

Sampling and Reconstruction

The sampling and reconstruction process

- Real world: continuous
- Digital world: discrete

Basic signal processing

- Fourier transforms and the convolution theorem
- The sampling theorem

Aliasing and antialiasing

- Uniform supersampling
- Nonuniform supersampling

Imagers = Signal Sampling

All imagers convert a continuous image to a discrete sampled image by integrating over the active “area” of a sensor.

$$R = \int_T \int_\Omega \int_A L(x, \omega, t) P(x) S(t) \cos \theta \, dA \, d\omega \, dt$$

Examples:

- Retina: photoreceptors
- CCD array

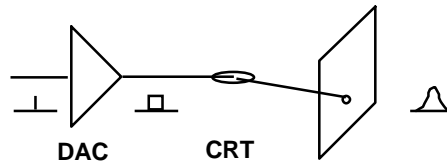
Virtual “computer graphics” cameras do not integrate, instead they simply sample radiance along rays ...

Displays = Signal Reconstruction

All physical displays recreate a continuous image from a discrete sampled image by using a finite sized source of light for each pixel.

Examples:

- DACs: sample and hold
- Cathode ray tube: phosphor spot and grid



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Sampling in Computer Graphics

Artifacts due to sampling - Aliasing

- Jaggies
- Moire
- Flickering small objects
- Sparkling highlights
- Temporal strobing

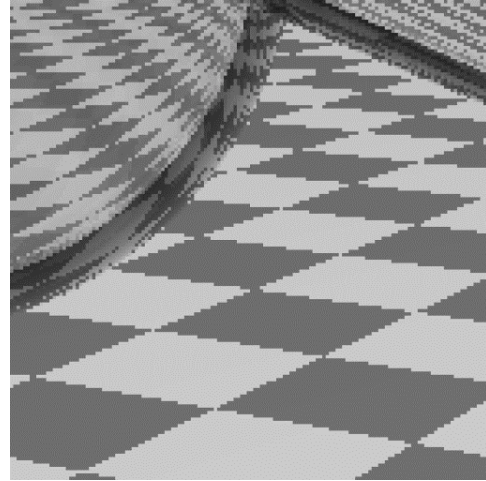
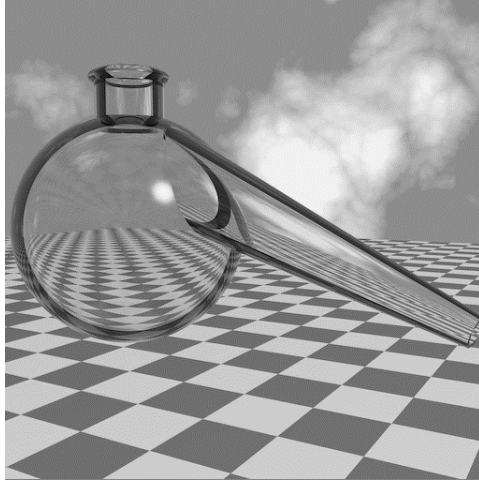
Preventing these artifacts - Antialiasing

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Jaggies

Retort sequence by Don Mitchell



Staircase pattern or jaggies

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Spectral Analysis / Fourier Transforms

Spectral representation treats the function as a weighted sum of sines and cosines

Each function has two representations

- Spatial (time) domain - normal representation
- Frequency domain - spectral representation

The *Fourier transform* converts between the spatial and frequency domain

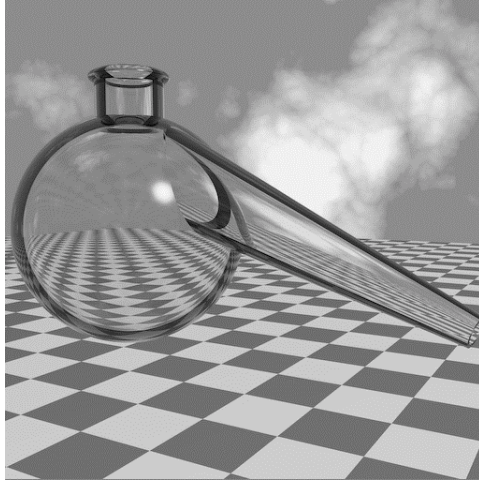
$$\begin{array}{ccc} \boxed{\text{Spatial Domain}} & \begin{array}{c} \Rightarrow \\ \\ \Leftarrow \end{array} & \begin{array}{c} F(\omega) = \int_{-\infty}^{\infty} f(x)e^{-i\omega x} dx \\ \\ f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega)e^{i\omega x} d\omega \end{array} & \begin{array}{c} \Rightarrow \\ \\ \Leftarrow \end{array} & \boxed{\text{Frequency Domain}} \end{array}$$

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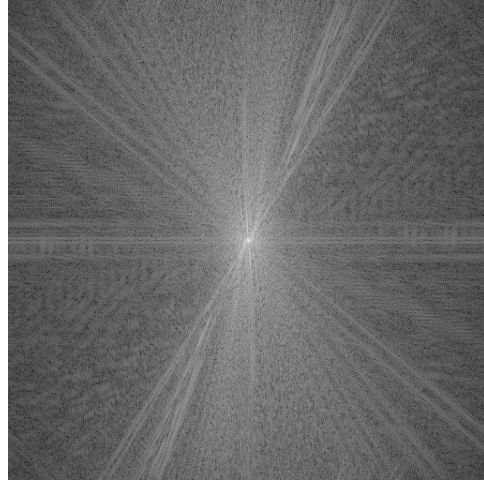
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Spatial and Frequency Domain

Spatial Domain



Frequency Domain



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Convolution

Definition

$$h(x) = f \otimes g = \int f(x')g(x-x') dx'$$

Convolution Theorem: Multiplication in the frequency domain is equivalent to convolution in the space domain.

$$f \otimes g \leftrightarrow F \times G$$

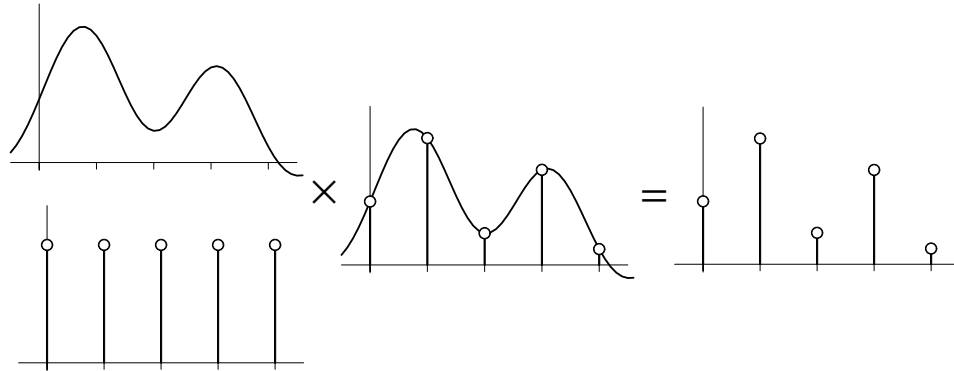
Symmetric Theorem: Multiplication in the space domain is equivalent to convolution in the frequency domain.

$$f \times g \leftrightarrow F \otimes G$$

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Sampling: Spatial Domain

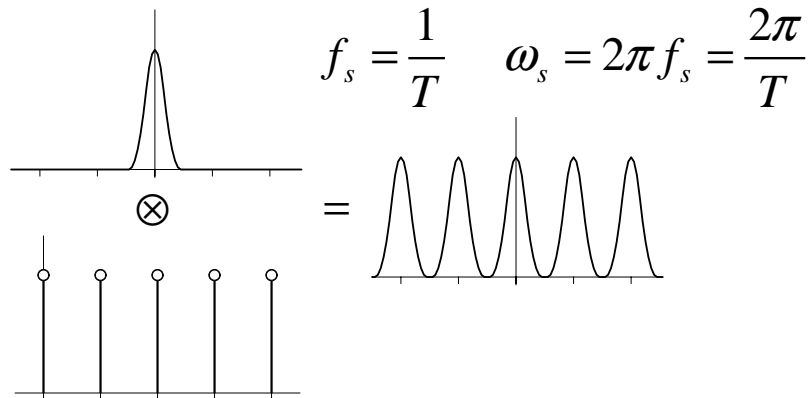


$$\text{III}(x) = \sum_{n=-\infty}^{n=\infty} \delta(x - nT)$$

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Sampling: Frequency Domain



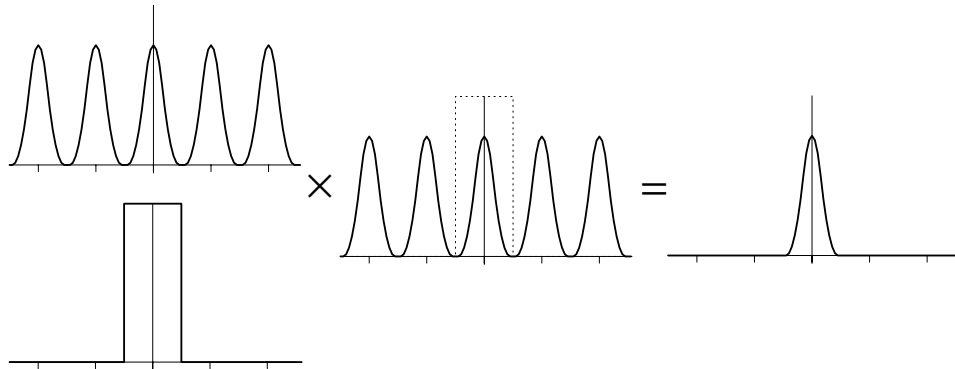
$$f_s = \frac{1}{T} \quad \omega_s = 2\pi f_s = \frac{2\pi}{T}$$

$$\text{III}(\omega) = \sum_{n=-\infty}^{n=\infty} \delta(\omega - n\omega_s)$$

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Reconstruction: Frequency Domain

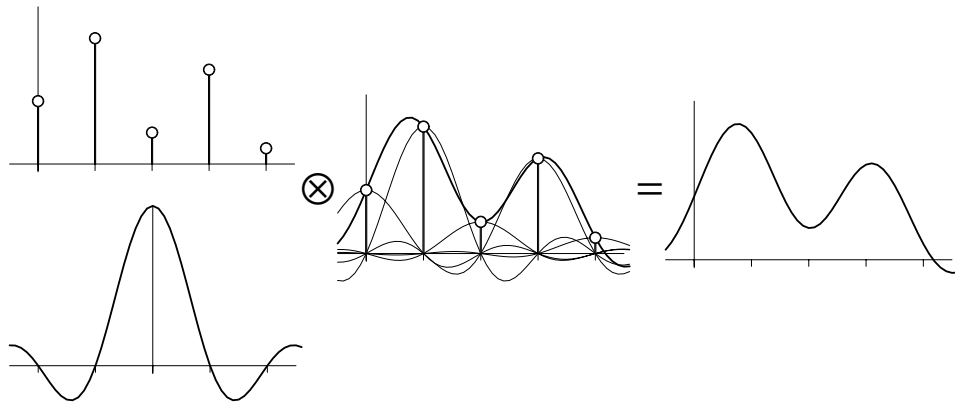


$$\Pi(x) = \begin{cases} 1 & |x| \leq \frac{1}{2} \\ 0 & |x| > \frac{1}{2} \end{cases}$$

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Reconstruction: Spatial Domain

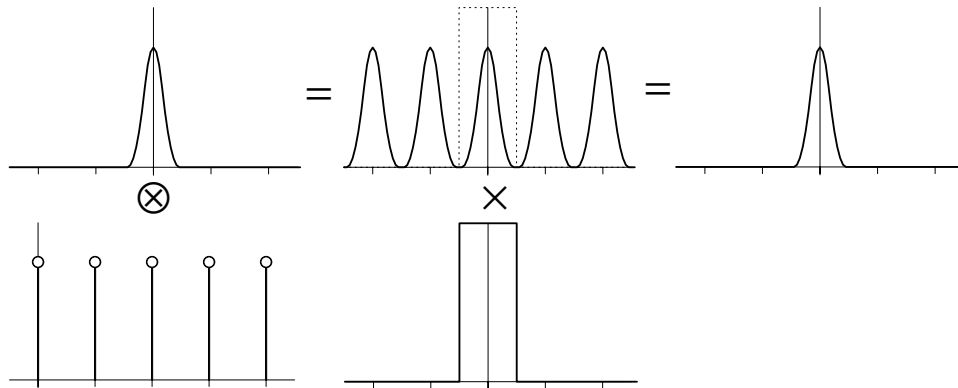


$$\text{sinc } x = \frac{\sin \pi x}{\pi x}$$

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Sampling and Reconstruction



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Sampling Theorem

This result is known as the **Sampling Theorem** and is due to **Claude Shannon** who first discovered it in **1949**

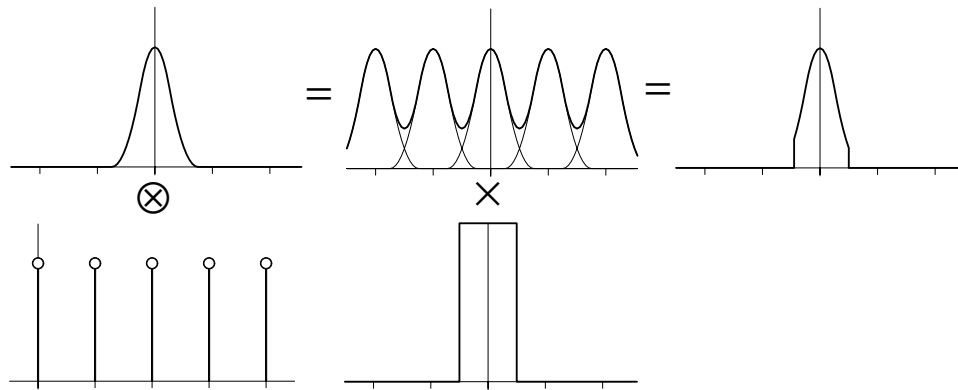
A signal can be reconstructed from its samples without loss of information, if the original signal has no frequencies above $1/2$ the sampling frequency

For a given bandlimited function, the rate at which it must be sampled is called the Nyquist Frequency

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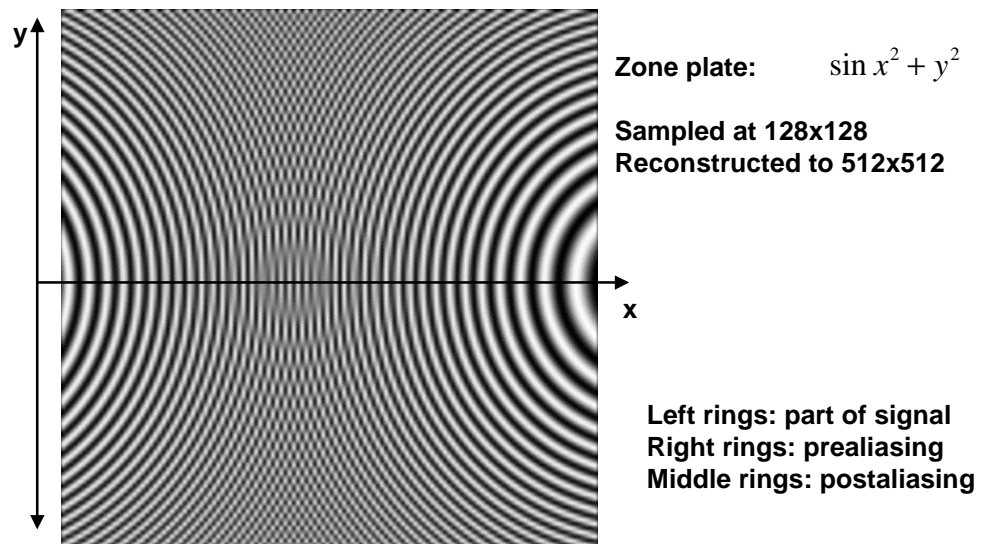
Undersampling: Aliasing



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Sampling a "Zone Plate"



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Ideal Reconstruction

Ideally, use a perfect low-pass filter - the sinc function - to bandlimit the sampled signal and thus remove all copies of the spectra introduced by sampling

Unfortunately,

- The sinc has infinite extent and we must use simpler filters with finite extents. Physical processes in particular do not reconstruct with sincs
- The sinc may introduce ringing which are perceptually objectionable

Mitchell Cubic Filter

$$h(x) = \frac{1}{6} \begin{cases} (12 - 9B - 6C)x^3 + (-18 + 12B + 6C)x^2 + (6 - 2B) & |x| < 1 \\ (-B - 6C)x^3 + (6B + 30C)x^2 + (-12B - 48C)x + (8B + 24C) & 1 < |x| < 2 \\ 0 & \text{otherwise} \end{cases}$$

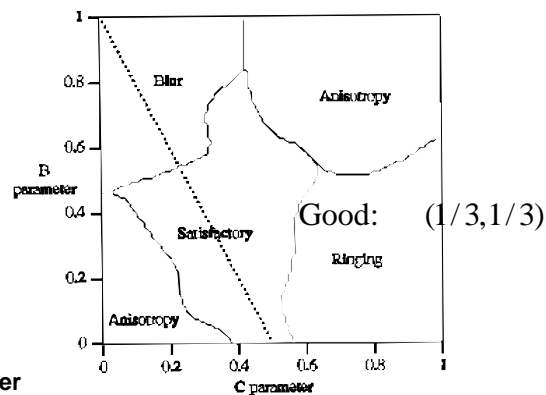
Properties:

$$\sum_{n=-\infty}^{\infty} h(x) = 1$$

B-spline: (1, 0)

Catmull-Rom: (0, 1/2)

From Mitchell and Netravali
Look at other figures in that paper



Antialiasing

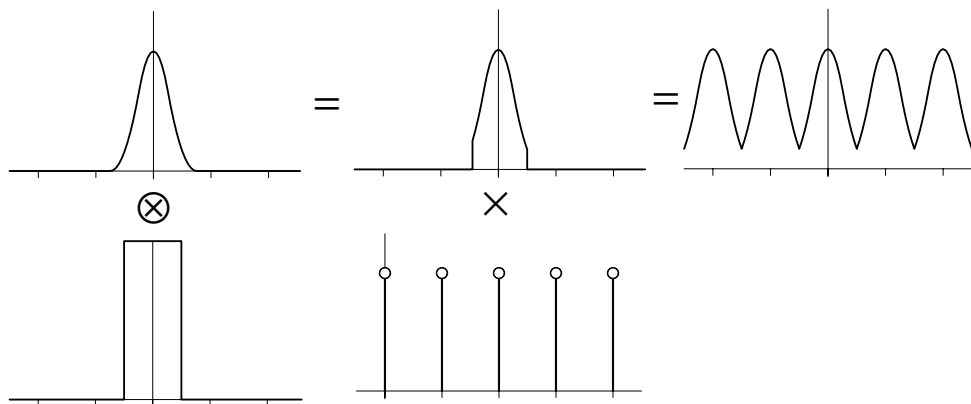
Preventing aliasing or antialiasing:

1. Analytically prefilter the signal
Usually impractical
2. Uniform supersampling and resample
3. Nonuniform or stochastic sampling

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Antialiasing by Prefiltering



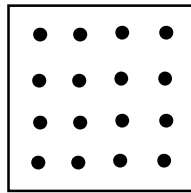
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Uniform Supersampling

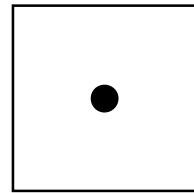
Increasing the sampling rate moves each copy of the spectra further apart, potentially reducing the overlap and thus aliasing

Resulting samples must be resampled (filtered) to image sampling rate



Samples

$$Pixel = \sum_s w_s \cdot Sample_s$$

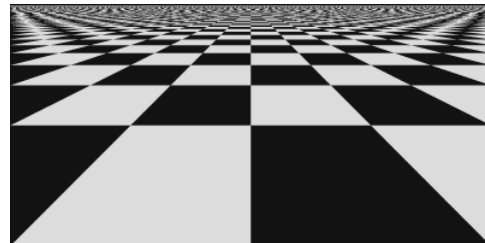
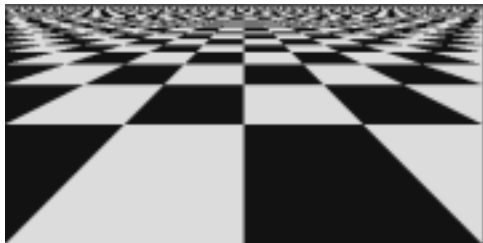
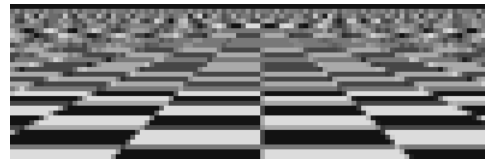


Pixel

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Point vs. Supersampled



Point

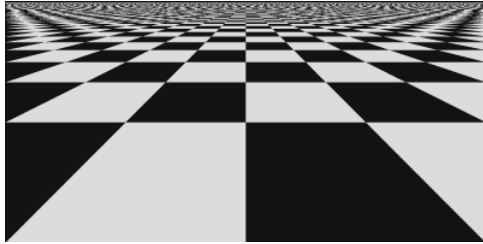
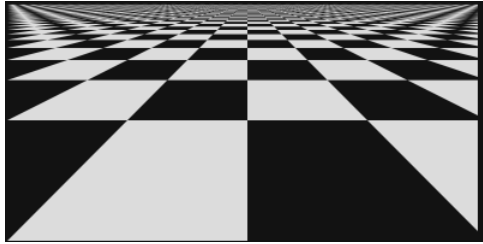
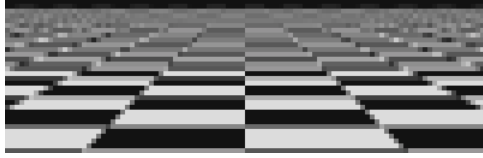
4x4 Supersampled

Checkerboard sequence by Tom Duff

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Analytic vs. Supersampled



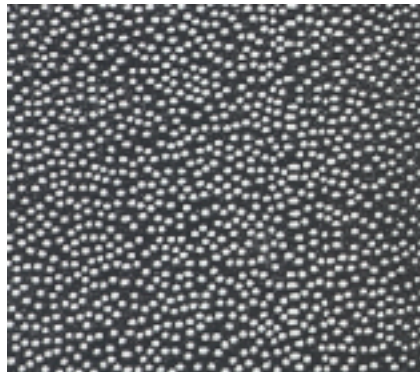
Exact Area

4x4 Supersampled

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Distribution of Extrafoveal Cones



Monkey eye cone distribution



Fourier transform

Yellot theory

- Aliases replaced by noise
- Visual system less sensitive to high frequency noise

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Non-uniform Sampling

Intuition

Uniform sampling

- The spectrum of uniformly spaced samples is also a set of uniformly spaced spikes
- Multiplying the signal by the sampling pattern corresponds to placing a copy of the spectrum at each spike (in freq. space)
- Aliases are coherent, and very noticeable

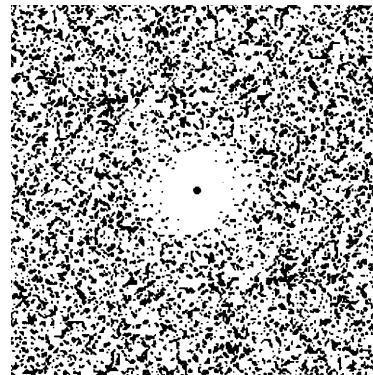
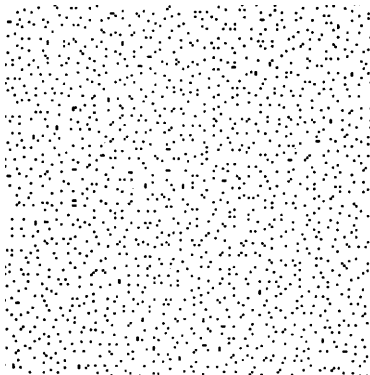
Non-uniform sampling

- Samples at non-uniform locations have a different spectrum; a single spike plus noise
- Sampling a signal in this way converts aliases into broadband noise
- Noise is incoherent, and much less objectionable

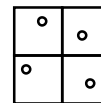
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Jittered Sampling



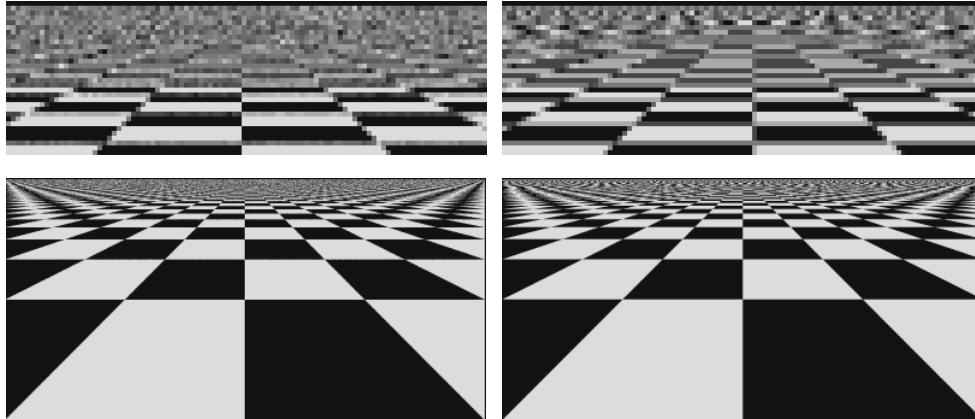
Add uniform random jitter to each sample



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Jittered vs. Uniform Supersampling



4x4 Jittered Sampling

4x4 Uniform

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Analysis of Jitter

Non-uniform sampling

$$s(x) = \sum_{n=-\infty}^{n=\infty} \delta(x - x_n)$$

$$x_n = nT + j_n$$

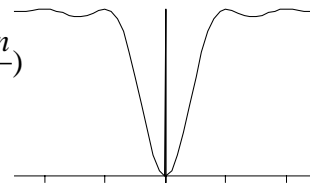
Jittered sampling

$$j_n \sim j(x)$$

$$j(x) = \begin{cases} 1 & |x| \leq 1/2 \\ 0 & |x| > 1/2 \end{cases}$$

$$J(\omega) = \text{sinc } \omega$$

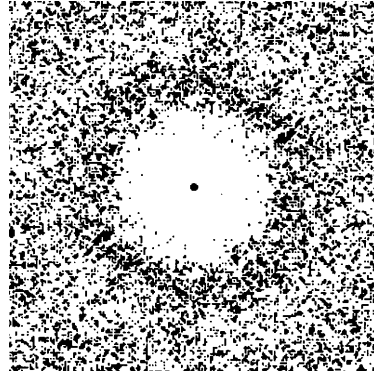
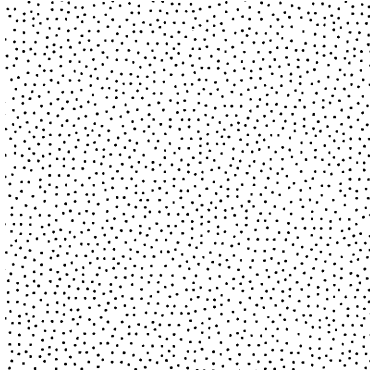
$$\begin{aligned} S(\omega) &= \frac{1}{T} \left[1 - |J(\omega)|^2 \right] + \frac{2\pi}{T^2} |J(\omega)|^2 \sum_{n=-\infty}^{n=\infty} \delta\left(\omega - \frac{2\pi n}{T}\right) \\ &= \frac{1}{T} \left[1 - \text{sinc}^2 \omega \right] + \delta(\omega) \end{aligned}$$



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Poisson Disk Sampling

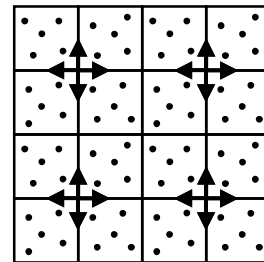
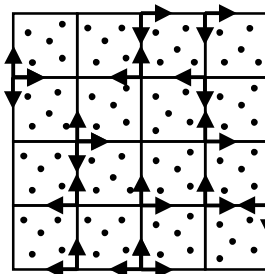
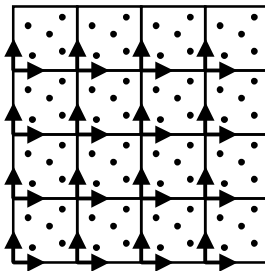


Dart throwing algorithm

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Tiling



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