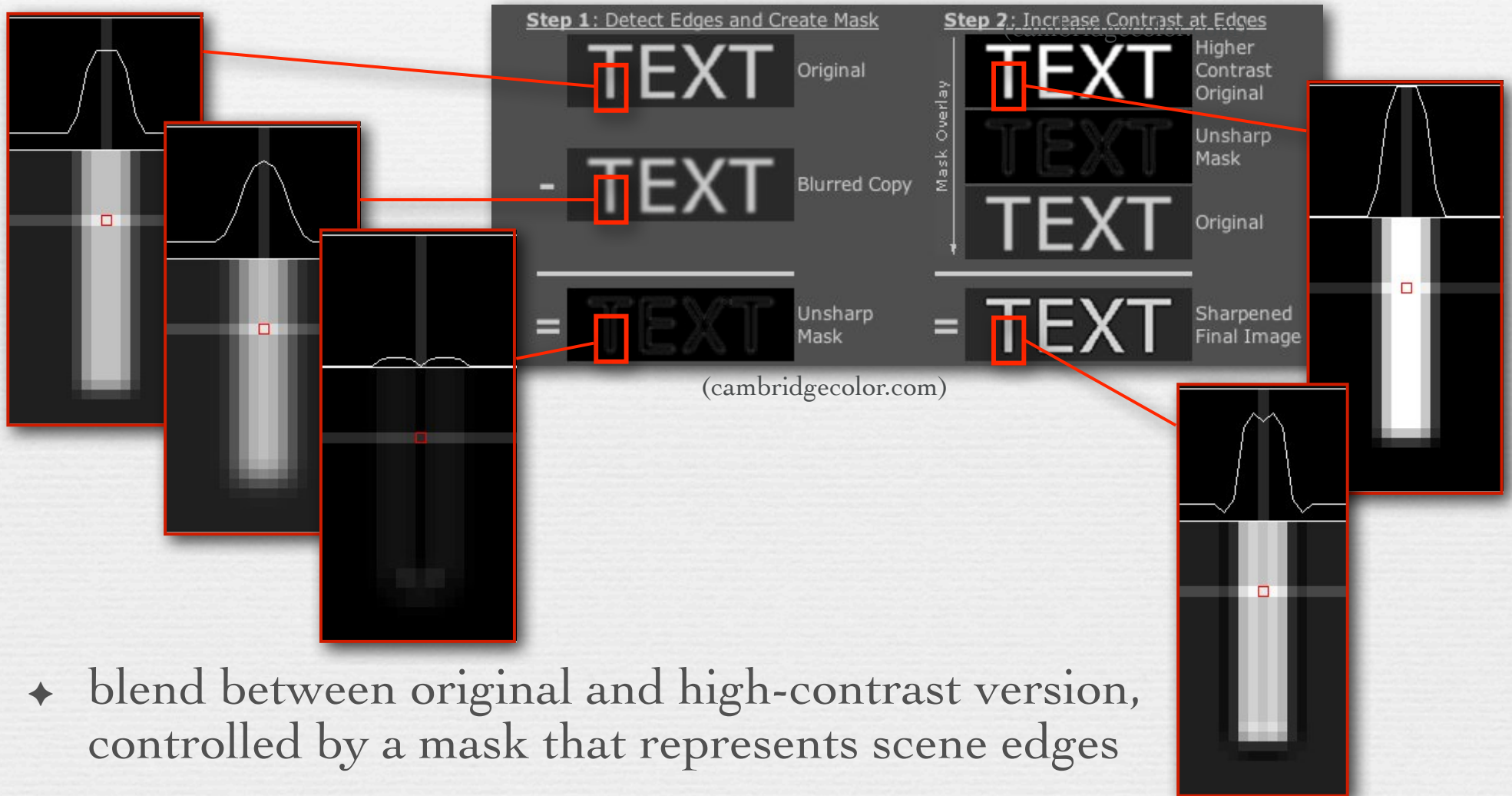
© Marc Levoy

Sharpening



Filter/Other/Custom
in Photoshop CS4

Unsharp masking



- ◆ blend between original and high-contrast version, controlled by a mask that represents scene edges
- ◆ dropping (thresholding) the darkest mask pixels avoids sharpening noise, and makes the filter non-linear

Sharpening



Custom

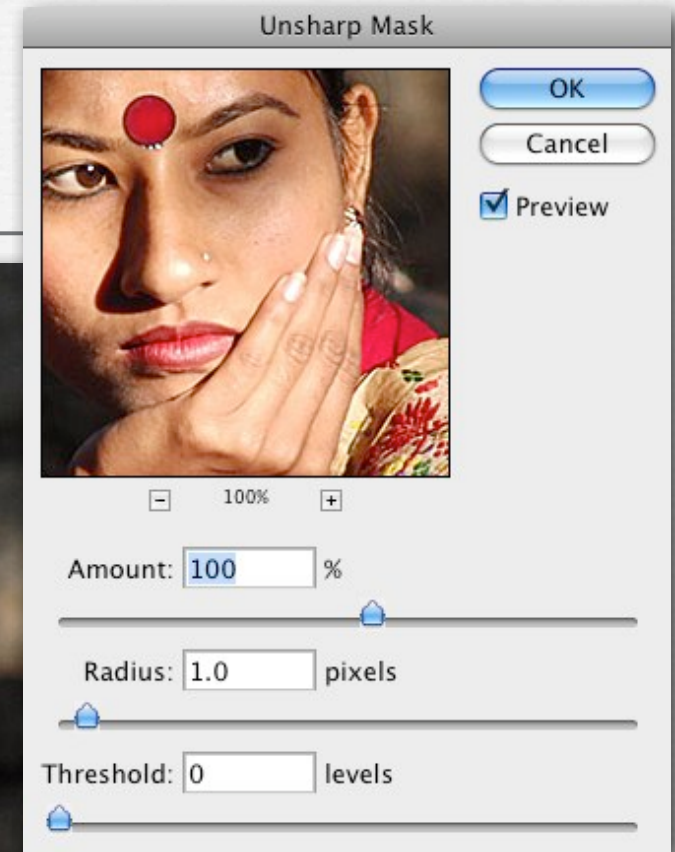
<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>
<input type="text"/>	<input type="text"/>	-1	<input type="text"/>	<input type="text"/>
<input type="text"/>	-1	5	-1	<input type="text"/>
<input type="text"/>	<input type="text"/>	-1	<input type="text"/>	<input type="text"/>
<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>

Scale: Offset:

Preview

Filter/Other/Custom
in Photoshop CS4

Sharpening



Filter/Sharpen/
Unsharp Mask in CS4

Sharpening



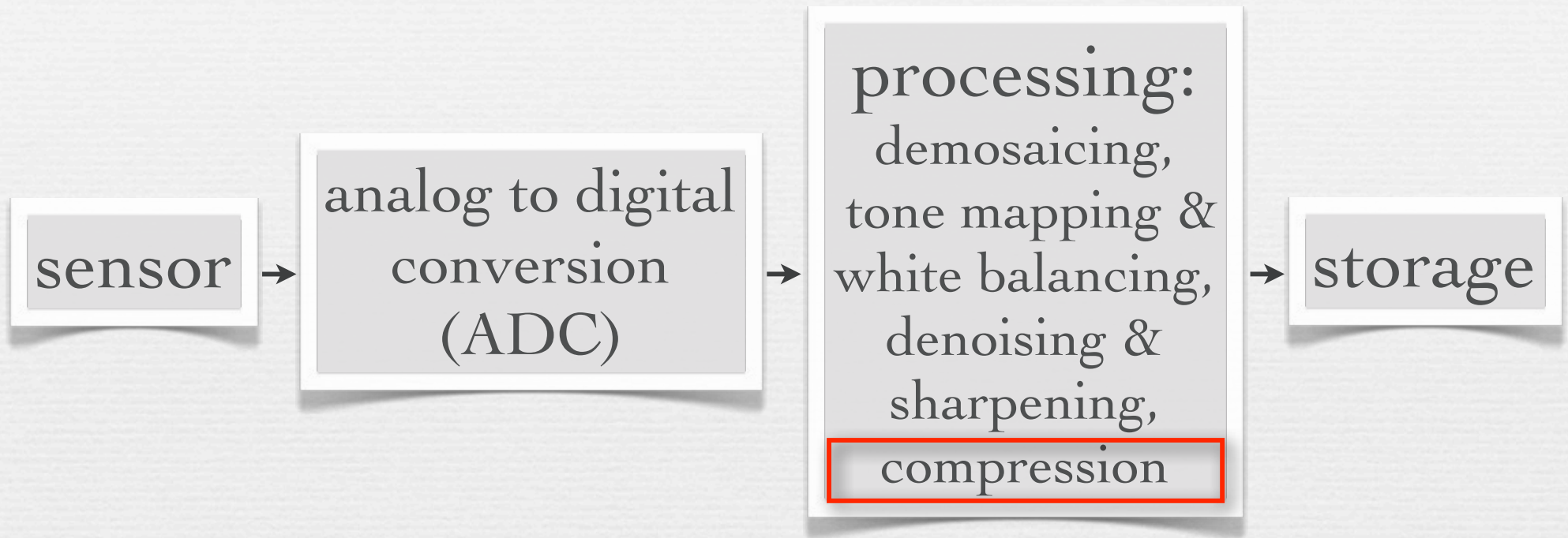
original

Recap

- ◆ *bilateral filtering* reduces noise while preserving edges
 - replaces each pixel with a weighted sum of its neighbors, where the weight drops with increasing distance from the pixel in X and Y and with increasing intensity difference
- ◆ *unsharp masking* sharpens edges but doesn't sharpen noise
 - replaces each pixel with a weighted sum of the original and a contrast-enhanced version, using the latter along edges, where the edge mask is $\text{threshold}(\text{original} - \text{blur}(\text{original}))$
- ◆ both are non-linear filters
 - i.e. they are not convolutions by a spatially invariant filter kernel

Questions?

Camera pixel pipeline



JPEG files

- ◆ Joint Photographic Experts Group
 - organized 1986, standard adopted 1994
- ◆ defines how an image is to be compressed (*codec*) into a stream of bytes, and the file format for storing that stream
 - file format is JFIF, but people use .JPG or .JPEG extensions
- ◆ good for compressing images of natural scenes
 - not so good for compressing drawings or graphics
- ◆ *lossy*, so loses quality each time you open → edit → save
 - especially if you crop or shift pixels (hence block boundaries)
 - for *lossless* compression, use PNG or TIFF

EXIF data

- ◆ Exchangeable Image File Format
 - created by Japan Electronic Industries Development Assoc.
- ◆ used by nearly every digital camera manufactured today
 - actually a file format
 - JPEG or TIFF file + metadata about the camera and shot
 - .JPG or .JPEG extension is used, not .EXIF

EXIF data

File/File Info in
Photoshop CS4

(Marc Levoy)



shot with Canon 5D Mark II

Color Space: sRGB

male-pine-cones.JPG

Description IPTC Camera Data Video Data

Camera Data 1

Make: Canon
Model: Canon EOS 5D Mark II
Date Time: 2/1/2009 - 3:24 PM
Shutter Speed: 1/250 sec
Exposure Program: Normal program
F-Stop: f/5.6
Aperture Value: f/5.6
Max Aperture Value:
ISO Speed Ratings: 200
Focal Length: 105 mm
Lens:
Flash: Did not fire
No strobe return detection (0)
Compulsory flash suppression (2)
Flash function present
No red-eye reduction
Metering Mode: Pattern

Camera Data 2

Pixel Dimension X: 5616 Y: 3744
Orientation: Normal
Resolution X: 72 Y: 72
Resolution Unit: Inch
Compressed Bits per Pixel:
Color Space: sRGB
Light Source:
File Source:

Powered By **xmp**[™] Import... Cancel OK

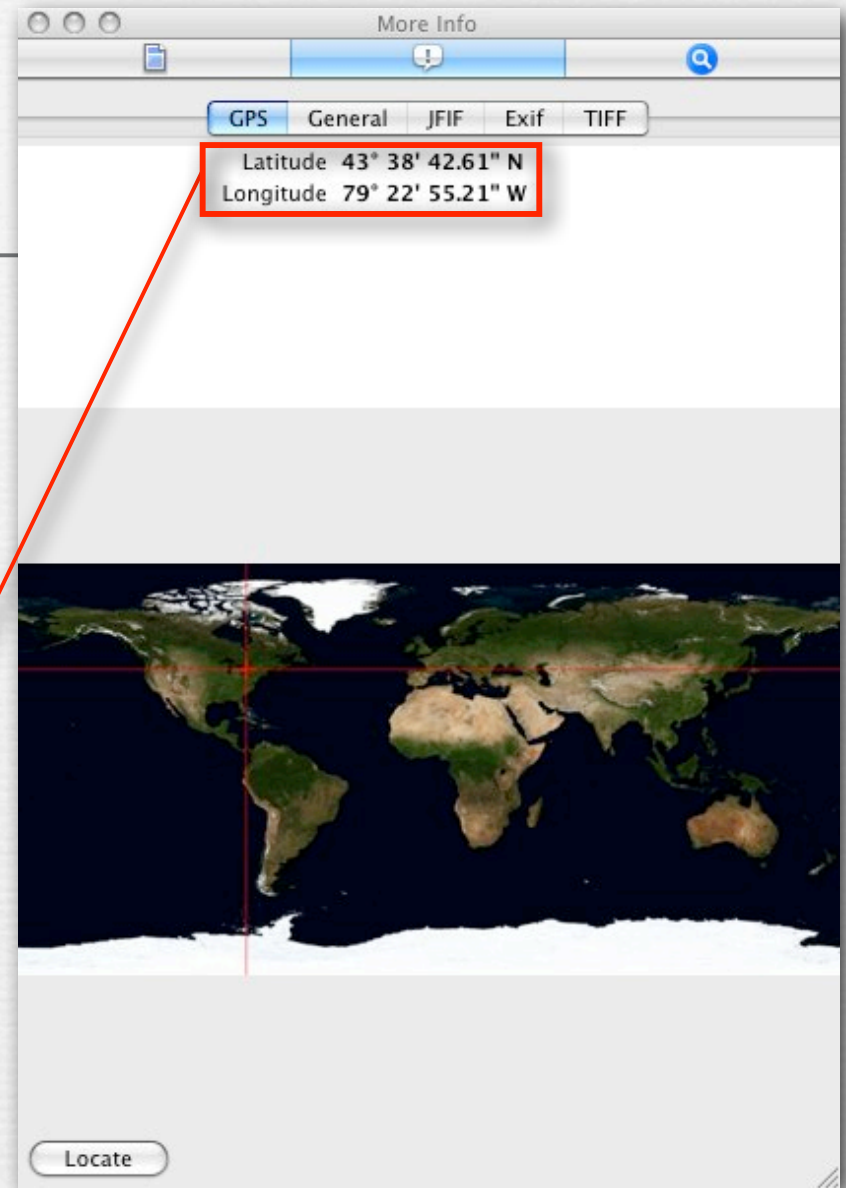
EXIF data

Mac
Preview



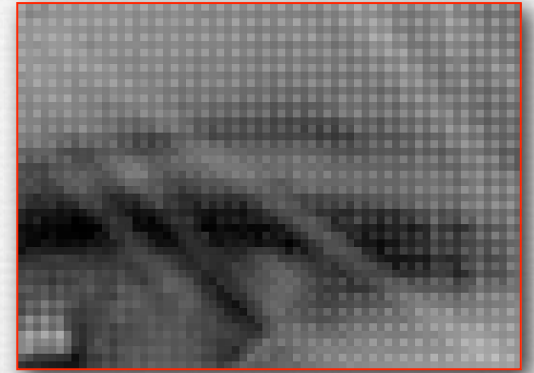
shot with iPhone 3G

Latitude 43° 38' 42.61" N
Longitude 79° 22' 55.21" W



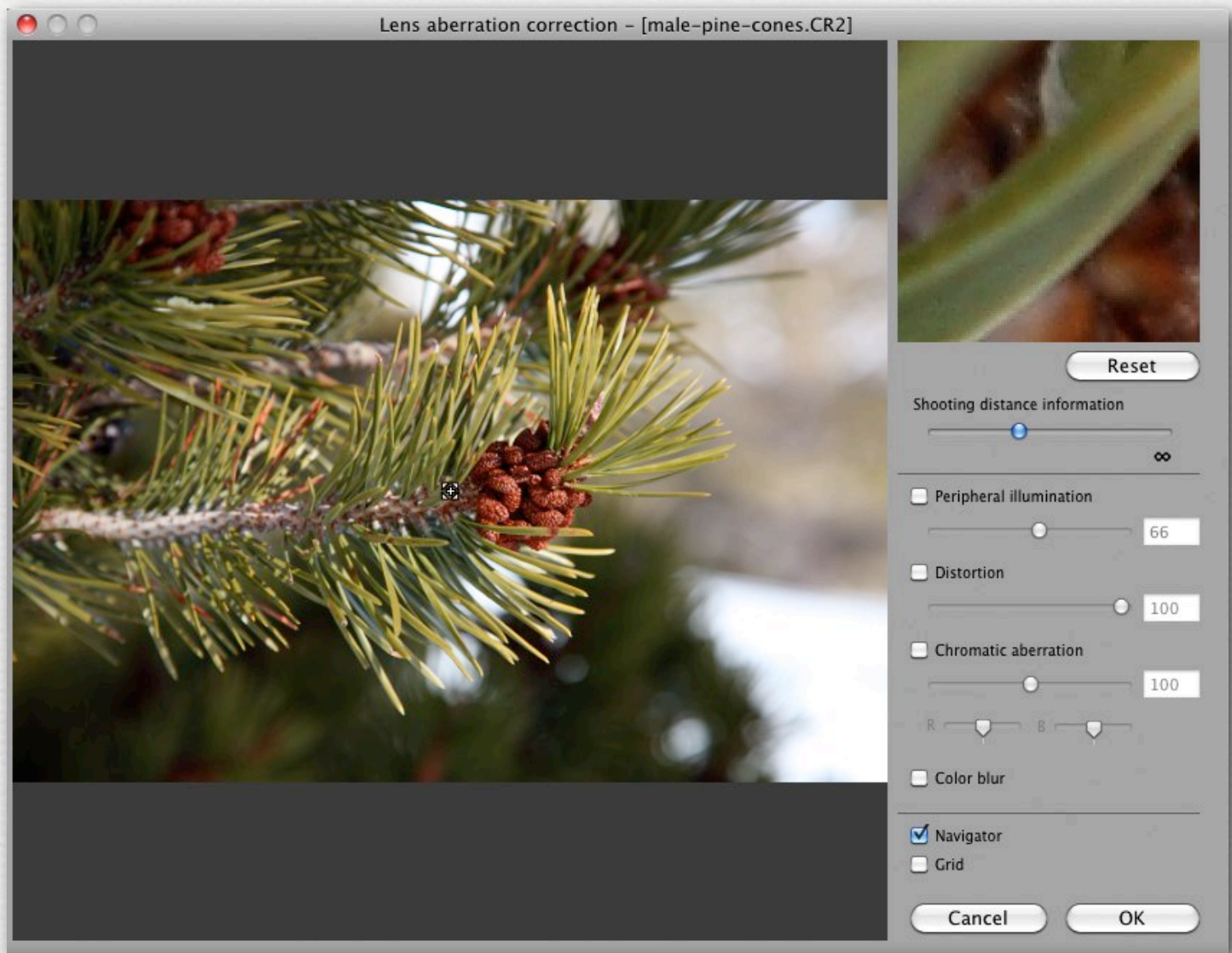
RAW files

- ◆ minimally processed images, not even demosaiced
- ◆ uncompressed or losslessly compressed
- ◆ includes metadata, possibly encrypted
- ◆ file format varies by manufacturer
- ◆ example extensions: .CR2, .NEF, .RW2, .ARW
- ◆ processed and converted to a JPEG file using
 - proprietary software (e.g. Canon Digital Photo Professional)
 - Photoshop or Lightroom (if they support your camera)
 - freeware programs like `dcraw`
 - or in your camera (every time you store a JPEG)
 - but their processing algorithms are all different!



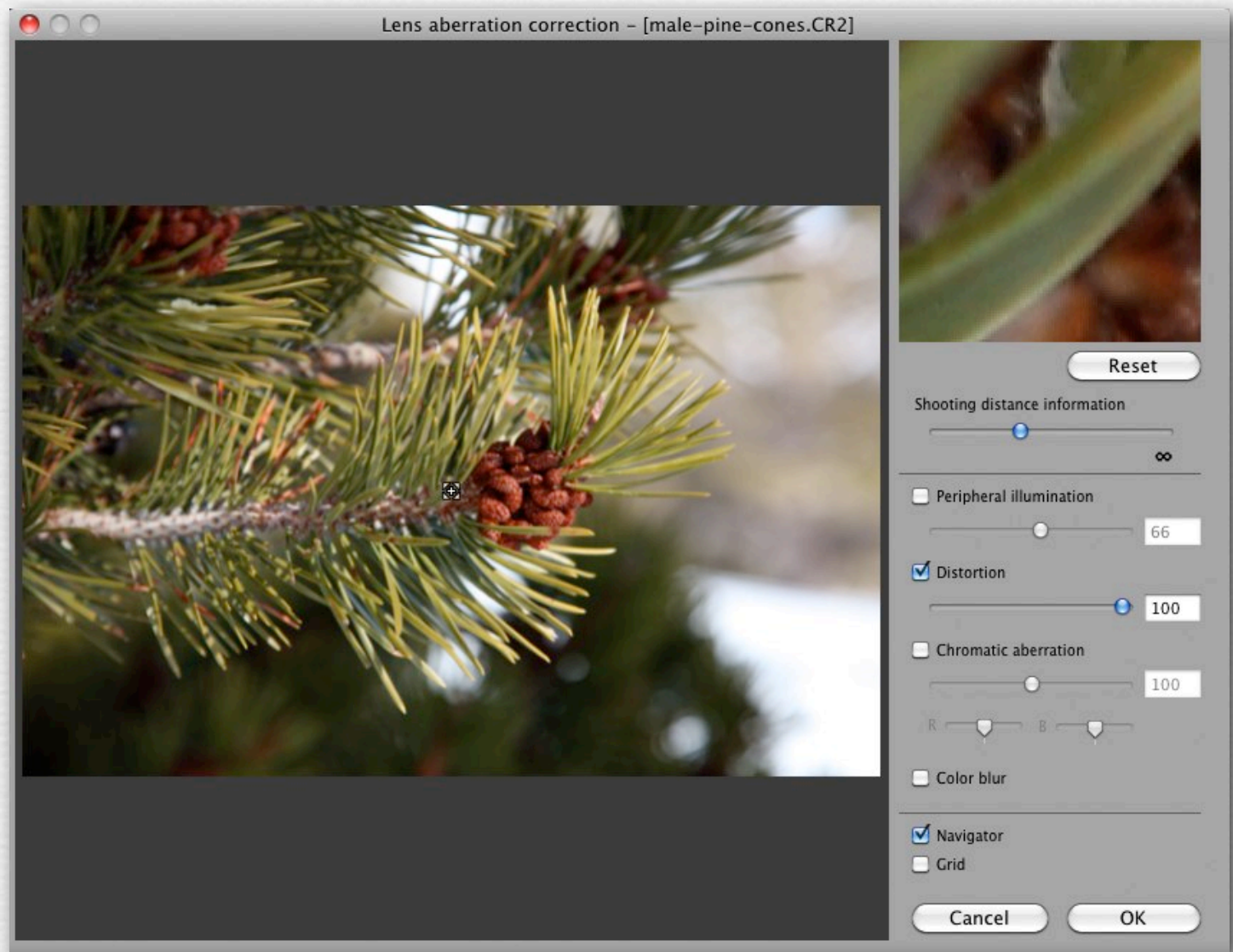
RAW file processor

Lens aberration correction panel in
Canon Digital
Photo Professional



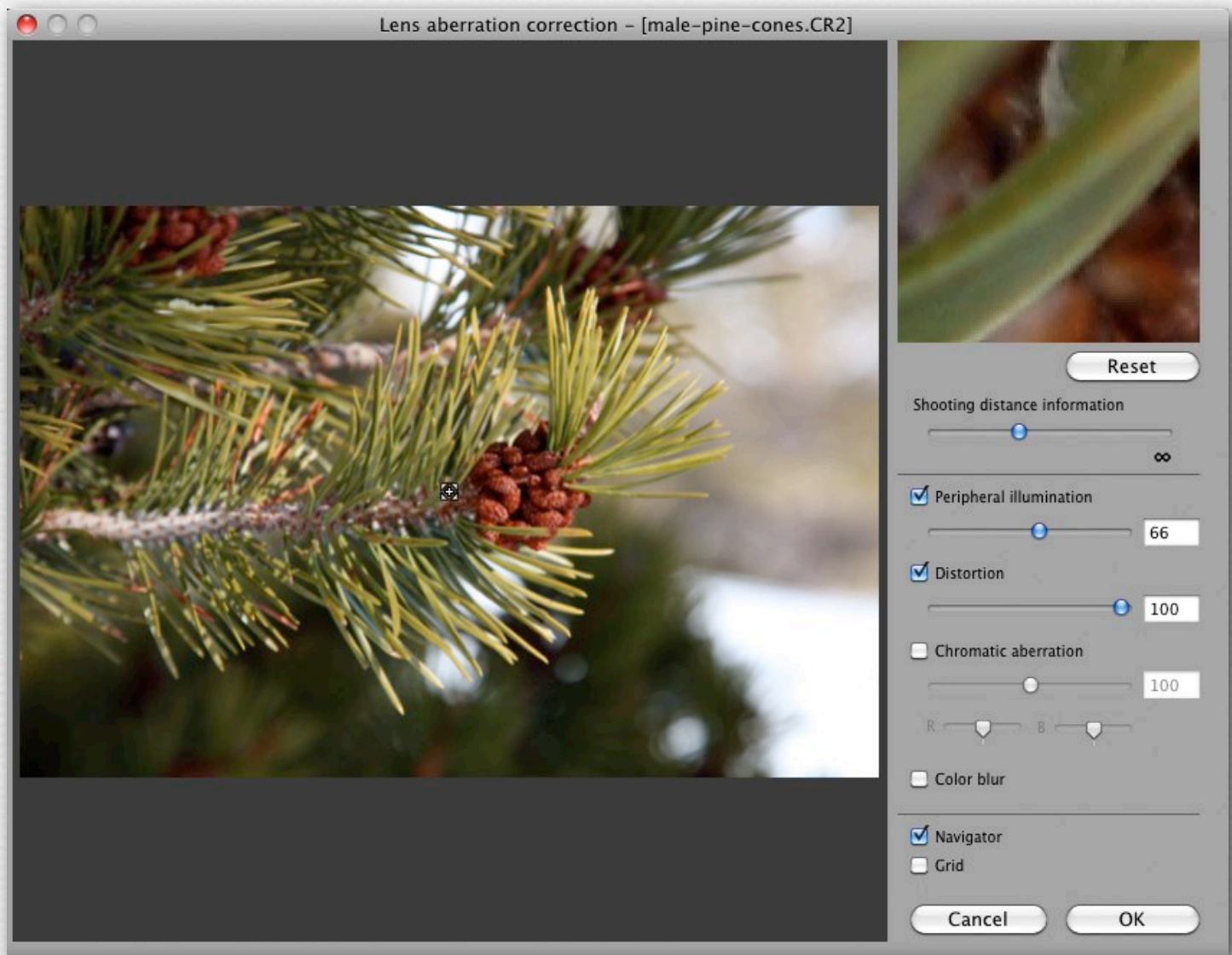
RAW file processor

Lens aberration correction panel in
Canon Digital
Photo Professional



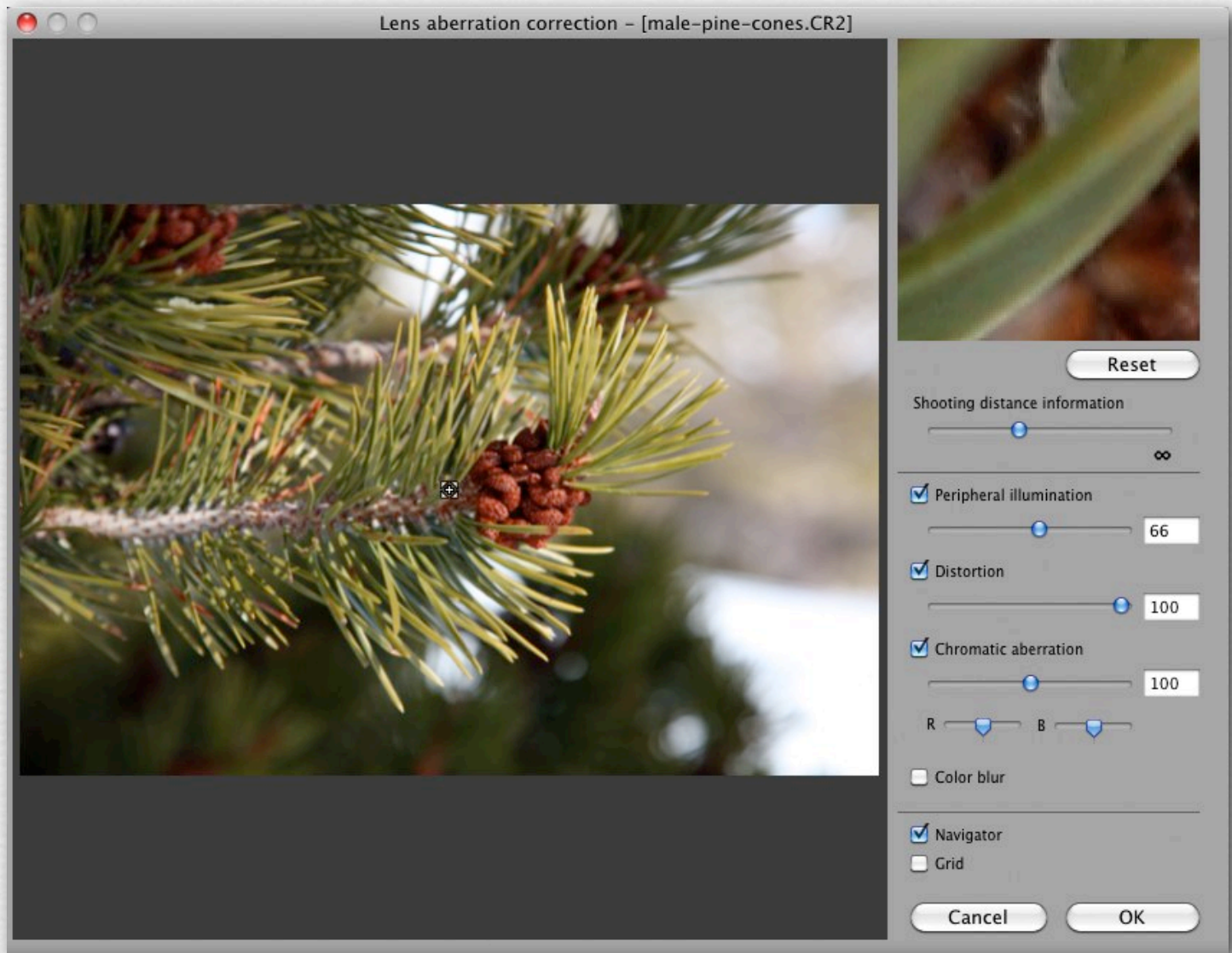
RAW file processor

Lens aberration correction panel in
Canon Digital
Photo Professional



RAW file processor

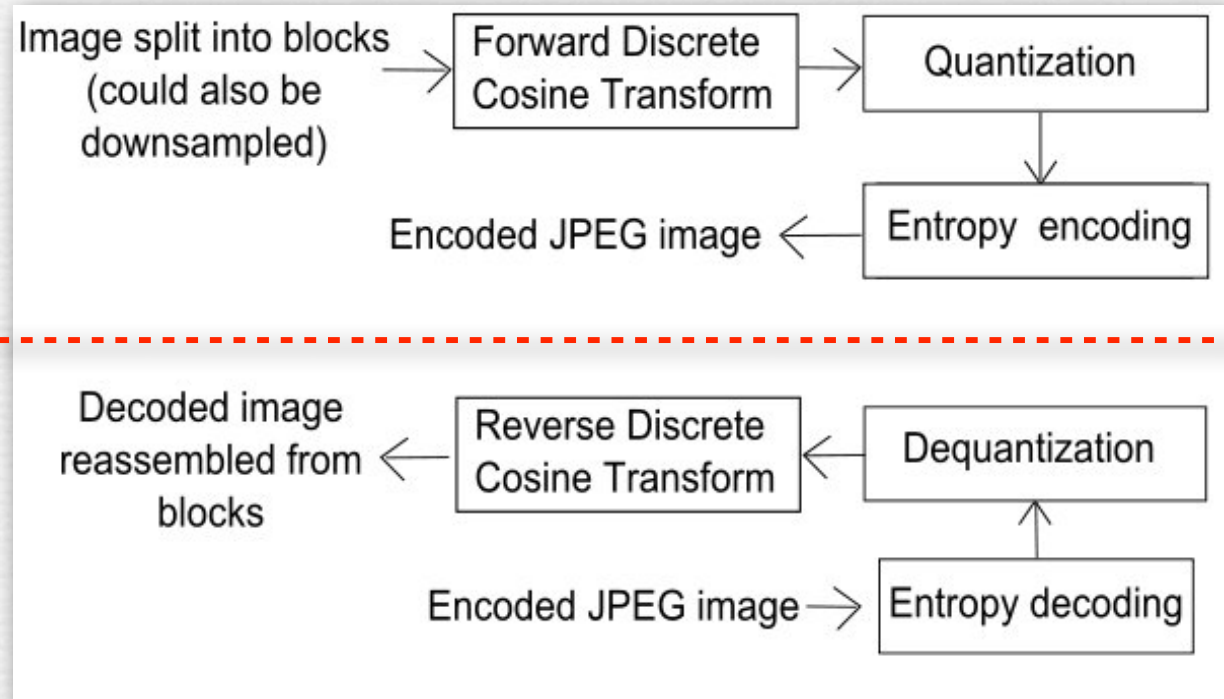
Lens aberration correction panel in
Canon Digital
Photo Professional



JPEG image compression

- compression (in camera)

- input is Y'CbCr
- Cb and Cr typically downsampled by 2x in X and Y
- each component is compressed separately



(wikipedia)

- decompression (for display)

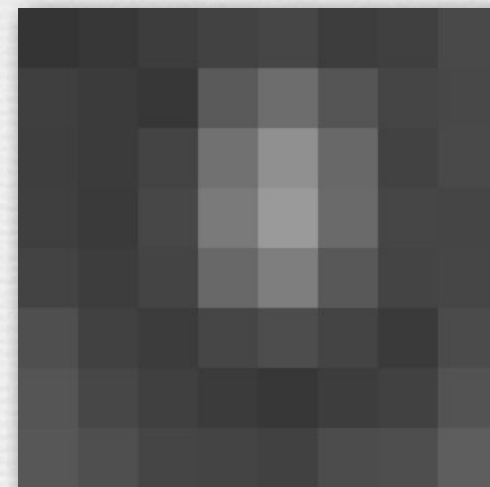
JPEG image compression

								x									
								→									
-76	-73	-67	-62	-58	-67	-64	-55										
-65	-69	-73	-38	-19	-43	-59	-56										
-66	-69	-60	-15	16	-24	-62	-55										
-65	-70	-57	-6	26	-22	-58	-59										
-61	-67	-60	-24	-2	-40	-60	-58										
-49	-63	-68	-58	-51	-60	-70	-53										
-43	-57	-64	-69	-73	-67	-63	-45										
-41	-49	-59	-60	-63	-52	-50	-34										

zero-centered image

52	55	61	66	70	61	64	73
63	59	55	90	109	85	69	72
62	59	68	113	144	104	66	73
63	58	71	122	154	106	70	69
67	61	68	104	126	88	68	70
79	65	60	70	77	68	58	75
85	71	64	59	55	61	65	83
87	79	69	68	65	76	78	94

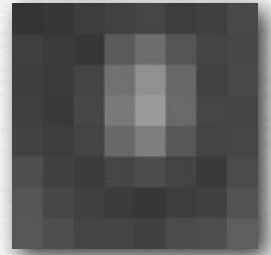
8-bit image



8x8 pixel block

- ◆ step #1: split into 8x8 pixel blocks
- ◆ step #2: quantize to 8 bits / pixel
- ◆ step #3: convert to zero-centered

JPEG image compression



x →							
-76	-73	-67	-62	-58	-67	-64	-55
-65	-69	-73	-38	-19	-43	-59	-56
-66	-69	-60	-15	16	-24	-62	-55
-65	-70	-57	-6	26	-22	-58	-59
-61	-67	-60	-24	-2	-40	-60	-58
-49	-63	-68	-58	-51	-60	-70	-53
-43	-57	-64	-69	-73	-67	-63	-45
-41	-49	-59	-60	-63	-52	-50	-34

zero-centered image

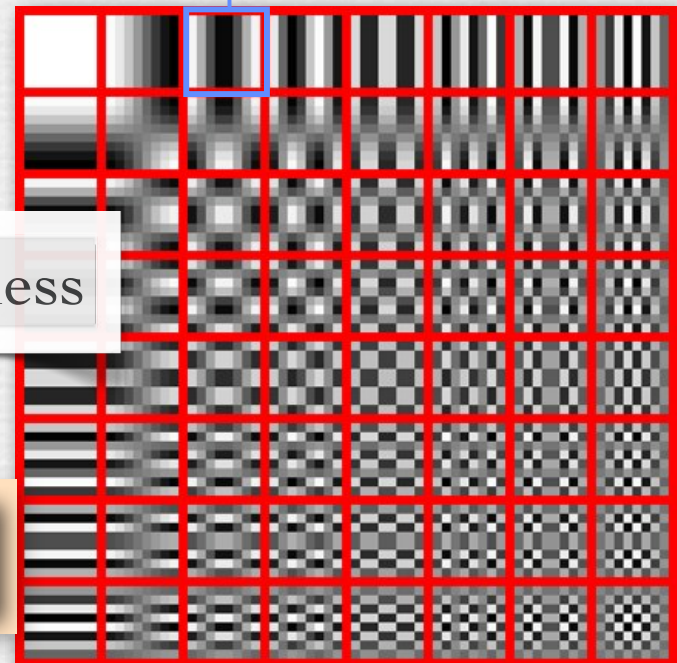
u →							
-415	-30	-61	27	56	-20	-2	0
4	-22	-61	10	13	-7	-9	5
-47	7	77	-25	-29	10	5	-6
-49	12	34	-15	-10	6	2	2
12	-7	-13	-4	-2	2	-3	3
-8	3	2	-6	-2	1	4	2
-1	0	0	-2	-1	-3	4	-1
0	0	-1	-4	-1	0	1	2

discrete cosine transform (DCT)

- any 8×8 pixel zero-centered image can be represented by a weighted sum of the 64 8×8 pixel *basis functions* shown at right

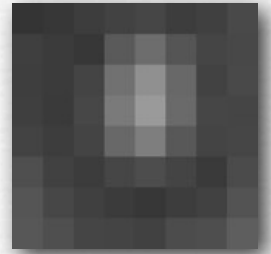
- step #4: compute the weighting for each basis function using:

$$G_{u,v} = \alpha(u)\alpha(v) \sum_{x=0}^7 \sum_{y=0}^7 g_{x,y} \cos \left[\frac{\pi}{8} \left(x + \frac{1}{2} \right) u \right] \cos \left[\frac{\pi}{8} \left(y + \frac{1}{2} \right) v \right]$$



lossless

JPEG image compression



16	11	10	16	24	40	51	61
12	12	14	19	26	58	60	55
14	13	16	24	40	57	69	56
14	17	22	29	51	87	80	62
18	22	37	56	68	109	103	77
24	35	55	64	81	104	113	92
49	64	78	87	103	121	120	101
72	92	95	98	112	100	103	99

bin size for each coefficient

			u					
			\rightarrow					
-415	-30	-61	27	56	-20	-2	0	
4	-22	-61	10	13	-7	-9	5	
-47	7	77	-25	-29	10	5	-6	
-49	12	34	-15	-10	6	2	2	
12	-7	-13	-4	-2	2	-3	3	v
-8	3	2	-6	-2	1	4	2	
-1	0	0	-2	-1	-3	4	-1	
0	0	-1	-4	-1	0	1	2	

discrete cosine transform (DCT)

- the human visual system is more sensitive to low & mid frequencies than very high frequencies, so quantize the latter coarsely

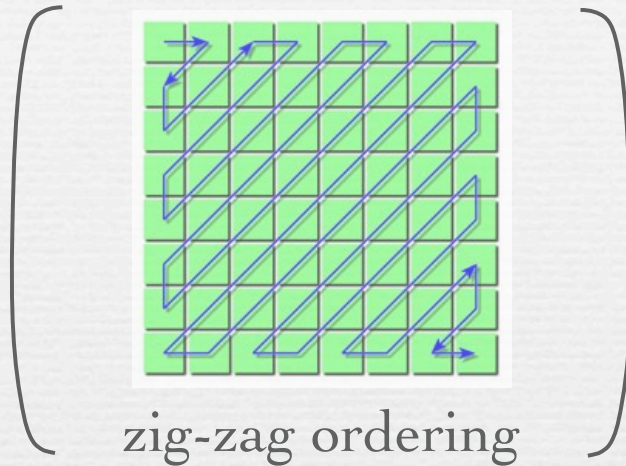
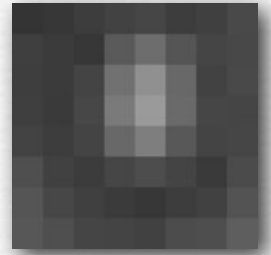
lossy

- step #5: quantize the DCT coefficients using bins whose size increases with frequency

-26	-3	-6	2	2	-1	0	0
0	-2	-4	1	1	0	0	0
-3	1	5	-1	-1	0	0	0
-4	1	2	-1	0	0	0	0
1	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

quantized DCT coefficients

JPEG image compression



-26							
-3	0						
-3	-2	-6					
2	-4	1	-4				
1	1	5	1	2			
-1	1	-1	2	0	0		
0	0	0	-1	-1	EOB		

- ◆ step #6: arrange the non-zero coefficients in zig-zag order

lossless

- ◆ step #7: use run-length encoding to remove repeated elements
- ◆ step #8: apply Huffman coding to reduce number of bits needed for each coefficient

-26	-3	-6	2	2	-1	0	0
0	-2	-4	1	1	0	0	0
-3	1	5	-1	-1	0	0	0
-4	1	2	-1	0	0	0	0
1	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

quantized DCT coefficients

JPEG image compression

Q = 100



2.6 : 1

Q = 25



23 : 1

Q = 1



144 : 1



144:1 looks fine if it's
displayed small enough



- ◆ not easily comparable to Photoshop quality numbers, since Adobe uses its own (proprietary) encoder

Recap

- ◆ RAW files is the direct output of the camera sensor
 - not demosaiced, 16 bits per pixel, losslessly compressed
 - contains metadata, usually proprietary
- ◆ JPEG files are a standard format for storing images
 - typically 8 bits per pixel, lossy compression
 - contains metadata in EXIF format
- ◆ JPEG's compression format is designed to discard details
 - images are partitioned into blocks of 8×8 pixels
 - each block is represented by a weighted sum of cosinusoids (DCT)
 - the coefficients of high frequency cosinusoids are heavily quantized, which reduces # of bits, hence file size, but also loses images quality
 - these coefficients are losslessly compressed using Huffman coding

Questions?

Slide credits

◆ Fredo Durand

- ◆ Wandell, B., *Foundations of Vision*, Sinauer, 1995.
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- ◆ Rudman, T., *Photographer's Master Printing Course*, Focal Press, 1998.
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- ◆ Goldstein, B.E., *Sensation and Perception*, Wadsworth, 1999.
- ◆ Wolfe, J.M., *Sensation and Perception*, Sinauer, 2006.