

Radiosity

Classic radiosity = finite element method

Assumptions

- **Diffuse reflectance**
- **Usually polygonal surfaces**

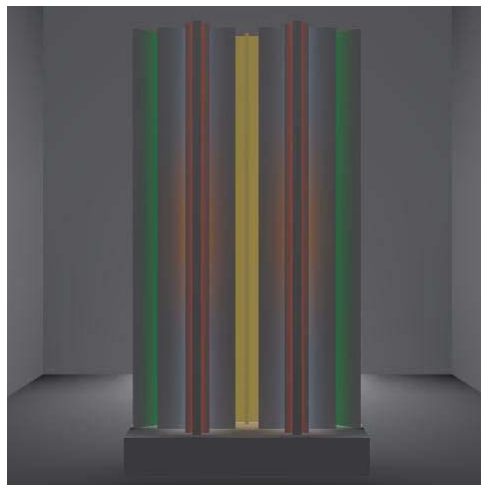
Advantages

- **Soft shadows and indirect lighting**
- **View independent solution**
- **Precompute for a set of light sources**
- **Useful for walkthroughs**

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Early Radiosity



From Goral, Torrance, Greenberg, Battaile 1984

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Early Radiosity

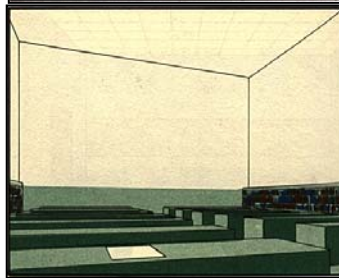
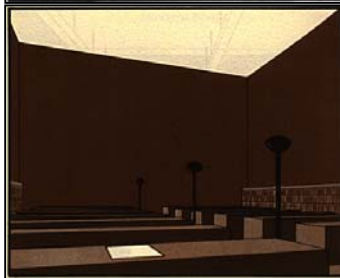
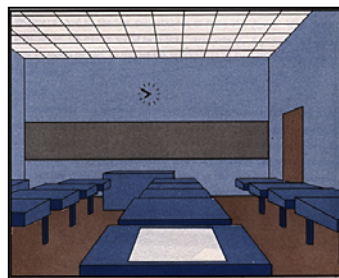
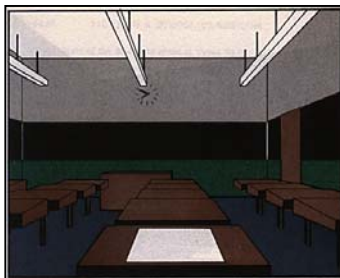


From Cohen, Chen, Wallace and Greenberg 1988

CS348B Lecture 17

Pat Hanrahan, Spring 2002

First Radiosity Pictures ...



Parry Moon and Domina Spencer (MIT), Lighting Design, 1948

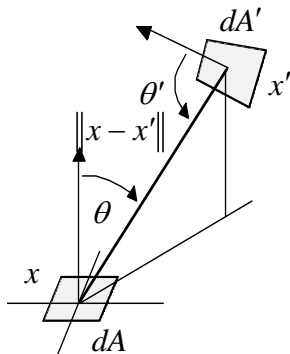
CS348B Lecture 17

Pat Hanrahan, Spring 2002

Finite Element Method

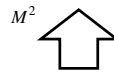
The Radiosity Equation

Assume diffuse reflection only
Solve for radiosity (2D function)



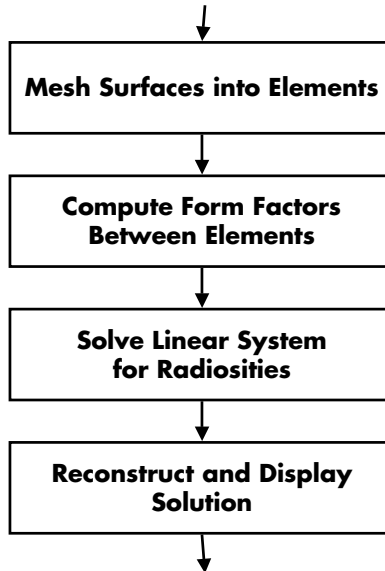
$$B(x) = B_e(x) + \rho(x)E(x)$$

$$B(x) = B_e(x) + \rho(x) \int F(x, x') B(x') dA'$$



$$F(x, x') = \frac{\cos \theta \cos \theta'}{\pi \|x - x'\|^2} V(x, x')$$

Classic Radiosity Algorithm



CS348B Lecture 17

Pat Hanrahan, Spring 2002

Simple Room Scene

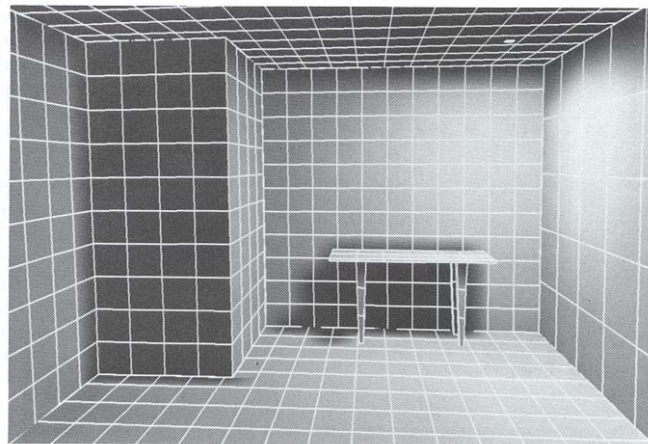


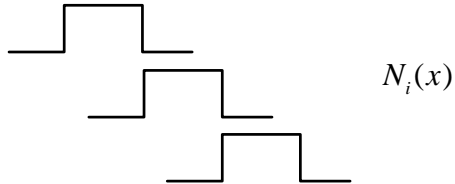
Table in room sequence from Cohen and Wallace

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Basic Functions

Piecewise constant basis functions



Express radiosity as sum of basis functions

$$B(x) = \sum_i B_i N_i(x) \quad \text{Constant radiosity assumption}$$

$$B_e(x) = \sum_i E_i N_i(x)$$

$$\rho(x) = \sum_i \rho_i N_i(x)$$

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Derivation

Convert integral equation to matrix equation

$$B(x) = B_e(x) + \rho(x) \int_{M^2} F(x, x') \sum B_j N_j(x') dA'$$

$$\sum_i B_i N_i(x) = \sum_i B_i N_i(x) + \sum_i \rho_i N_i(x) \left[\sum_j B_j \int_{A_j} F(x, x') N_j(x') dA' \right]$$

$$\int \left(\sum_i B_i N_i(x) = \sum_i B_i N_i(x) + \sum_i \rho_i N_i(x) \left[\sum_j B_j \int_{A_j} F(x, x') N_j(x') dA' \right] \right) dA$$

$$B_i A_i = E_i A_i + \rho_i \sum_j B_j \int_{A_i} \int_{A_j} F(x, x') N_i(x) N_j(x') dA dA'$$

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Form Factor

Form Factor

$$A_i F_{ij} = A_j F_{ji} = \int_{A_i} \int_{A_j} \frac{\cos \theta'_o \cos \theta_i}{\pi \|x - x'\|^2} V(x, x') dA dA'$$

Summation

$$\sum_j F_{ij} = 1$$

Form factor is the percentage of light leaving i that makes it to j

Classic Radiosity

Power balance

$$B_i A_i = E_i A_i + \rho_i \sum_j B_j A_j F_{ij}$$

$$B_i = E_i + \rho_i \sum_j F_{ij} B_j$$

Linear system of equations

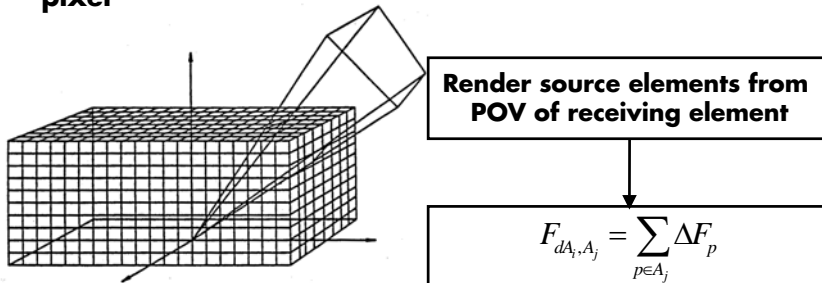
$$\begin{pmatrix} 1 - \rho_1 F_{11} & -\rho_1 F_{12} & \cdots & -\rho_1 F_{1n} \\ -\rho_2 F_{21} & 1 - \rho_2 F_{22} & \cdots & -\rho_2 F_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -\rho_n F_{n1} & -\rho_n F_{n2} & \cdots & 1 - \rho_n F_{nn} \end{pmatrix} \begin{pmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{pmatrix} = \begin{pmatrix} E_1 \\ E_2 \\ \vdots \\ E_n \end{pmatrix}$$

Form Factors

Hemicube Algorithm

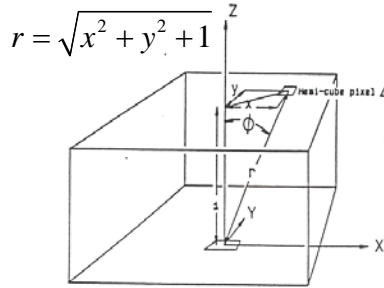
First radiosity algorithm to deal with occlusion

1. Render scene from the point of view of each vertex/element
2. Compute delta form factors - contribution from each pixel



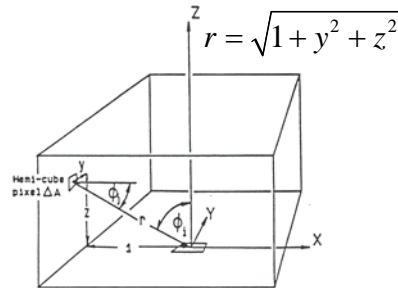
Typical resolution: 32x32

Hemicube Delta Form Factors



$$\cos \phi = \frac{1}{\sqrt{x^2 + y^2 + 1}}$$

$$\Delta F = \frac{\Delta A}{\pi(x^2 + y^2 + 1)^2}$$



$$\cos \phi = \frac{1}{\sqrt{1 + y^2 + z^2}}$$

$$\Delta F = \frac{\Delta A}{\pi(1 + y^2 + z^2)^2}$$

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Hemicube Algorithms

Advantages

- + **First practical method -> Patent!**
- + **Use existing rendering systems; Hardware**
- + **Computes row of form factors in $O(n)$**

Disadvantages

- **Computes differential-finite form factor**
- **Aliasing errors due to sampling**
Randomly rotate/shear hemicube
- **Proximity errors**
- **Visibility errors**
- **Expensive to compute a single form factor**

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Solving

Solve $[F][B] = [E]$

Direct methods: $O(n^3)$

- **Gaussian elimination**

Goral, Torrance, Greenberg, Battaile, 1984

Iterative methods: $O(n^2)$

Energy conservation

→ *diagonally dominant* → *iteration converges*

- **Gauss-Seidel, Jacobi: Gathering**

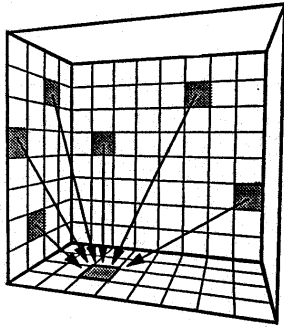
Nishita, Nakamae, 1985

Cohen, Greenberg, 1985

- **Southwell: Shooting**

Cohen, Chen, Wallace, Greenberg, 1988

Gathering



```

for(i=0; i<n; i++)
  B[i] = Be[i];

while( !converged ) {
  for(i=0; i<n; i++) {
    E[i] = 0;
    for(j=0; j<n; j++)
      E[i] += F[i][j]*B[j];
    B[i] = Be[i]+rho[i]*E[i];
  }
}

```

Row of F times B

Calculate one row of F and discard

Successive Approximation



L_e



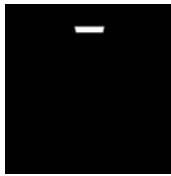
$K \circ L_e$



$K \circ K \circ L_e$



$K \circ K \circ K \circ L_e$



L_e



$L_e + K \circ L_e$

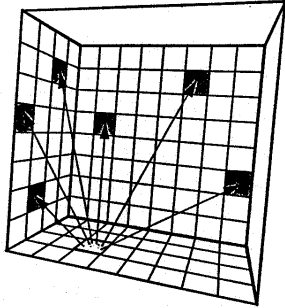


$L_e + \dots K^2 \circ L_e$



$L_e + \dots K^3 \circ L_e$

Shooting



```
for(i=0; i<n; i++) {  
  B[i] = dB[i] = Be[i];  
  while( !converged ) {  
    set i st dB[i] is the largest;  
    for(j=0; j<n; j++)  
      if(i!=j) {  
        db = rho[j]*F[j][i]*dB[i];  
        dB[j] += db;  
        B[j] += db;  
      }  
    dB[i]=0;  
  }  
}
```

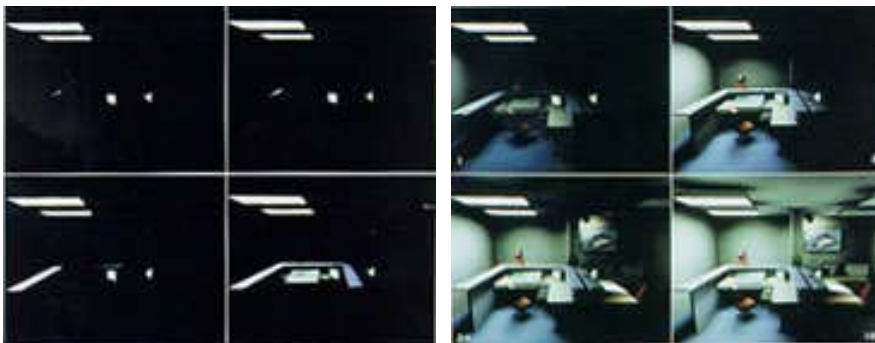
Brightness order

Column of F times B

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Progressive Radiosity



(a)

(b)

(a) Traditional Gauss-Seidel iteration of 1, 2, 24 and 100.

(b) Progressive Refinement (PR) iteration of 1, 2, 24 and 100.

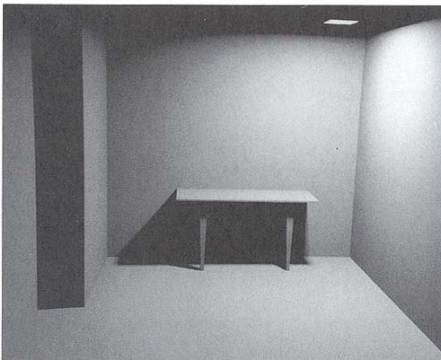
From Cohen, Chen, Wallace, Greenberg 1988

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Meshing

Accuracy



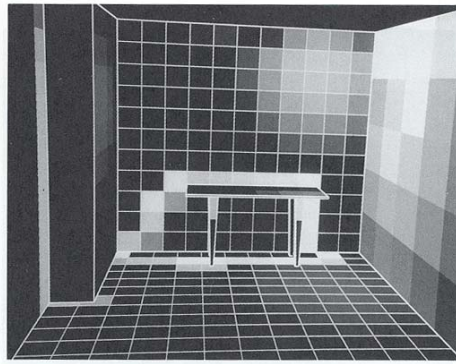
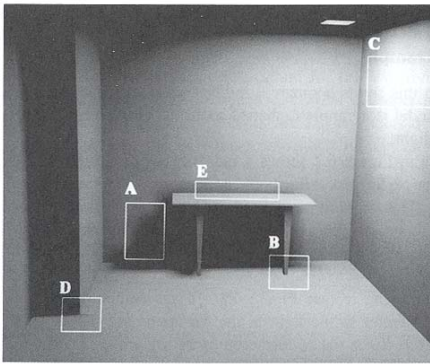
Reference Solution



Uniform Mesh

Table in room sequence from Cohen and Wallace

Artifacts



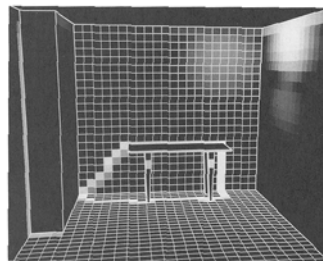
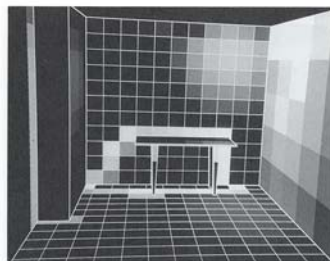
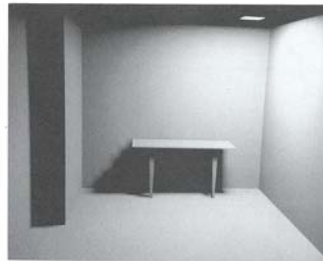
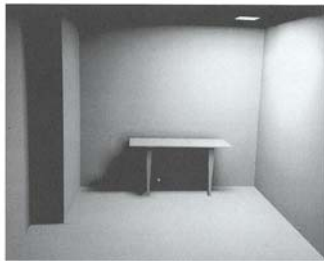
Error Image

- A. Blocky shadows**
- B. Missing features**
- C. Mach bands**
- D. Inappropriate shading discontinuities**
- E. Unresolved discontinuities**

CS348B Lecture 17

Pat Hanrahan, Spring 2002

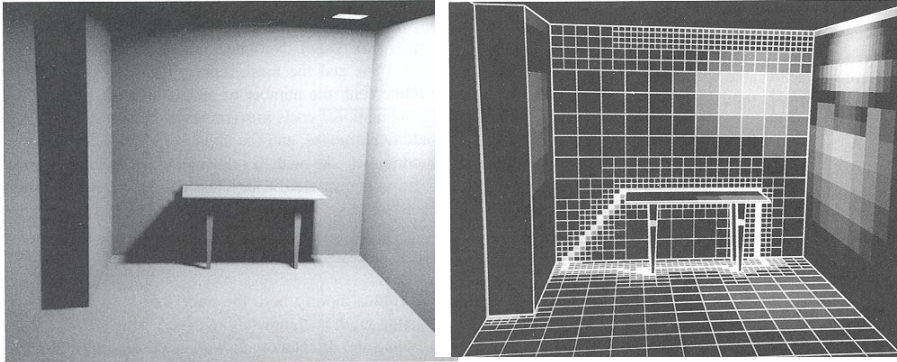
Increasing Resolution



CS348B Lecture 17

Pat Hanrahan, Spring 2002

Adaptive Meshing



CS348B Lecture 17

Pat Hanrahan, Spring 2002

Discontinuity Mesh

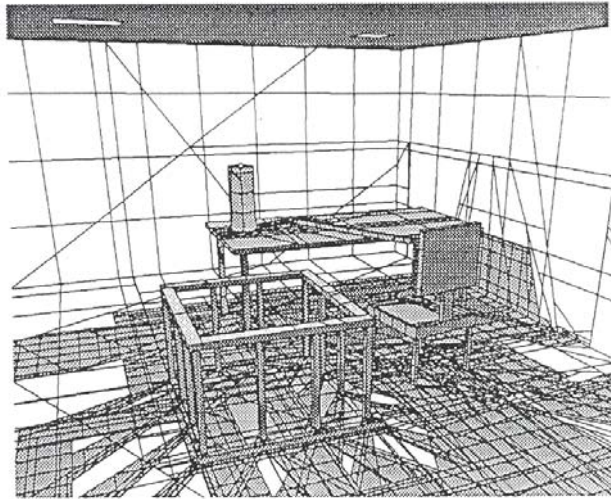


CS348B Lecture 17

From Baum et al.

Pat Hanrahan, Spring 2002

Discontinuity Mesh



From Campbell et al.

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Discontinuity Meshing

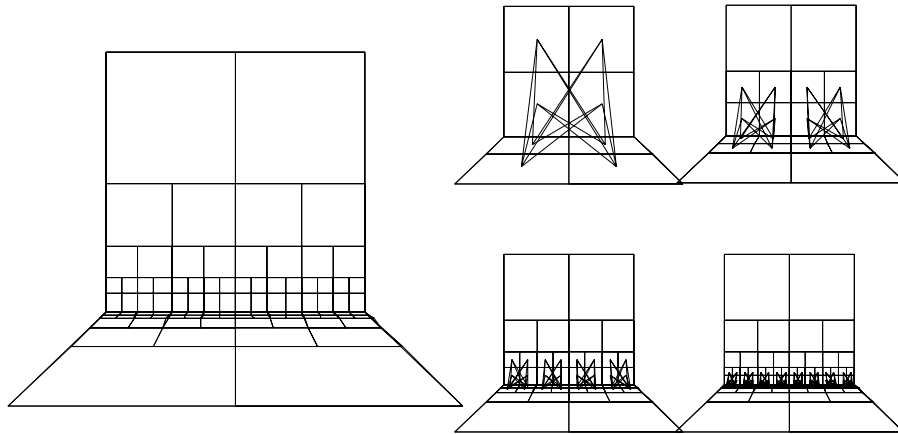


From Lischinski, Tampieri, Greenberg 1992

CS348B Lecture 17

Pat Hanrahan, Spring 2002

Hierarchical Radiosity



CS348B Lecture 17

Pat Hanrahan, Spring 2002

Summary

Remember assumptions

- Diffuse reflectance
- Polygons

Difficult to relax assumptions

Computation challenges

- Meshing
 - Complex input geometry
 - Complexity due to shadows
- Dense coupling
 - $O(n^2)$ matrix elements
 - HR leads to $O(n)$ algorithm (ignoring discontinuities)

CS348B Lecture 17

Pat Hanrahan, Spring 2002