

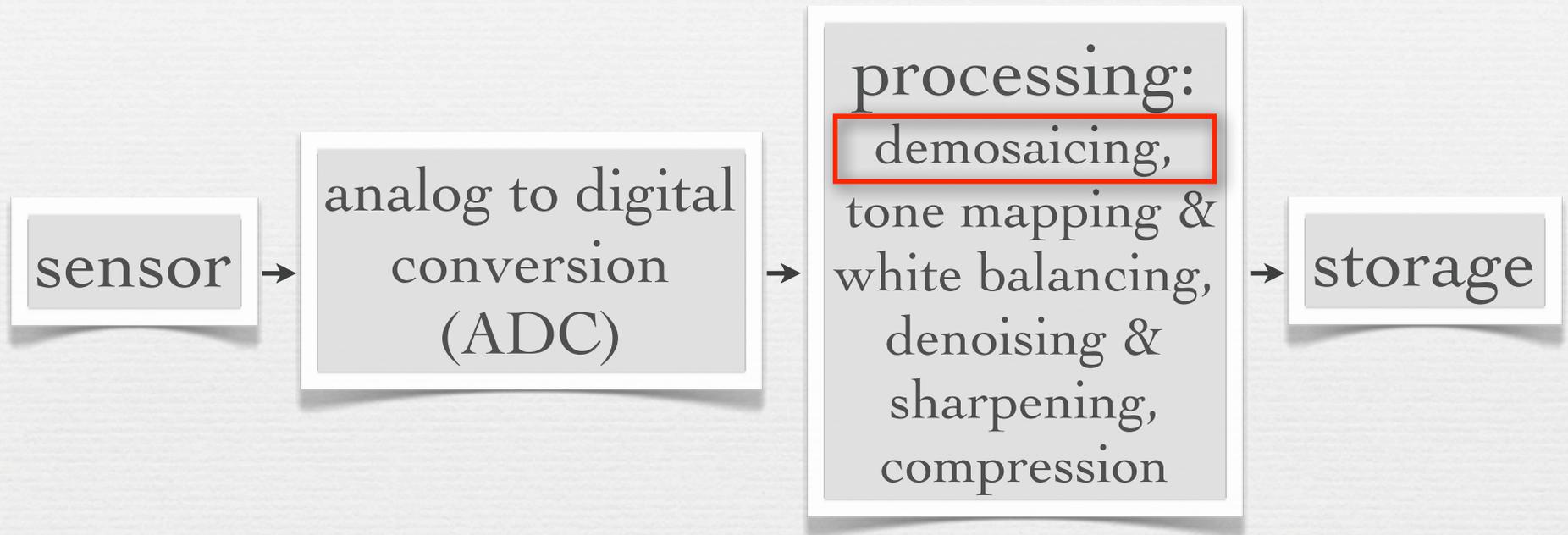
Post-processing pipeline

CS 448A, Winter 2010



Marc Levoy
Computer Science Department
Stanford University

Camera pixel pipeline



- ◆ every camera uses different algorithms
- ◆ the processing order may vary
- ◆ most of it is proprietary

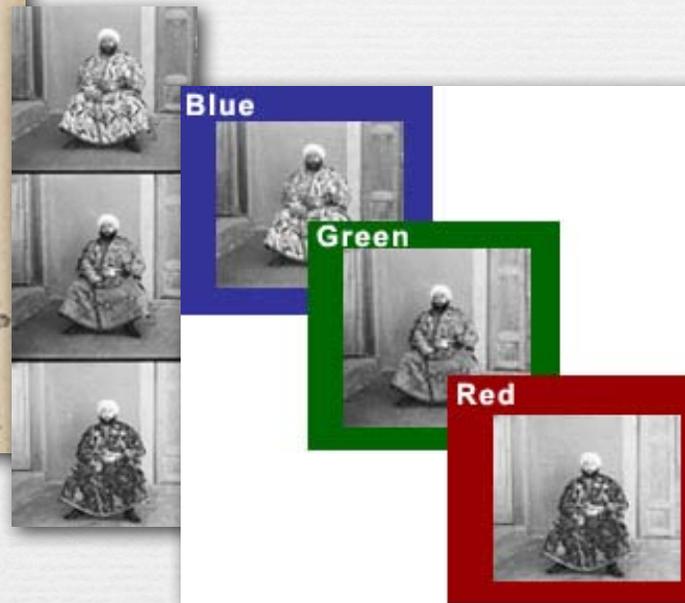
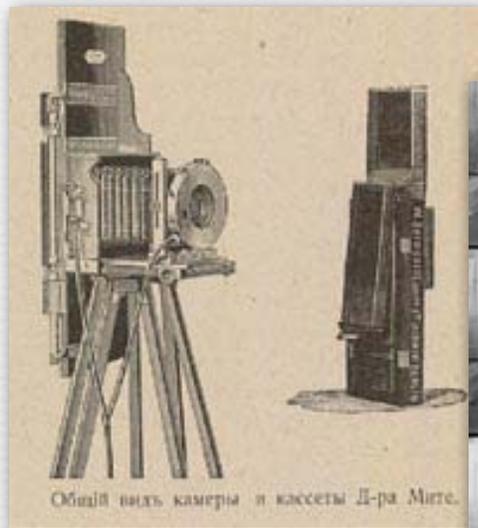
Sensing color

- ◆ silicon detects all visible frequencies well
- ◆ can't differentiate wavelengths after photon knocks an electron loose
 - all electrons look alike
- ◆ must select desired frequencies before light reaches photodetector
 - block using a filter, or separate using a prism or grating
- ◆ 3 spectral responses is enough
 - a few consumer cameras record 4
- ◆ silicon is also sensitive to near infrared (NIR)
 - most sensors have an IR filter to block it
 - to make a NIR camera, remove this filter

Color sensing technologies

- ◆ field-sequential
- ◆ 3-sensor
- ◆ vertically stacked
- ◆ color filter arrays

Sergey Prokudin-Gorsky



- shot sequentially through R, G, B filters
- simultaneous projection provided good saturation, but available printing technology did not
- digital restoration lets us see them in full glory...

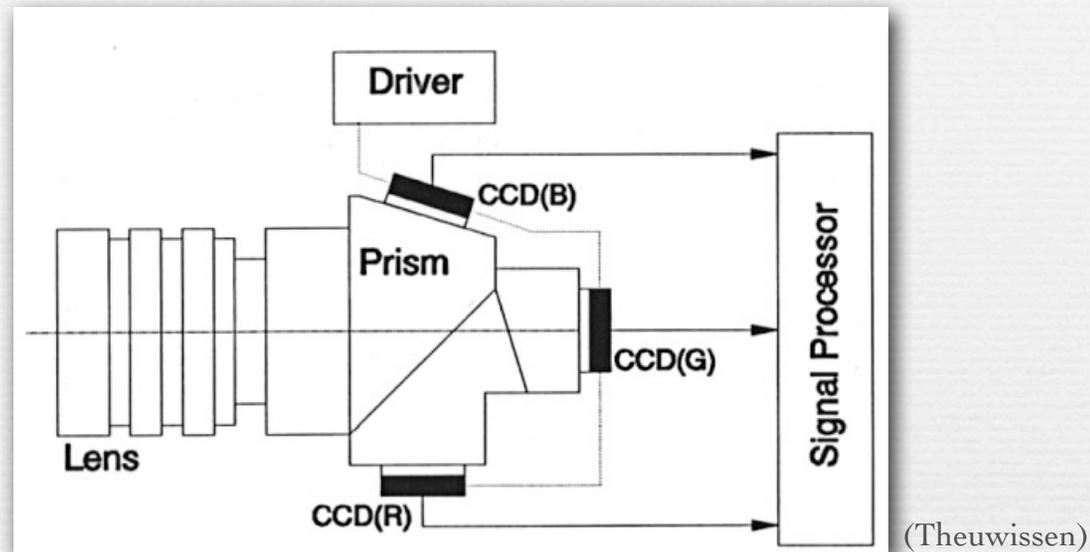


Sergey Prokudin-Gorsky, Alim Khan, emir of Bukhara (1911)



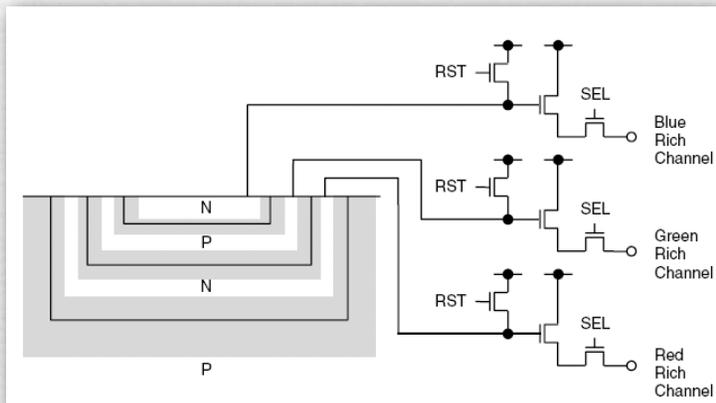
Sergey Prokudin-Gorsky,
Pinkhus Karlinskii, Supervisor of the Chernigov Floodgate (1919)

3-CCD cameras



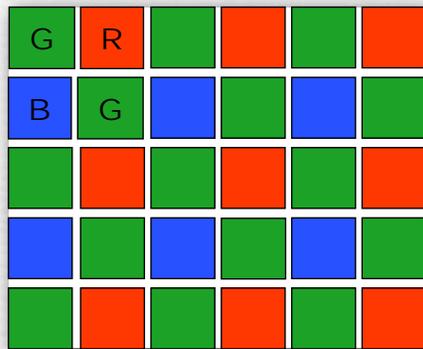
- ◆ high-quality video cameras
- ◆ prism & dichroic mirrors split the image into 3 colors, each routed to a separate CCD sensor
- ◆ no light loss, as compared to filters
- ◆ expensive, and complicates lens design

Foveon stacked sensor

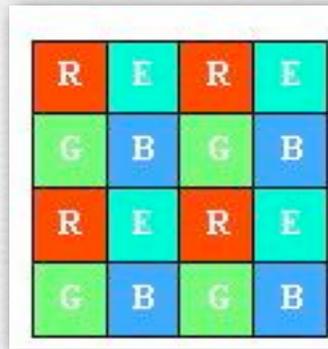


- ◆ longer wavelengths penetrate deeper into silicon, so arrange a set of vertically stacked detectors
 - top gets mostly blue, middle gets green, bottom gets red
 - no control over spectral responses, so requires processing
- ◆ fewer color artifacts than color filter arrays
 - but possibly worse noise performance

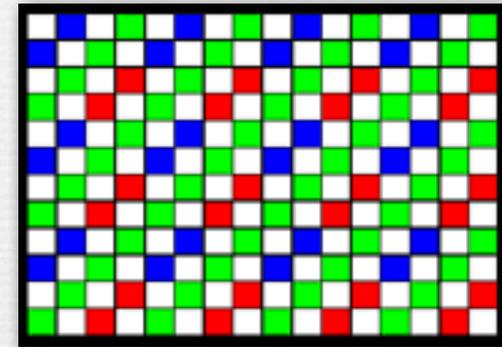
Color filter arrays



Bayer pattern

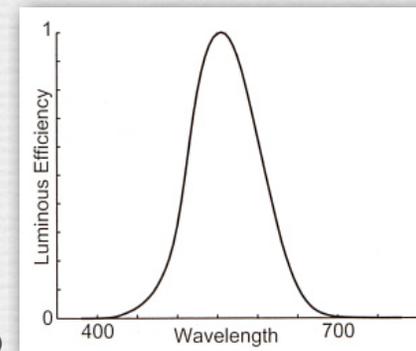


Sony RGB+E
better color



Kodak RGB+C
less noise

- ♦ Why more green pixels than red or blue?
 - because humans are most sensitive in the middle of the visible spectrum
 - sensitivity given by the human luminous efficiency curve



(Stone)

Example of Bayer mosaic image



Small fan at
Stanford women's
soccer game

(Canon 1D III)

Example of Bayer mosaic image

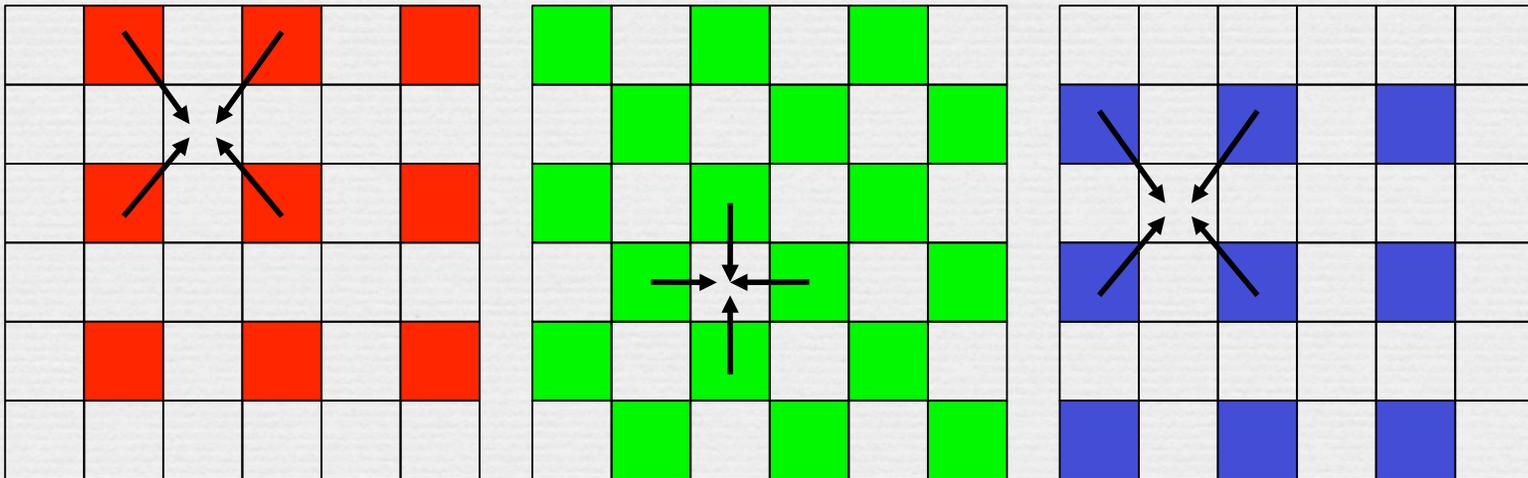


Before demosaicking (dcrw -d)



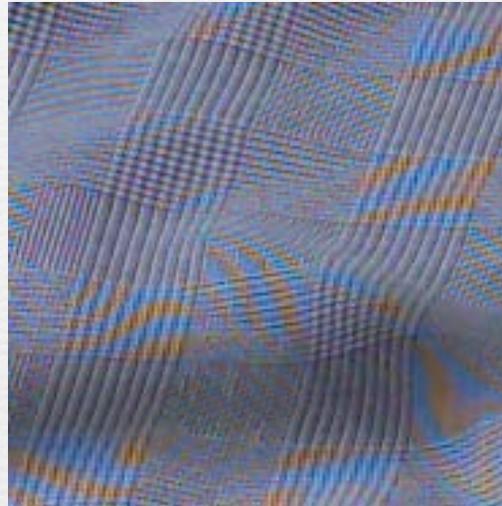
Demosaicing

- ◆ linear interpolation
 - average of the 4 nearest neighbors
- ◆ smoother kernels are possible
 - e.g. bicubic interpolation (what Photoshop uses by default)
 - but need more neighbors (16 instead of 4)



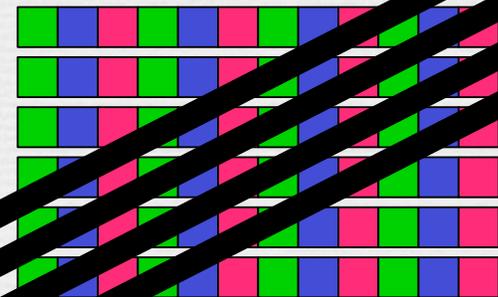
Demosaicing errors

- ◆ color fringes or moiré



- ◆ the cause of color moiré
 - fine black and white detail in scene is mis-interpreted by interpolation algorithm as color information

simplified
1D detector



fine diagonal
B&W stripes

Common solution: low-pass filter chrominance signal

- ◆ color artifacts are places where chrominance changes abruptly but only transiently

Apparent spatial sharpness depends mainly on luminance, not chrominance

original
image



(Wandell)



Y

Cb

Cr

Apparent spatial sharpness depends mainly on luminance, not chrominance

red-green
channel
blurred



(Wandell)



Y

Cb

Cr

Apparent spatial sharpness depends mainly on luminance, not chrominance

original
image



(Wandell)



Y

Cb

Cr

Apparent spatial sharpness depends mainly on luminance, not chrominance

blue-yellow
channel
blurred



(Wandell)



Y

Cb

Cr

Apparent spatial sharpness depends mainly on luminance, not chrominance

original
image



(Wandell)



Y

Cb

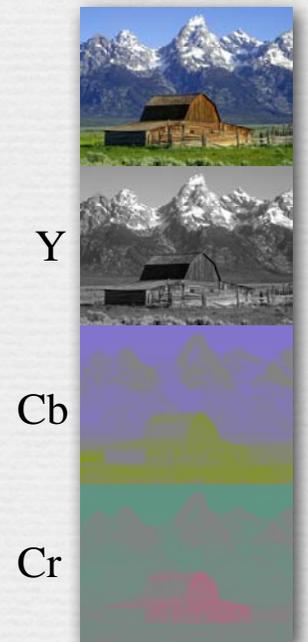
Cr

Apparent spatial sharpness depends mainly on luminance, not chrominance

luminance
channel
blurred

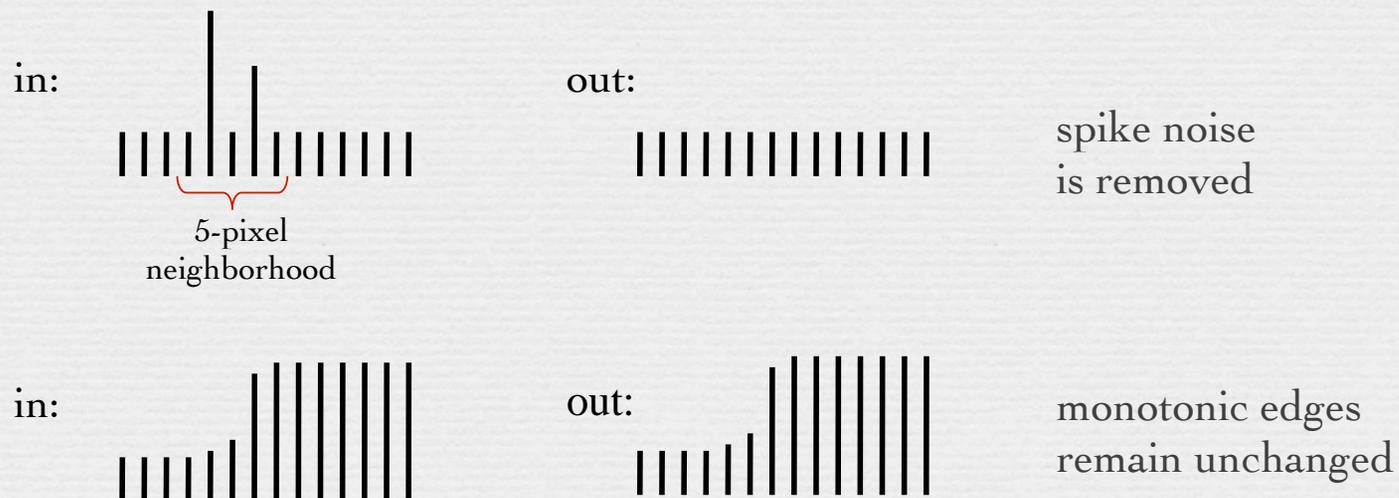


(Wandell)



Common solution: low-pass filter chrominance signal

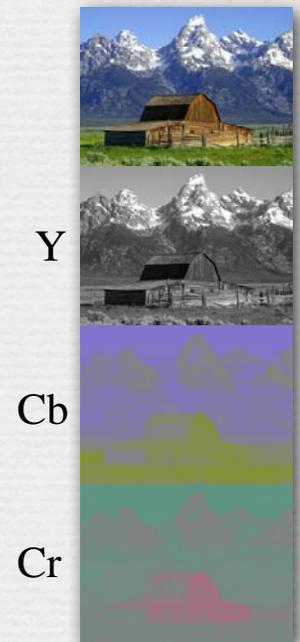
- ◆ color artifacts are places where chrominance changes abruptly but only transiently
- ◆ use a median filter on chrominance to remove outlier transient chrominance changes [Freeman 1988]
 - replace the chrominance of each pixel by the median value in a neighborhood
 - this is a non-linear filter



Common solution: low-pass filter chrominance signal

- ◆ color artifacts are places where chrominance changes abruptly but only transiently
- ◆ use a median filter on chrominance to remove outlier transient chrominance changes [Freeman 1988]
 - replace the chrominance of each pixel by the median value in a neighborhood
 - this is a non-linear filter
- ◆ summary of algorithm
 - 1. apply naive interpolation
 - 2. convert to YCbCr
 - 3. median filter Cr & Cb
 - 4. reconstruct R, G, B from sensor value and filtered Cr & Cb

(wikipedia)



Comparison



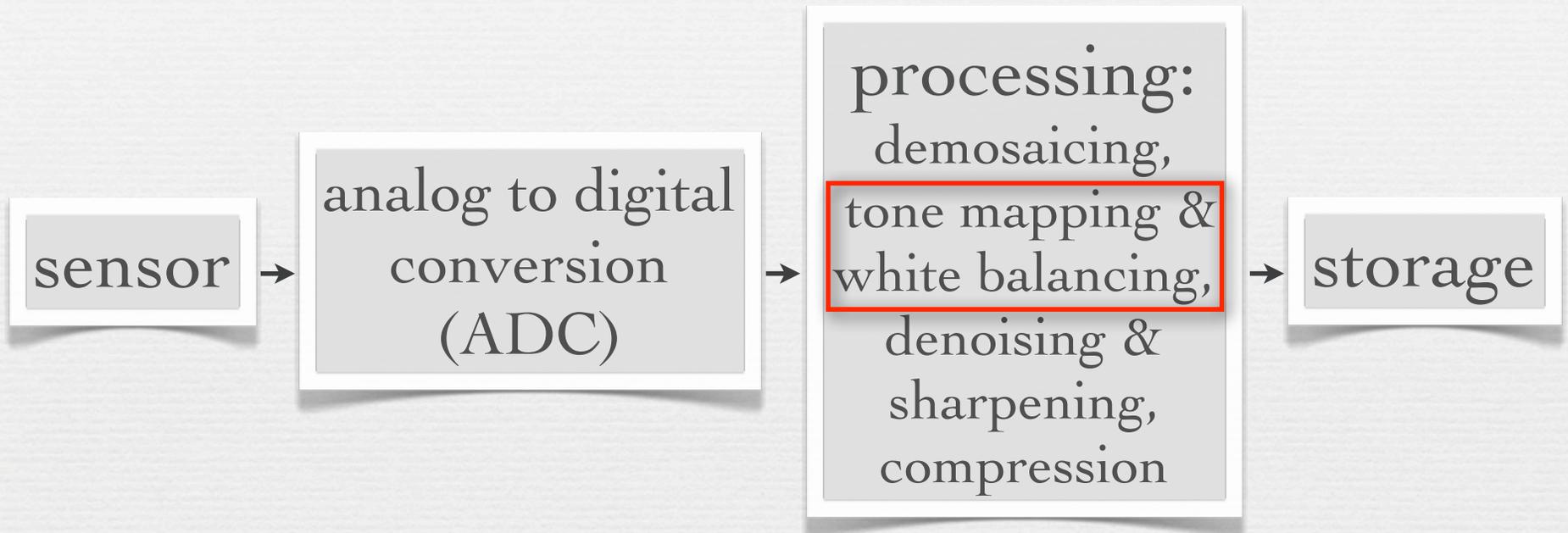
linear interpolation



median-filtered interpolation

- ◆ take-home lesson: $2/3$ of your data is made up!
- ◆ there are better and worse ways to do this

Camera pixel pipeline

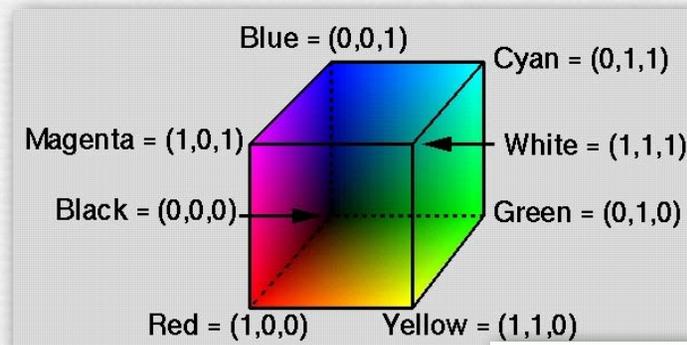


Summary of chromaticity diagrams (1 of 2)

- ◆ choose three primaries R,G,B, pure wavelengths or not
- ◆ adjust R=1,G=1,B=1 to obtain a desired *reference white*
- ◆ this yields an *RGB cube*

(FLASH DEMO)

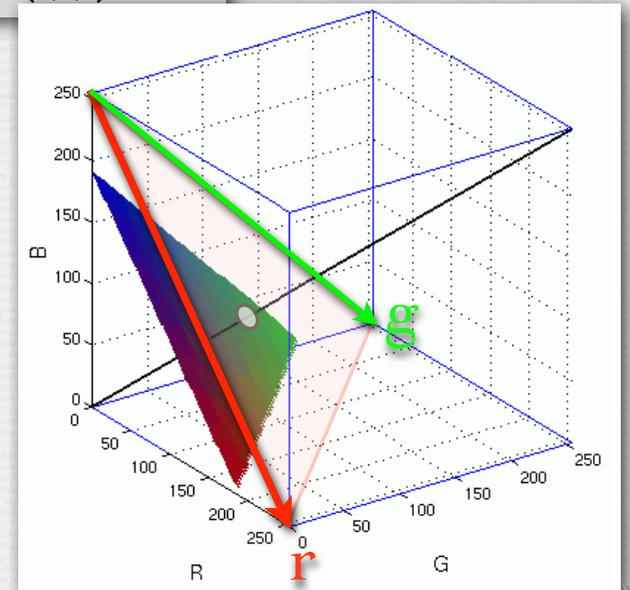
<http://graphics.stanford.edu/courses/cs178/applets/threedgamut.html>



$$r = \frac{R}{R + G + B}$$

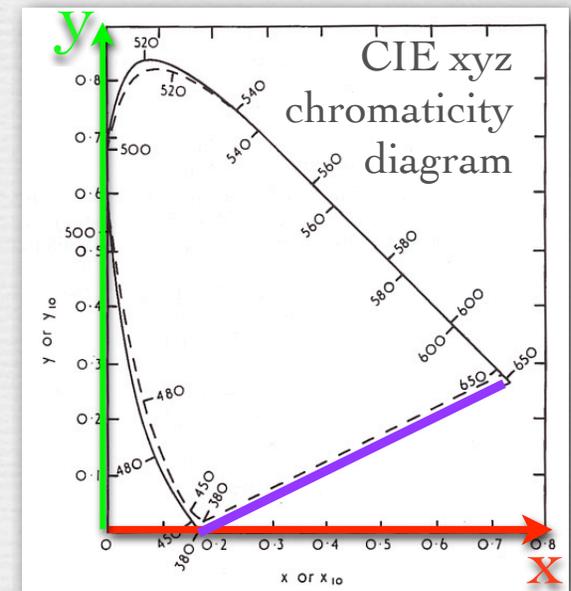
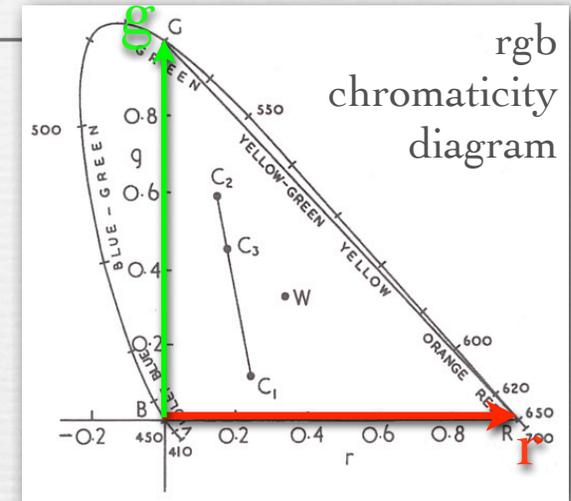
$$g = \frac{G}{R + G + B}$$

- ◆ one may factor the brightness out of any point in the cube by drawing a line to the origin and intersecting this line with the triangle made by corners Red, Green, Blue
- ◆ all points on this triangle, which are addressable by two coordinates, have the same brightness but differing *chromaticity*

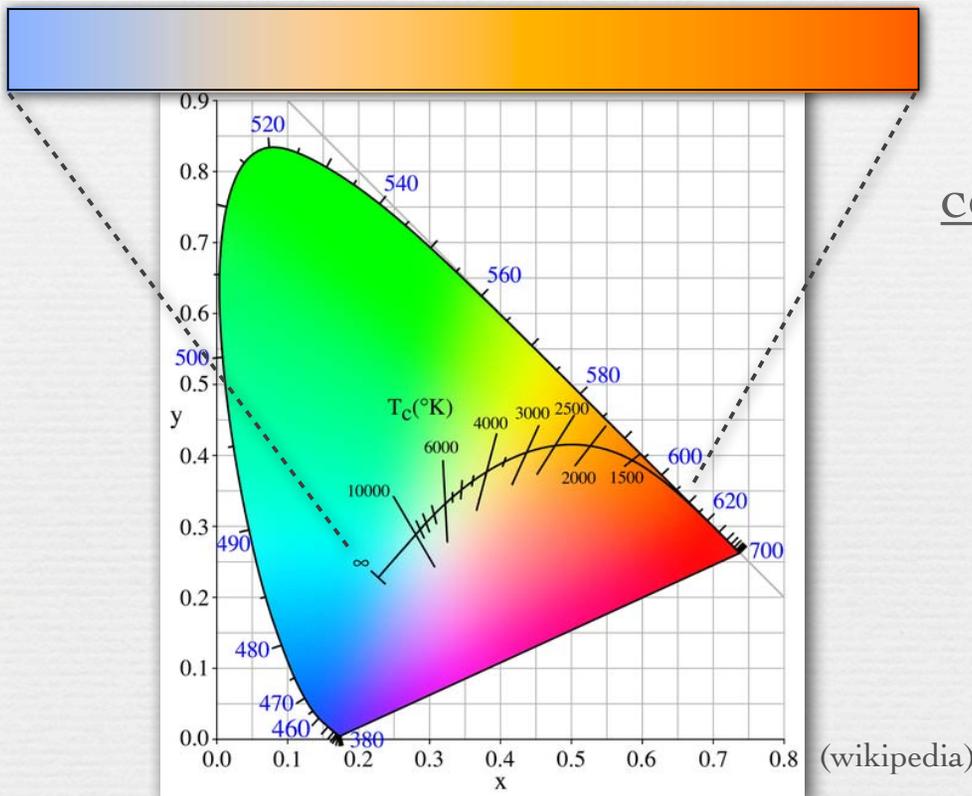


Summary of chromaticity diagrams (2 of 2)

- ◆ this triangle is called the *rgb chromaticity diagram* for the chosen RGB primaries
 - mixtures of colors lie along straight lines
 - neutral (black to white) lies at $(\frac{1}{3}, \frac{1}{3})$
 - $r > 0, g > 0$ does not enclose spectral locus
- ◆ the same construction can be performed using any set of 3 vectors as primaries, even physically impossible ones
- ◆ the CIE has defined a set of primaries XYZ, and the associated *xyz chromaticity diagram*
 - $x > 0, y > 0$ does enclose spectral locus
 - one can connect red and green on the locus with a *line of extra-spectral purples*
 - x, y is a standardized way to denote colors



Application of chromaticity diagrams #1: color temperature and white balancing



correlated color temperatures

3200°K incandescent light

4000°K cool white fluorescent

5000°K equal energy white (D50, E)

6000°K midday sun, photo flash

6500°K overcast, television (D65)

7500°K northern blue sky

- ◆ the apparent colors emitted by a *black-body radiator* heated to different temperatures fall on a curve in the chromaticity diagram
- ◆ for non-blackbody sources, the nearest point on the curve is called the *correlated color temperature*

White balancing in digital photography

- ◆ 1. choose an object in the photograph you think is neutral (somewhere between black and white) in the real world
- ◆ 2. compute scale factors (S_R, S_G, S_B) that map the object's (R, G, B) to neutral $(R=G=B)$, i.e. $S_R = \frac{1}{3} (R+G+B) / R$, etc.
- ◆ 3. apply the same scaling to all pixels in the sensed image
- ◆ the eventual appearance of $R=G=B$, hence of your chosen object, depends on the color space of the camera
 - the color space of most digital cameras is sRGB
 - the reference white for sRGB is D65 (6500°K)
- ◆ thus, white balancing on an sRGB camera forces your chosen object to appear 6500°K (blueish white)
- ◆ if you trust your object to be neutral, this procedure is equivalent to finding the color temperature of the illumination

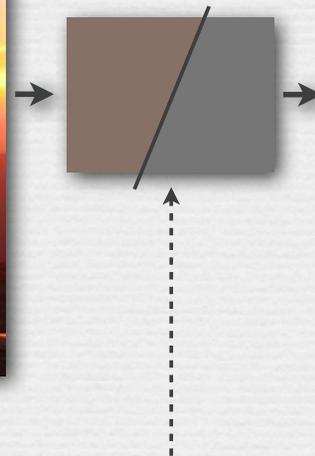
Finding the color temperature of the illumination

◆ Auto White Balance (AWB)

- gray world: assume the average color of a scene is gray, so force the average color to be gray - often inappropriate



(Marc Levoy)

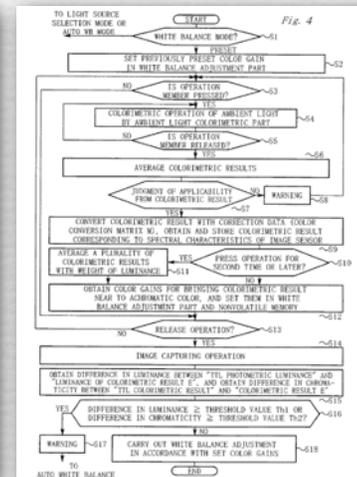
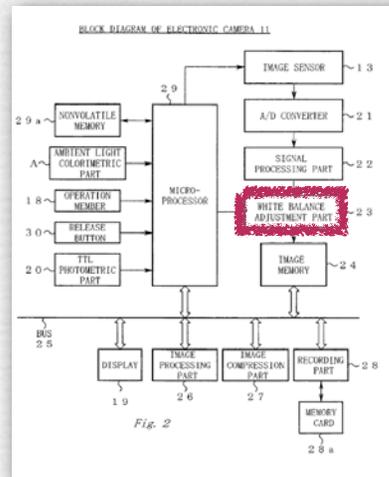


average (R, G, B) = (100%, 81%, 73%) → (100%, 100% 100%)

Finding the color temperature of the illumination

◆ Auto White Balance (AWB)

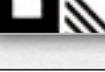
- gray world: assume the average color of a scene is gray, so force the average color to be gray - often inappropriate
- assume the brightest pixel (after demosaicing) is a specular highlight and therefore should be white
 - fails if pixel is saturated
 - fails if object is metallic - gold has gold-colored highlights
- find a neutral-colored object in the scene
 - but how??

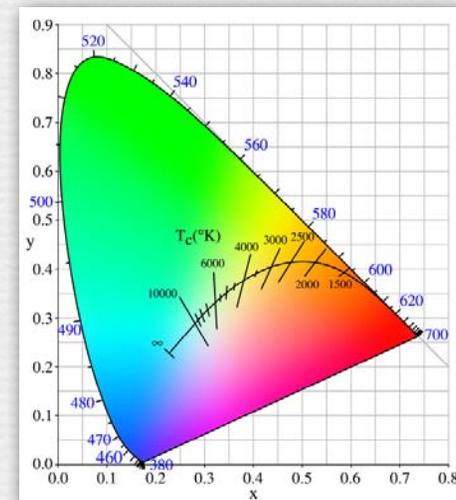


Finding the color temperature of the illumination

- ◆ Auto White Balance (AWB)
- ◆ manually specify the illumination's color temperature
 - each color temperature corresponds to a unique (x,y)
 - for a given camera, one can measure the (R,G,B) values recorded when a neutral object is illuminated by this (x,y)
 - compute scale factors (S_R, S_G, S_B) that map this (R,G,B) to neutral $(R=G=B)$; apply this scaling to all pixels as before



	tungsten: 3,200K
	fluorescent: 4,000K
	daylight: 5,200K
	cloudy or hazy:
	flash: 6,000K
	shaded places: 7,000K



Incorrectly chosen white balance

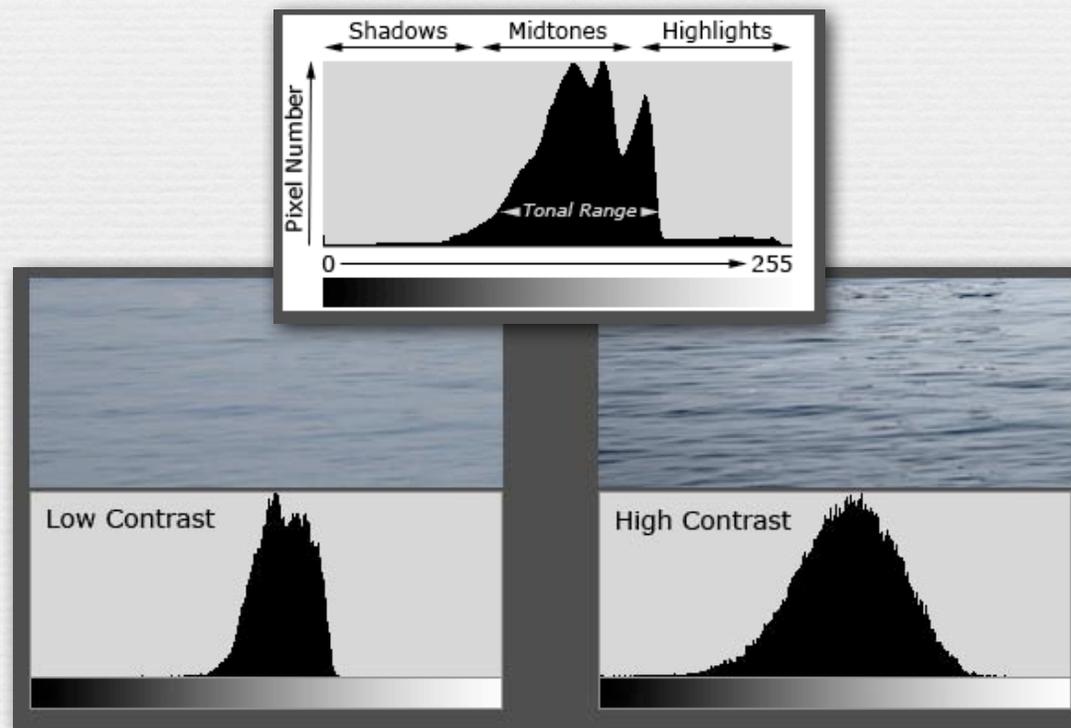


(Eddy Talvala)

- ◆ scene was photographed in sunlight, then re-balanced as if it had been photographed under something warmer, like tungsten
 - re-balancer assumed illumination was very reddish, so it boosted blues
 - same thing would have happened if originally shot with tungsten WB

Contrast correction (a.k.a. tone mapping)

- ◆ manual editing
 - store image in RAW mode, then fiddle with histogram in Photoshop, dcraw, Canon Digital Photo Professional, etc.



Contrast correction (a.k.a. tone mapping)

- ◆ manual editing
 - store image in RAW mode, then fiddle with histogram in Photoshop, dcrw, Canon Digital Photo Professional, etc.
- ◆ gamma transform
 - output = input $^\gamma$ (for $0 \leq I_i \leq 1$)
 - simple but crude



original



$\gamma = 0.5$

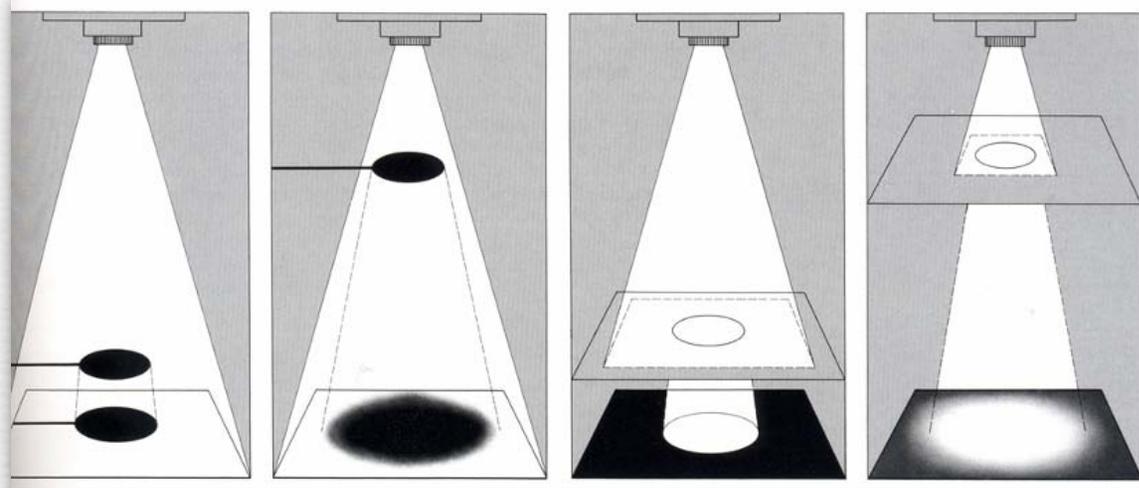


$\gamma = 2.0$

Contrast correction (a.k.a. tone mapping)

- ◆ manual editing
 - store image in RAW mode, then fiddle with histogram in Photoshop, dcrw, Canon Digital Photo Professional, etc.
- ◆ gamma transform
 - output = input ^{γ} (for $0 \leq I_i \leq 1$)
 - simple but crude
- ◆ global versus local transformations

Traditional dodging and burning

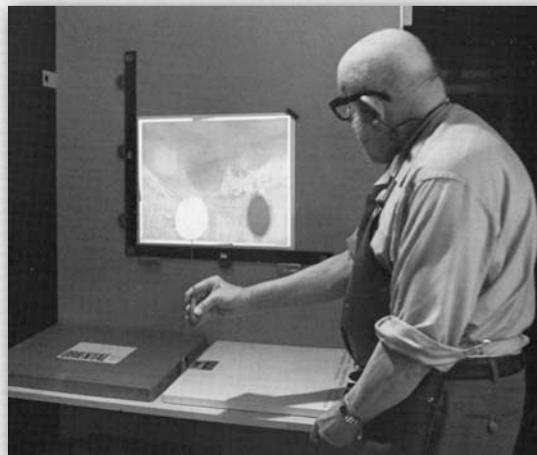


(Rudman)

dodging
(leaves print lighter)

burning
(makes print darker)

Ansel Adams in
his darkroom



(Adams)



straight
print

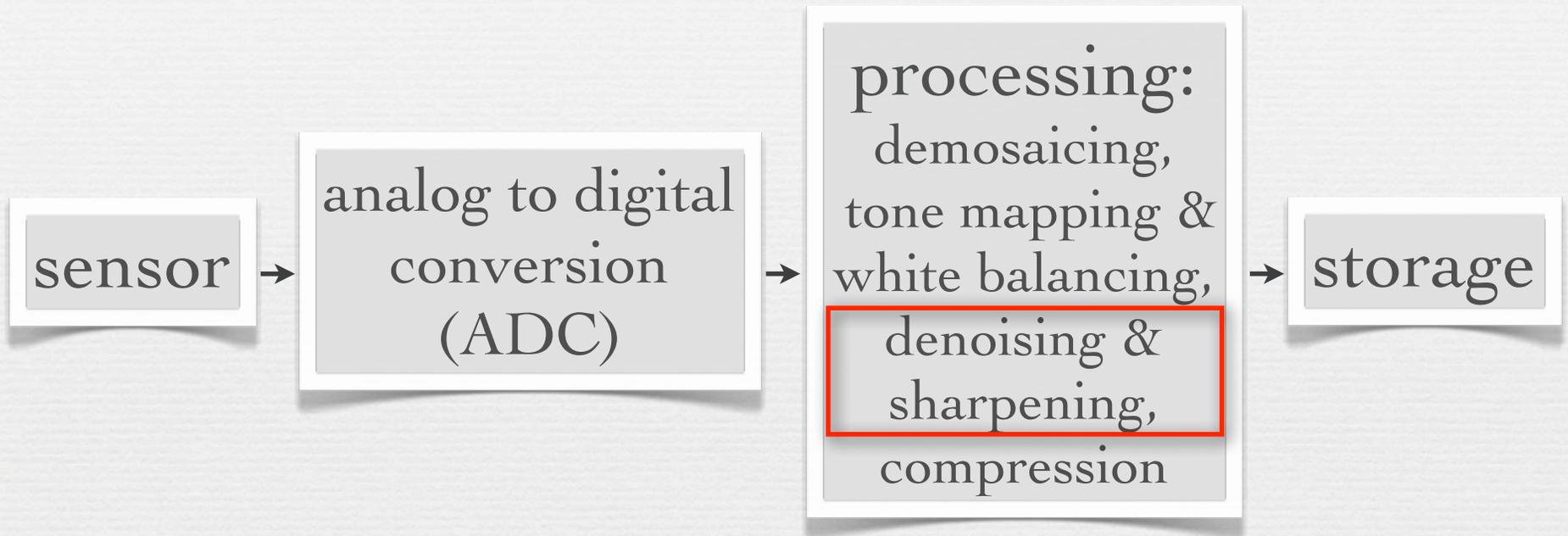
Ansel Adams, Clearing Winter Storm, 1942



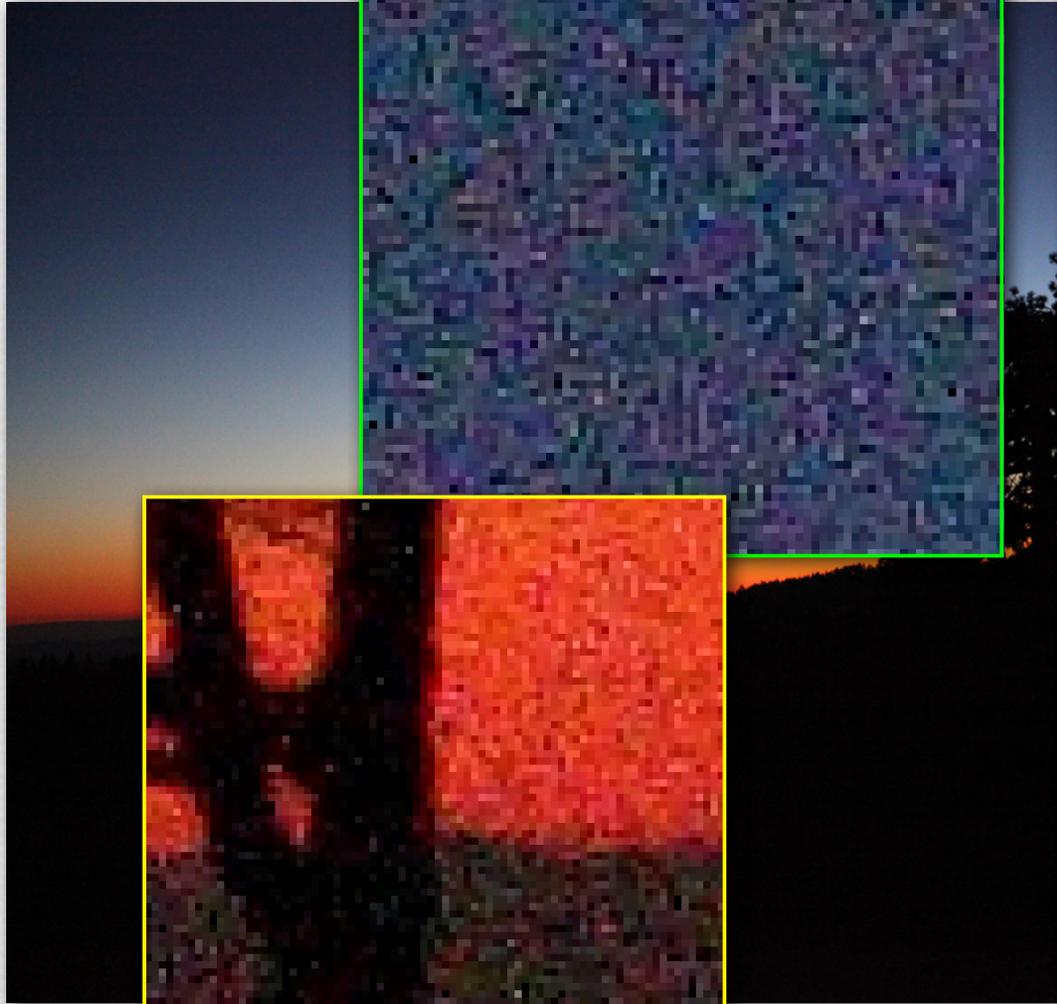
toned
print

Ansel Adams, *Clearing Winter Storm*, 1942

Camera pixel pipeline



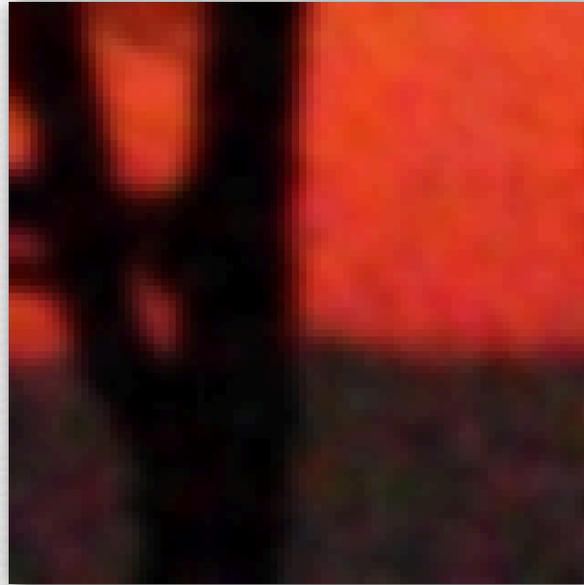
Canon 5D II at dusk



Denoising



RAW (ISO 6400)



Gaussian blur, radius = 1.3

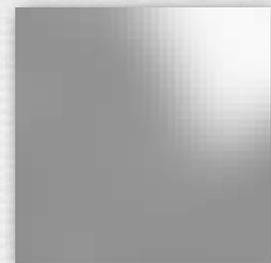
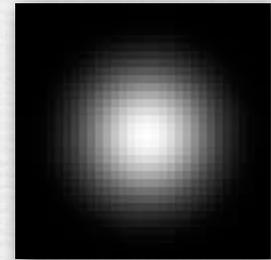
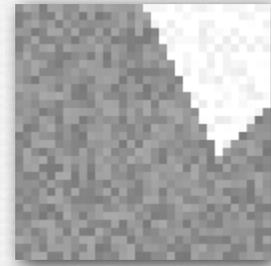


Canon denoising

- ◆ goal is to remove sensor noise
 - blurring works, but also destroys edges
 - I don't know what Canon does, but here's something that works...

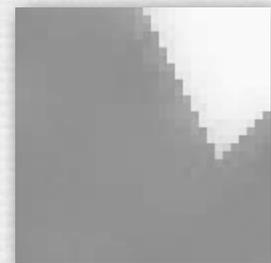
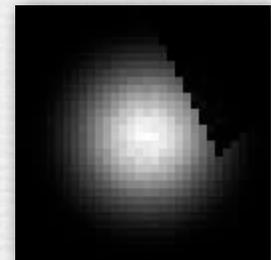
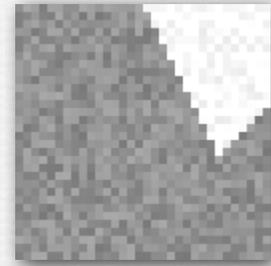
Bilateral filtering [Tomasi ICCV 1998]

- ◆ assume the image is piecewise constant with noise added
- ◆ therefore, nearby pixels are probably a different noisy measurement of the same data
- ◆ blurring doesn't work
- ◆ we should do a weighted blur where the weight is the probability a pixel is from the same piece of the scene



Bilateral filtering

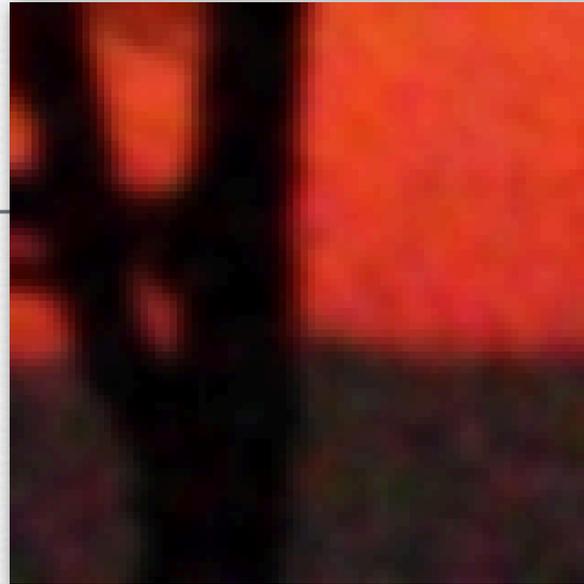
- ◆ if the pixels are similar in intensity, the probability they are from the same piece of the scene is high
- ◆ so perform a convolution where the weight assigned to nearby pixels falls off
 - with increasing (x,y) distance from the pixel being blurred
 - with increasing intensity difference from the pixel being blurred
- ◆ i.e. blur in the *domain* and *range* dimensions!



Denoising



RAW (ISO 6400)

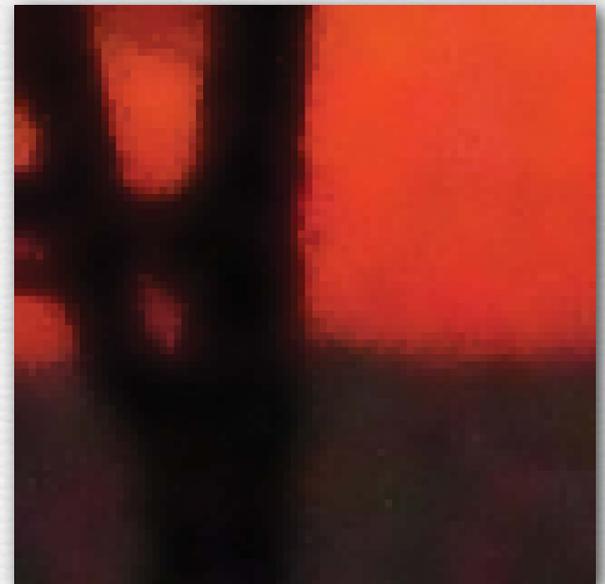


Gaussian blur, radius = 1.3



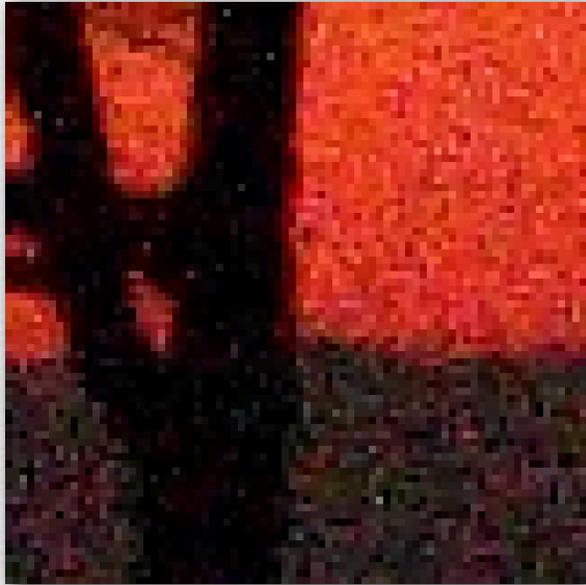
Canon denoising

- ◆ bilateral filtering removes sensor noise without blurring edges
- ◆ can easily be extended to RGB



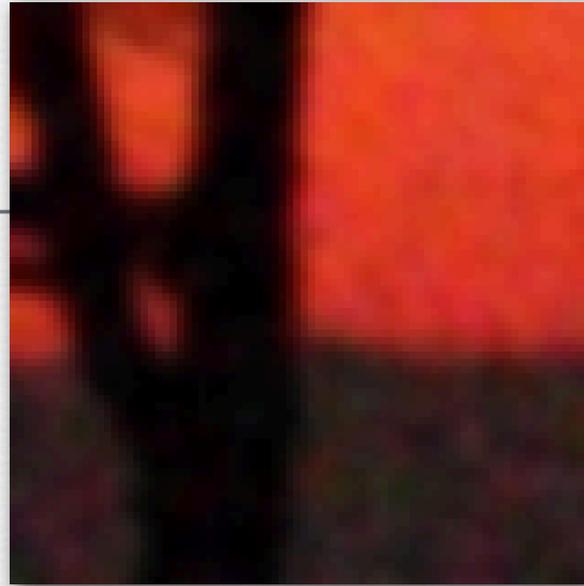
bilateral filtering

Denoising



RAW (ISO 6400)

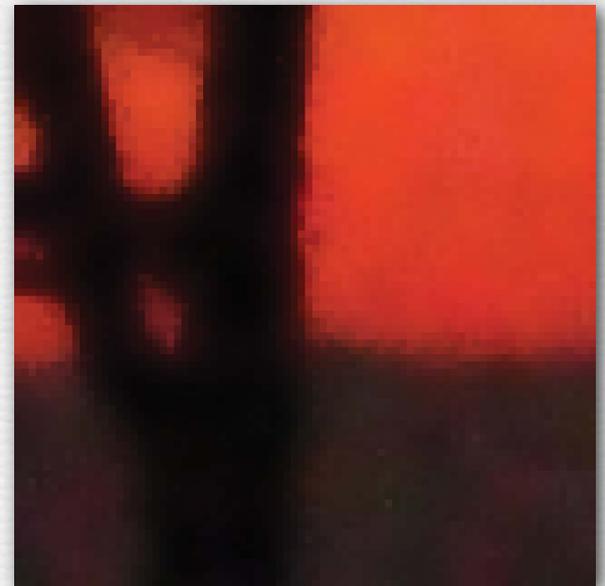
- ◆ can be applied more (or less) strongly to chrominance than luminance
- ◆ can be combined with demosaicing
- ◆ active area of research...



Gaussian blur, radius = 1.3



Canon denoising



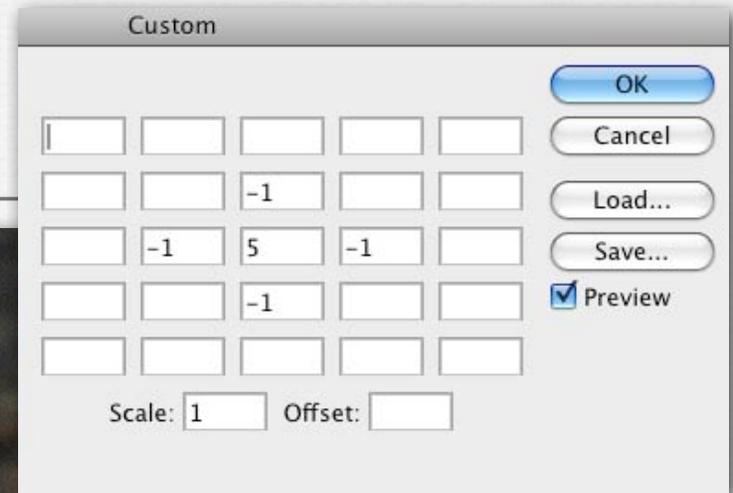
bilateral filtering

Sharpening



original

Sharpening



Filter/Other/Custom
in Photoshop CS4

Sharpening



Custom

<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="button" value="OK"/>
<input type="text"/>	<input type="text"/>	<input type="text" value="-2"/>	<input type="text"/>	<input type="text"/>	<input type="button" value="Cancel"/>
<input type="text"/>	<input type="text" value="-2"/>	<input type="text" value="9"/>	<input type="text" value="-2"/>	<input type="text"/>	<input type="button" value="Load..."/>
<input type="text"/>	<input type="text"/>	<input type="text" value="-2"/>	<input type="text"/>	<input type="text"/>	<input type="button" value="Save..."/>
<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input checked="" type="checkbox"/> Preview

Scale: Offset:

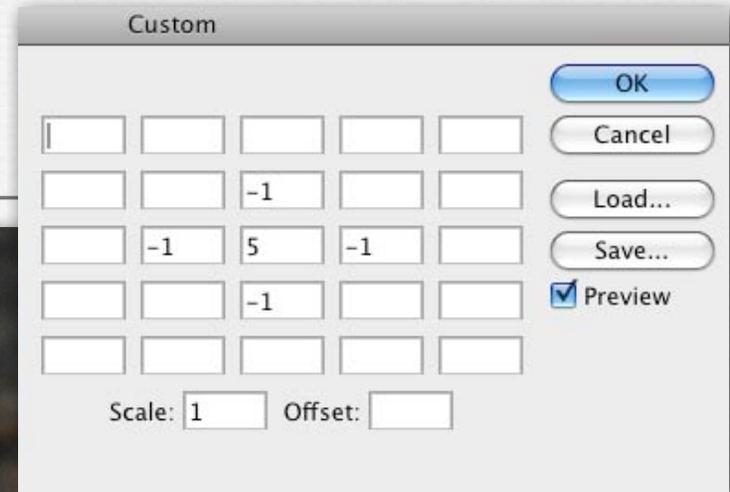
Filter/Other/Custom
in Photoshop CS4

Sharpening



original

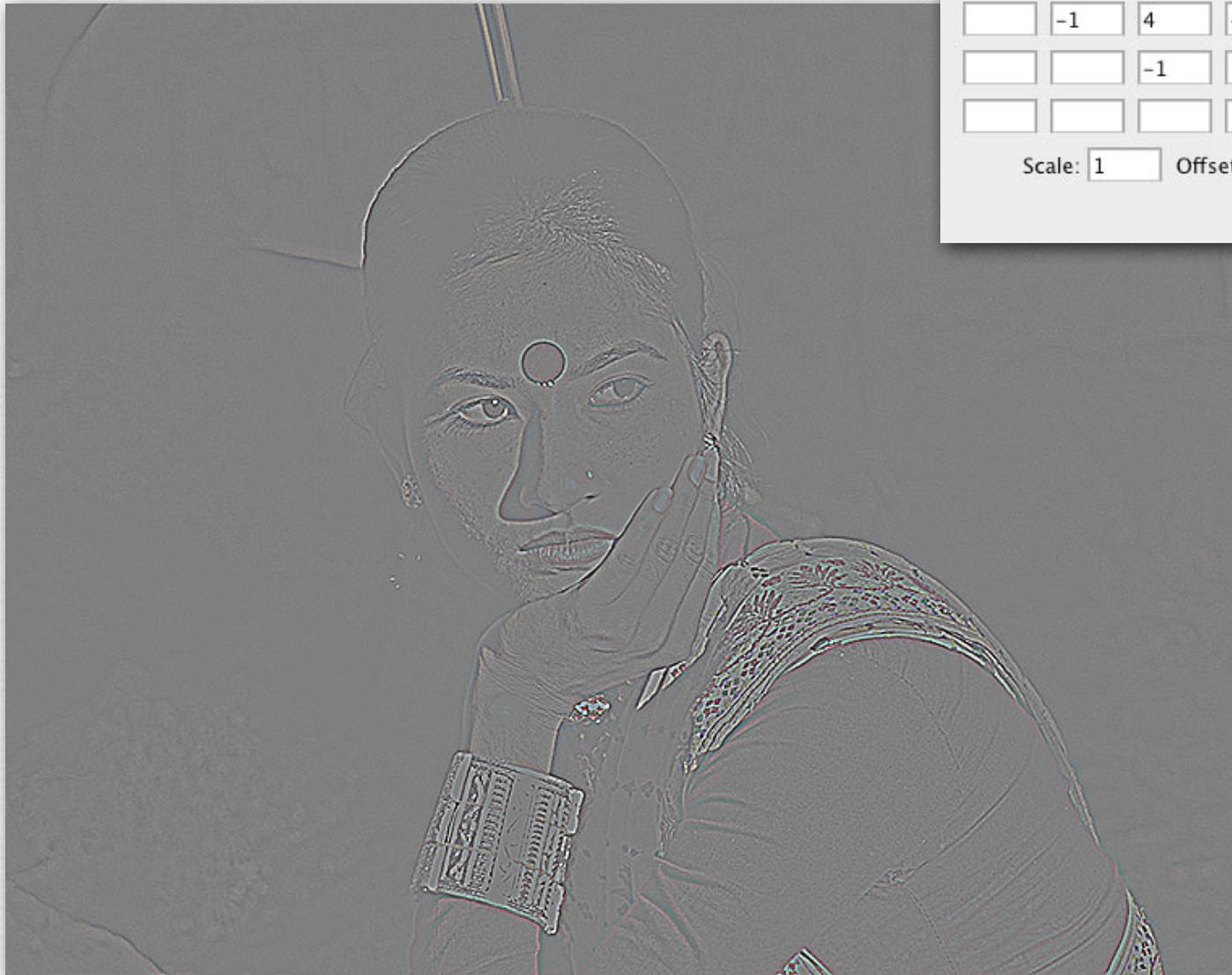
Sharpening



1st layer is original,
2nd layer is sharpened,
blend w. 30% opacity

(Marc Levoy)
© 2010 Marc Levoy

Sharpening



Custom

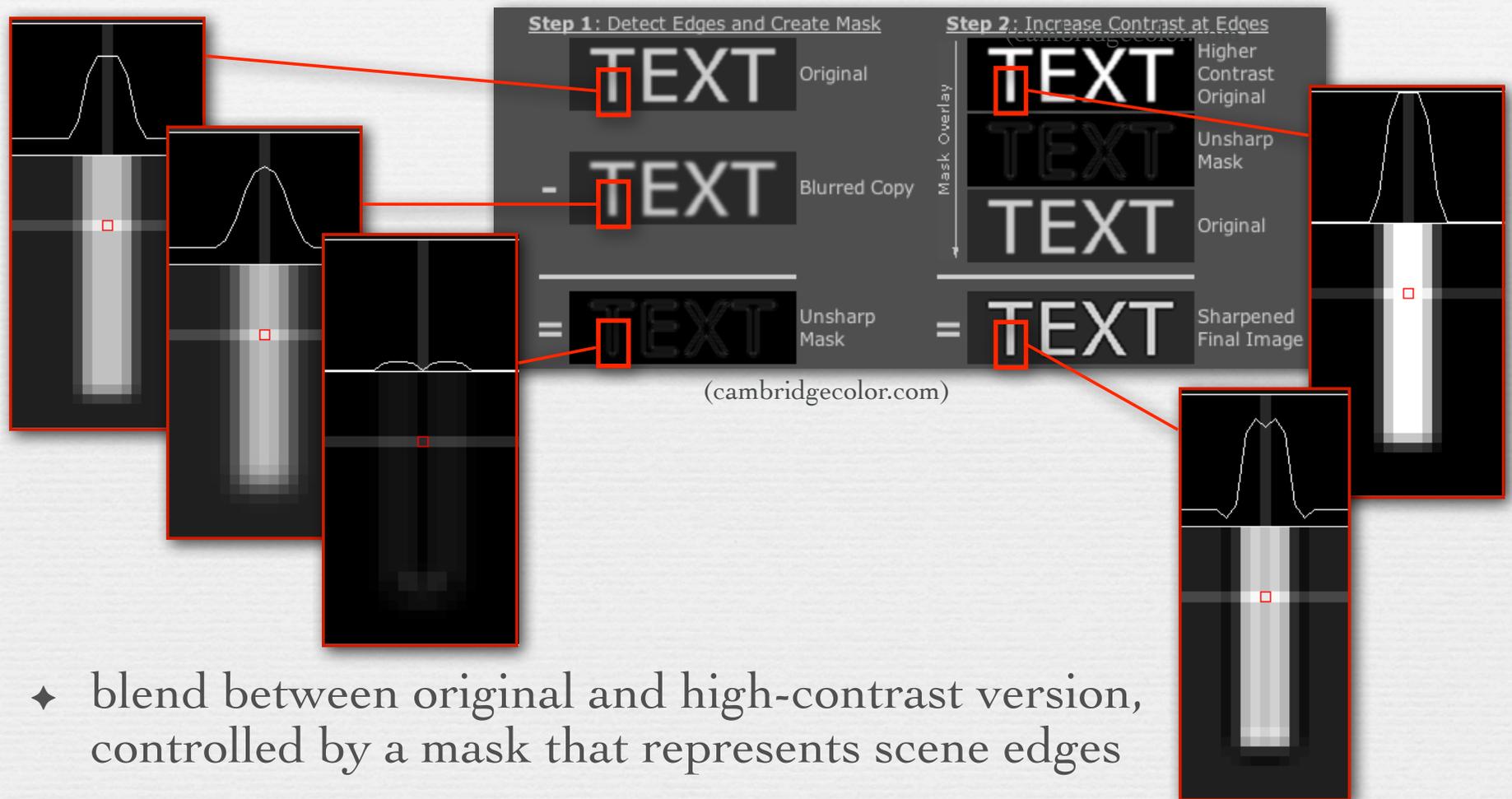
		-1		
	-1	4	-1	
		-1		

Scale: 1 Offset: 128

OK
Cancel
Load...
Save...
 Preview

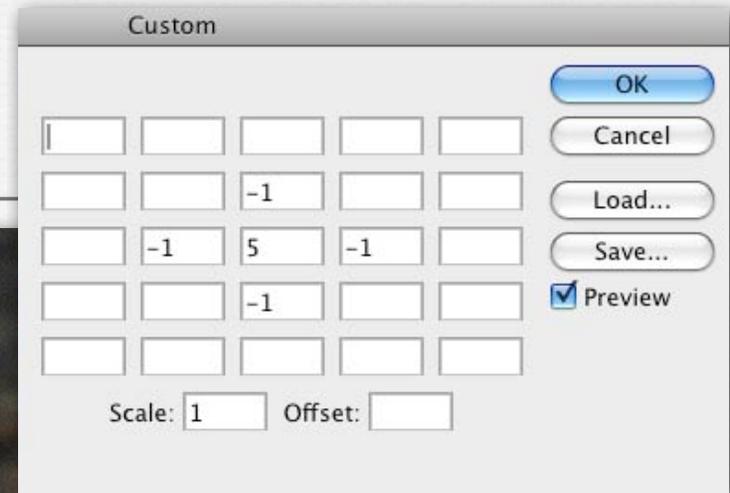
Filter/Other/Custom
in Photoshop CS4

Unsharp masking



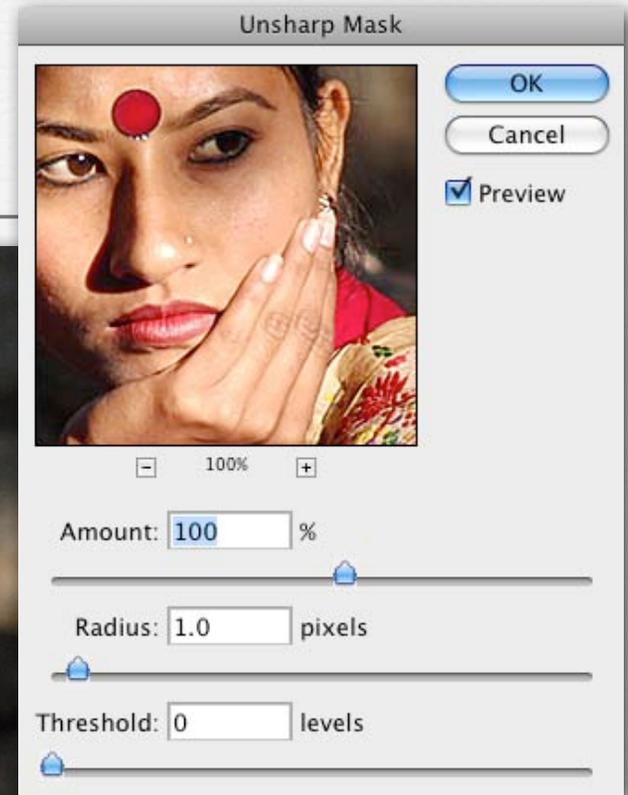
- ◆ blend between original and high-contrast version, controlled by a mask that represents scene edges
- ◆ dropping (thresholding) the darkest mask pixels avoids sharpening noise, and makes the filter non-linear

Sharpening



Filter/Other/Custom
in Photoshop CS4

Sharpening



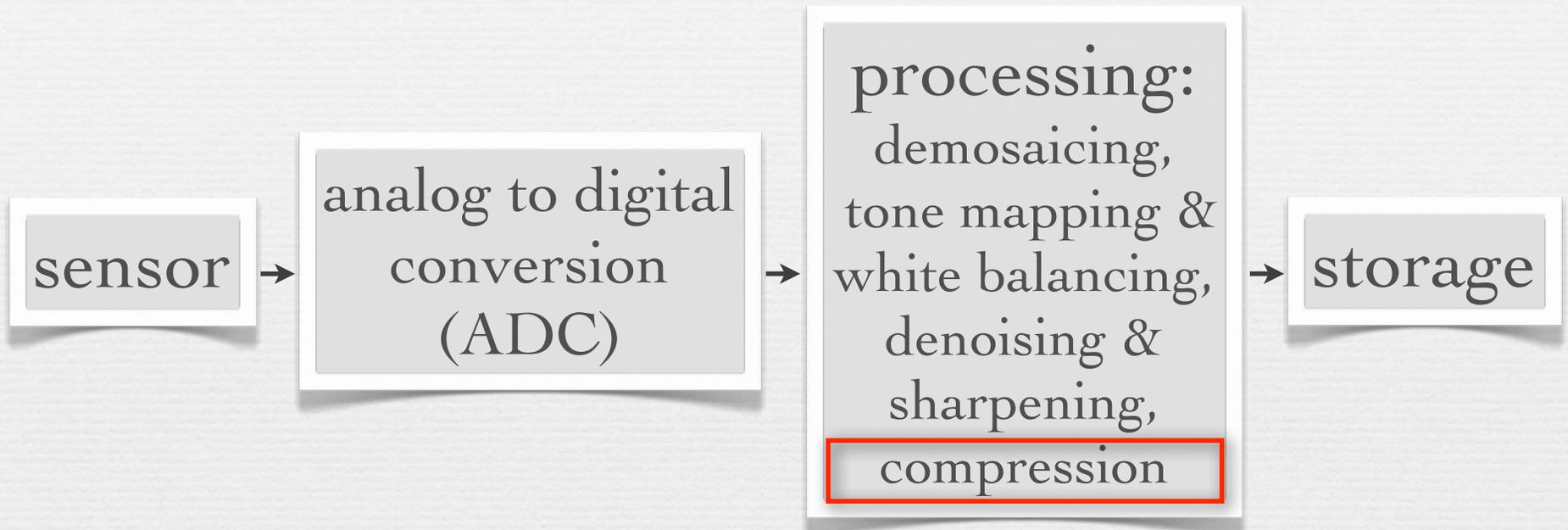
Filter/Sharpen/
Unsharp Mask in CS4

Sharpening



original

Camera pixel pipeline



JPEG files

- ◆ Joint Photographic Experts Group
 - organized 1986, standard adopted 1994
- ◆ defines how an image is to be compressed into a stream of bytes (codec) and the file format for storing that stream
 - file format is JFIF, but people use .JPG or .JPEG extensions
- ◆ good for compressing images of natural scenes;
not so good for compressing drawings or graphics
- ◆ lossy, so loses quality each time you open → edit → save
 - especially if you crop or shift pixels (hence block boundaries)
 - for lossless compression, use PNG or TIFF

EXIF data

- ◆ Exchangeable Image File Format
 - created by Japan Electronic Industries Development Assoc.
- ◆ used by nearly every digital camera manufactured today
 - actually a file format
 - JPEG or TIFF file + metadata about the camera and shot
 - .JPG or .JPEG extension is used

EXIF data

File/File Info in
Photoshop CS4

(Marc Levoy)



shot with Canon 5D Mark II

Color Space: sRGB

male-pine-cones.JPG

Description IPTC Camera Data Video Data

Camera Data 1

Make: Canon
Model: Canon EOS 5D Mark II
Date Time: 2/1/2009 - 3:24 PM
Shutter Speed: 1/250 sec
Exposure Program: Normal program
F-Stop: f/5.6
Aperture Value: f/5.6
Max Aperture Value:
ISO Speed Ratings: 200
Focal Length: 105 mm
Lens:
Flash: Did not fire
No strobe return detection (0)
Compulsory flash suppression (2)
Flash function present
No red-eye reduction
Metering Mode: Pattern

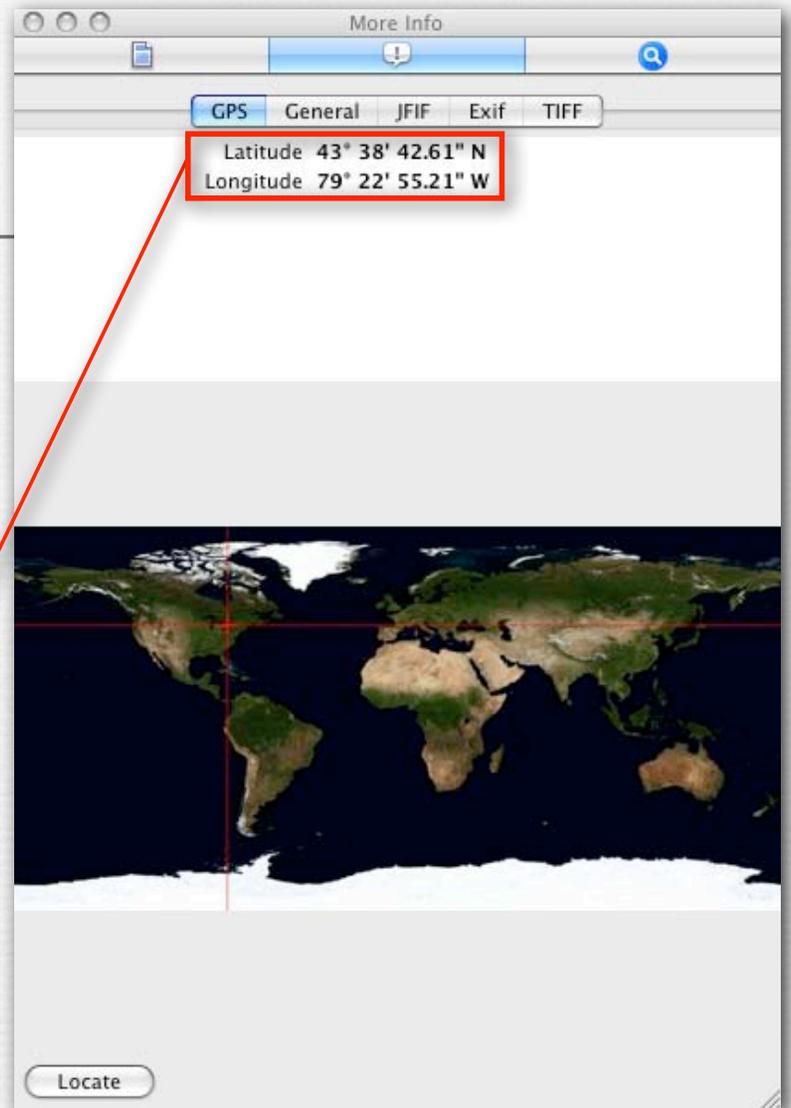
Camera Data 2

Pixel Dimension X: 5616 Y: 3744
Orientation: Normal
Resolution X: 72 Y: 72
Resolution Unit: Inch
Compressed Bits per Pixel:
Color Space: sRGB
Light Source:
File Source:

Powered By **xmp™** Import... Cancel OK

EXIF data

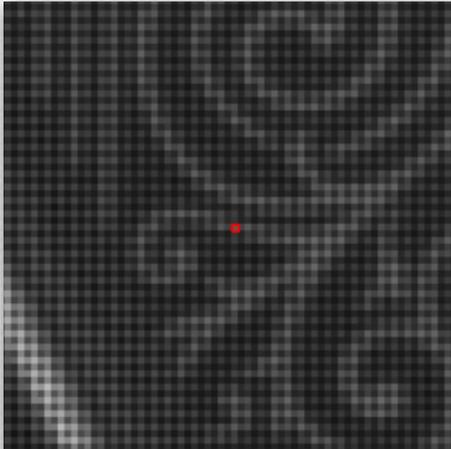
Mac
Preview



shot with iPhone 3G

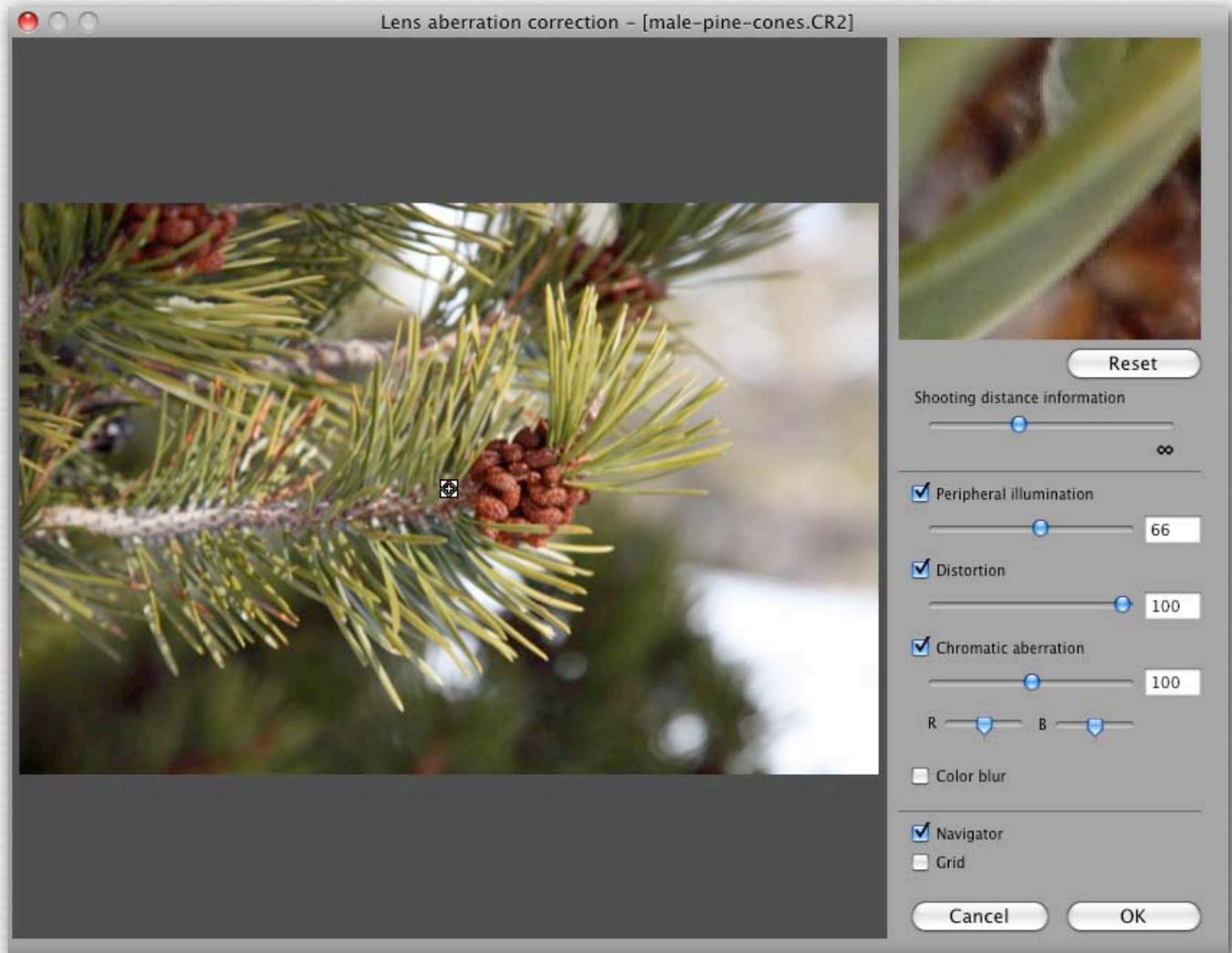
Latitude 43° 38' 42.61" N
Longitude 79° 22' 55.21" W

RAW files

- ◆ minimally processed images, not even demosaiced
 - ◆ uncompressed or losslessly compressed
 - ◆ includes metadata, possibly encrypted
 - ◆ file format varies by manufacturer
 - ◆ example extensions: .CR2, .NEF, .RW2
- 
- ◆ processed and converted to a JPEG file using
 - proprietary software (e.g. Canon Digital Photo Professional)
 - Photoshop or Lightroom (if you're lucky)
 - freeware programs like dcrw
 - but their processing algorithms are all different!

RAW file processor

Lens aberration correction panel in Canon Digital Photo Professional



Slide credits

◆ Fredo Durand

- ◆ Stone, M., *A Field Guide to Digital Color*, A.K. Peters, 2003.
- ◆ Wandell, B., *Foundations of Vision*, Sinauer, 1995.
- ◆ Rudman, T., *Photographer's Master Printing Course*, Focal Press, 1998.
- ◆ Adams, A., *The Print*, Little, Brown and Co., 1980.